

Control Module (4ch)

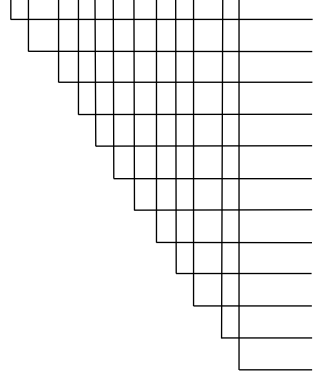
Model: **QTC1-4**

(Except Power / CUnet comm. function,
Connector type & Relay output)



■ Model

(e.g.) QTC1 - 4 P T - R S A V M M A V - 2 2



Power supply / communication option: Power supply / host communication function
 Wiring method: Terminal block type
 CH1 control output: Relay contact
 CH2 control output: Non-contact voltage (for driving SSR)
 CH3 control output: Direct current output, 4 to 20 mA DC
 CH4 control output: DC voltage output, 0 to 1 V DC
 CH1 input: Multi-range
 CH2 input: Multi-range
 CH3 input: Direct current input
 CH4 input: DC voltage input
 Heater burnout alarm option: 4-point CT, 20 A
 Event input/output option: Event output (4 points)

QTC1 - 4		☐	☐	- ☐	☐	☐	☐	☐	☐	☐	- ☐	☐
Power supply / communication options	0											No options
	P											Power supply / host communication function
	C											Power supply / CUnet communication function
Wiring method	T											Terminal block type
	C											Connector type
CH1 control output		- ☐										See output code table
CH2 control output			☐									
CH3 control output				☐								
CH4 control output					☐							
CH1 input						☐						See input code table
CH2 input							☐					
CH3 input								☐				
CH4 input									☐			
Heater burnout alarm options (*1)											-0	No options
											-2	4-point CT, 20 A (*2)
											-A	4-point CT, 100 A (*2)
Event input/output options											0	No options
											1	Event input (4 points) (*3)
											2	Event output (4 points) (*3)

(*1) Cannot be added to Direct current output type, DC voltage output type.

(*2) CT and connector harness are sold separately.

(*3) Connector harness is sold separately.

Output Codes

Code	Output Type
R	Relay contact output
S	Non-contact voltage output (for driving SSR)
A	Direct current output, 4 to 20 mA DC
0	Direct current output, 0 to 20 mA DC
V	DC voltage output, 0 to 1 V DC
1	DC voltage output, 0 to 5 V DC
2	DC voltage output, 1 to 5 V DC
3	DC voltage output, 0 to 10 V DC
C	Open collector output

Input Codes

Code	Input Type	Range
M	Thermocouple	K
		K
		J
		R
		S
		B
		E
		T
		N
		PL- II
		C
		K
		K
		J
		R
		S
		B
		E
		T
		N
		PL- II
		C
	RTD	Pt100
		Pt100
	DC voltage	0 to 1 V DC
	Direct current	4 to 20 mA DC (Externally mounted shunt resistor)
		0 to 20 mA DC (Externally mounted shunt resistor)
A	Direct current	4 to 20 mA DC (Built-in shunt resistor)
		0 to 20 mA DC (Built-in shunt resistor)
V	DC voltage	0 to 5 V DC
		1 to 5 V DC
		0 to 10 V DC

■ Accessories Sold Separately

Product Name	Model
50 Ω shunt resistor	RES-S01-050
100 Ω terminator	RES-S07-100
Front terminal cover	TC-QTC
CT for 20 A	CTL-6-S-H (*1)
CT for 100 A	CTL-12-S36-10L1U (*1)
Heater burnout alarm connector harness	WQ (*1)
Event input/output connector harness	EVQ (*2)

(*1) For heater burnout alarm (heater burnout alarm option symbols: -2, -A)

(*2) For event input or event output (event input/output option symbols: 1, 2)

Rating

Rated Scale

Selected Scale							
Input (TC)	Scale Range		Resolution	Input (RTD)	Scale Range		Resolution
K	-200 to 1370°C	-328 to 2498°F	1°C (°F)	Pt100	-200.0 to 850.0°C	-328.0 to 1562.0°F	0.1°C (°F)
	-200.0 to 400.0°C	-328.0 to 752.0°F	0.1°C (°F)				
J	-200 to 1000°C	-328 to 1832°F	1°C (°F)				
R	0 to 1760°C	32 to 3200°F	1°C (°F)				
S	0 to 1760°C	32 to 3200°F	1°C (°F)	Input (DC)	Scale Range		Resolution
B	0 to 1820°C	32 to 3308°F	1°C (°F)	4 to 20 mA	-32768 to 32767 (*)		1
E	-200 to 800°C	-328 to 1472°F	1°C (°F)	0 to 20 mA			
T	-200.0 to 400.0°C	-328.0 to 752.0°F	0.1°C (°F)	0 to 1 V			
N	-200 to 1300°C	-328 to 2372°F	1°C (°F)	0 to 5 V			
PL-Ⅱ	0 to 1390°C	32 to 2534°F	1°C (°F)	1 to 5 V			
C	0 to 2315°C	32 to 4199°F	1°C (°F)	0 to 10 V			

(*) Scalable

Input

Thermocouple (TC)	K, J, R, S, B, E, T, N, C (JIS C1602-2015), PL-Ⅱ (ASTM E1751M-15) External resistance: 100 Ω or less (However, B input: 40 Ω or less)
RTD	Pt100, 3-wire type (JIS C1604-2013) Allowable input lead wire resistance: 10 Ω or less per wire
Direct current (mA DC)	0 to 20 mA DC, 4 to 20 mA DC Input impedance: 50 Ω (Shunt resistance) Allowable input current: 50 mA or less
DC voltage (V DC)	0 to 1 V DC Input impedance: 1 MΩ or more Allowable input voltage: 5 V DC or less Allowable signal source resistance: 2 kΩ or less 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC Input impedance: 100 kΩ or more Allowable input voltage: 15 V DC or less Allowable signal source resistance: 100 Ω or less

Performance

Basic accuracy	At ambient temperature of 23°C and mounting angle of ±5 degrees	
	Thermocouple	Within ±0.2% of each input span However, below 0°C (32°F): Within ±0.4% of each input span R, S inputs, 0 to 200°C (32 to 392°F): Within ±6°C (12°F) B input, 0 to 300°C (32 to 572°F): Accuracy is not guaranteed.
	RTD	Within ±0.1% of each input span
	Direct current	Within ±0.2% of each input span
	DC voltage	Within ±0.2% of each input span
Cold junction temperature compensation accuracy		Within ±1°C at -10 to 50°C
Effect of ambient temperature		Thermocouple input (no decimal point): Within ±100 ppm/°C of each input span Below 0°C (32°F): Within ±200 ppm/°C of each input span
		Thermocouple input (decimal point): Within ±200 ppm/°C of each input span Below 0°C (32°F): Within ±400 ppm/°C of each input span
Other:		Within ±100 ppm/°C of each input span
Effects of electromagnetic interference		Within ±1% of each input span
Input sampling period		20 ms (with only DC voltage input and direct current input enabled)
		50 ms (with only DC voltage input and direct current input enabled)
		125 ms
		Note: Fixed to 125 ms regardless of settings for thermocouple input and RTD input

■ Control Performance

Control action	Control method selectable from 2DOF PID control, Fast-PID control, Slow-PID control, ON-OFF control, or Gap-PID control. For optimal control, select the best control method according to the intended use and process. (Factory default: 2DOF PID control)																						
2DOF PID control Fast-PID control Slow-PID control Gap-PID control	2DOF PID control A control method that offers both tracking characteristics with SV changes, and disturbance suppression. This method offers the same disturbance responsiveness as Fast-PID control as well as control actions with reduced overshooting. Fast-PID control This general PID control method is used for constant value control (SV control at a single value). • P control: When integral time and derivative time are set to 0. • PI control: When derivative time is set to 0. • PD control: When integral time is set to 0. • Deviation PID control: When the proportional gain 2DOF coefficient (α) is set to 1.00 and the derivative 2DOF coefficient (γ, Cd) is set to 1.00. Slow-PID control This control method is effective for processes where generating overshoot is not desired, and processes where the PV does not easily decrease after having exceeded the SV. Gap-PID control If the PV is noisy or if there is hysteresis in the operation unit, a slight fluctuation may be maintained near the deviation of 0. In such cases, a dead band is usually used, but since control is not performed within dead bands, the PV changes in the event of a disturbance. In this way, this control method ensures deviation characteristics in dead bands and allows for disturbance responses. <table border="1"> <thead> <tr> <th>Item</th><th>Setting Range</th></tr> </thead> <tbody> <tr> <td>Proportional band (P)</td><td>1 to Input span °C (°F) or 0.1 to Input span °C (°F) Direct current input, DC voltage input: 0.10 to 100.00% or 0.1 to 1000.00 %</td></tr> <tr> <td>Integral time (I)</td><td>0 to 3600 sec or 0.0 to 2000.0 sec 1 to 3600 sec or 0.1 to 2000.0 sec (When Slow-PID control is selected) The setting range varies depending on the selected integral/derivative decimal point position.</td></tr> <tr> <td>Derivative time (D)</td><td>0 to 3600 sec or 0.0 to 2000.0 sec The setting range varies depending on the selected integral/derivative decimal point position.</td></tr> <tr> <td>Proportional gain 2DOF coefficient (α)</td><td>0.00 to 1.00</td></tr> <tr> <td>Integral 2DOF coefficient (β)</td><td>0.00 to 10.00</td></tr> <tr> <td>Derivative 2DOF coefficient (γ, Cd)</td><td>0.00 to 1.00</td></tr> <tr> <td>Proportional cycle</td><td>0.1 to 100.0 sec</td></tr> <tr> <td>Output high limit, output low limit</td><td>0.0 to 100.0% Direct current output, DC voltage input: -5.0 to 105.0%</td></tr> <tr> <td>Gap width (*)</td><td>0.0 to 10.0% Proportional band × Gap width</td></tr> <tr> <td>Gap coefficient (*)</td><td>0.0 to 1.0</td></tr> </tbody> </table> (*) With Gap-PID control only	Item	Setting Range	Proportional band (P)	1 to Input span °C (°F) or 0.1 to Input span °C (°F) Direct current input, DC voltage input: 0.10 to 100.00% or 0.1 to 1000.00 %	Integral time (I)	0 to 3600 sec or 0.0 to 2000.0 sec 1 to 3600 sec or 0.1 to 2000.0 sec (When Slow-PID control is selected) The setting range varies depending on the selected integral/derivative decimal point position.	Derivative time (D)	0 to 3600 sec or 0.0 to 2000.0 sec The setting range varies depending on the selected integral/derivative decimal point position.	Proportional gain 2DOF coefficient (α)	0.00 to 1.00	Integral 2DOF coefficient (β)	0.00 to 10.00	Derivative 2DOF coefficient (γ , Cd)	0.00 to 1.00	Proportional cycle	0.1 to 100.0 sec	Output high limit, output low limit	0.0 to 100.0% Direct current output, DC voltage input: -5.0 to 105.0%	Gap width (*)	0.0 to 10.0% Proportional band × Gap width	Gap coefficient (*)	0.0 to 1.0
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ON-OFF control	Control method that operates with only two values: ON and OFF <table border="1"> <thead> <tr> <th>Item</th><th>Setting Range</th></tr> </thead> <tbody> <tr> <td>ON/OFF hysteresis</td><td>0.1 to 1000.0°C (0.1 to 1800.0°F) Direct current input, DC voltage input: 1 to 10000</td></tr> </tbody> </table>	Item	Setting Range	ON/OFF hysteresis	0.1 to 1000.0°C (0.1 to 1800.0°F) Direct current input, DC voltage input: 1 to 10000																		
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Control range	Control output is turned OFF when the following control ranges are exceeded. Thermocouple input (no decimal point) Input range low limit value -50°C (90°F) to Input range high limit +50°C (90°F) Thermocouple input (decimal point), RTD input Input range low limit value - (Input span × 1%) °C (°F) to Input range high limit + 50.0°C (90.0°F) Direct current input, DC voltage input Scaling low limit value - Scaling width × 10% to Scaling high limit value + Scaling width × 10%																						

Control output	Relay contact output:	1a Control capacity: 3 A 250 V AC (resistive load) 1 A 250 V AC (inductive load $\cos\phi = 0.4$) Electrical life: 100,000 cycles Minimum applicable load: 10 mA 5 V DC
	Non-contact voltage output (for driving SSR)	12 V DC $\pm 15\%$ Max. 40 mA (short circuit protected) * The power supply is not electrically insulated from the output.
	Direct current output	4 to 20 mA DC, 0 to 20 mA DC (Resolution: 12000) Load resistance: Maximum 550 Ω * The power supply is not electrically insulated from the output.
	DC voltage output:	0 to 1 V DC, 0 to 5 V DC, 1 to 5 V DC, 1 to 10 V DC (Resolution: 12000) Allowable load resistance: 1 k Ω or more * The power supply is not electrically insulated from the output.
	Open collector output (NPN):	Allowable load current: 100 mA or less Load voltage: 30 V DC or less

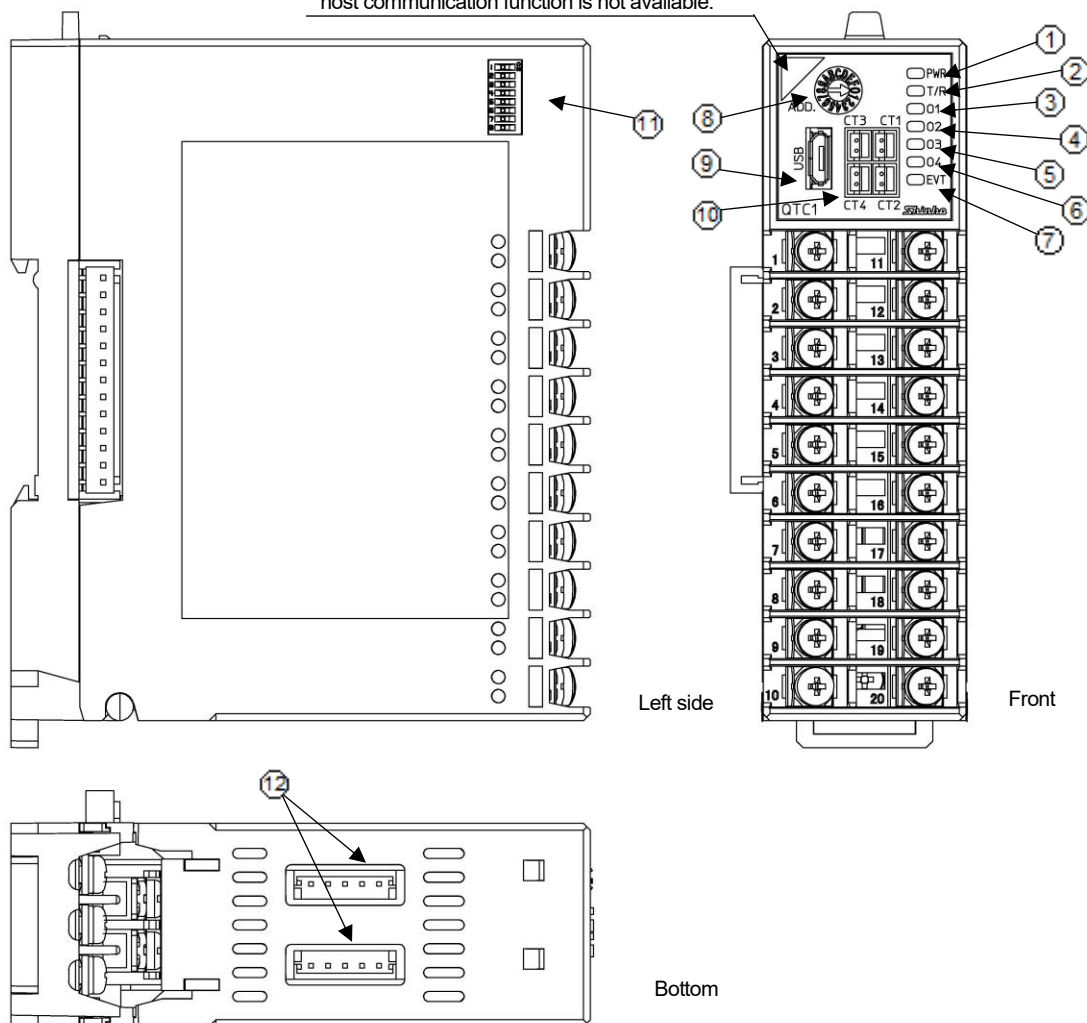
■ General Structure

Weight		Approx. 170 g
Dimensions		30 × 100 × 85 mm (W × H × D) (excl. protrusions) Depth with terminal cover attached: 95 mm
Mounting method		DIN rail mounting
Case		Flame-resistant resin, Color: Black
Panel		Polycarbonate sheet
Standards	EN	EN61010-1 (Pollution degree 2)
	EC (EMC directive)	EMI: EN61326 Electric-field strength of radiated disturbance: EN55011 Group 1, Class A Terminal noise voltage: EN55011 Group 1, Class A EMS: EN61326

■ Indication Structure / Settings Structure

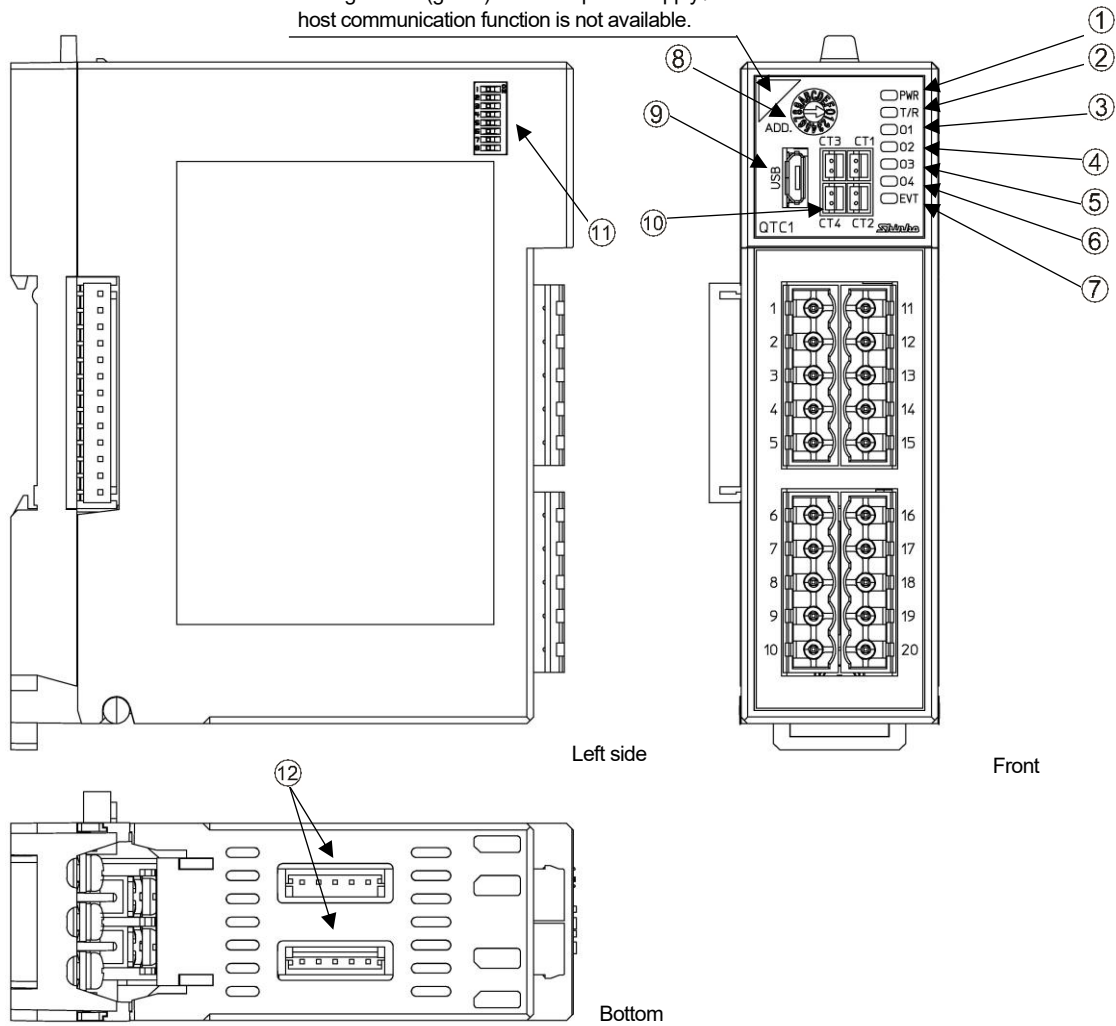
Terminal block type

* Triangle mark (green) when the power supply / host communication function is not available.



Connector type

* Triangle mark (green) when the power supply / host communication function is not available.



Action Indicator

No.	Symbol (color)	Name, Task	No.	Symbol (color)	Name, Task
①	PWR (green)	Power indicator Off: No power supplied to module On: Power supplied to module Flashing: Internal error during warm-up (Non-volatile memory, ADC input circuit)	③	O1 (green)	CH1 control output indicator
			④	O2 (green)	CH2 control output indicator
			⑤	O3 (green)	CH3 control output indicator
			⑥	O4 (green)	CH4 control output indicator
②	T/R (yellow)	Communication indicator Flashing: Normal communication, Communication error (reception error) Off: Communications error (no response), USB communication	⑦	EVT (red)	Event indicator Lights up when an alarm is activated, a loop break alarm is activated, or a heater burnout alarm (optional) is activated. Flashes in the event of a sensor error or overscale/underscale.

Switches, Connectors

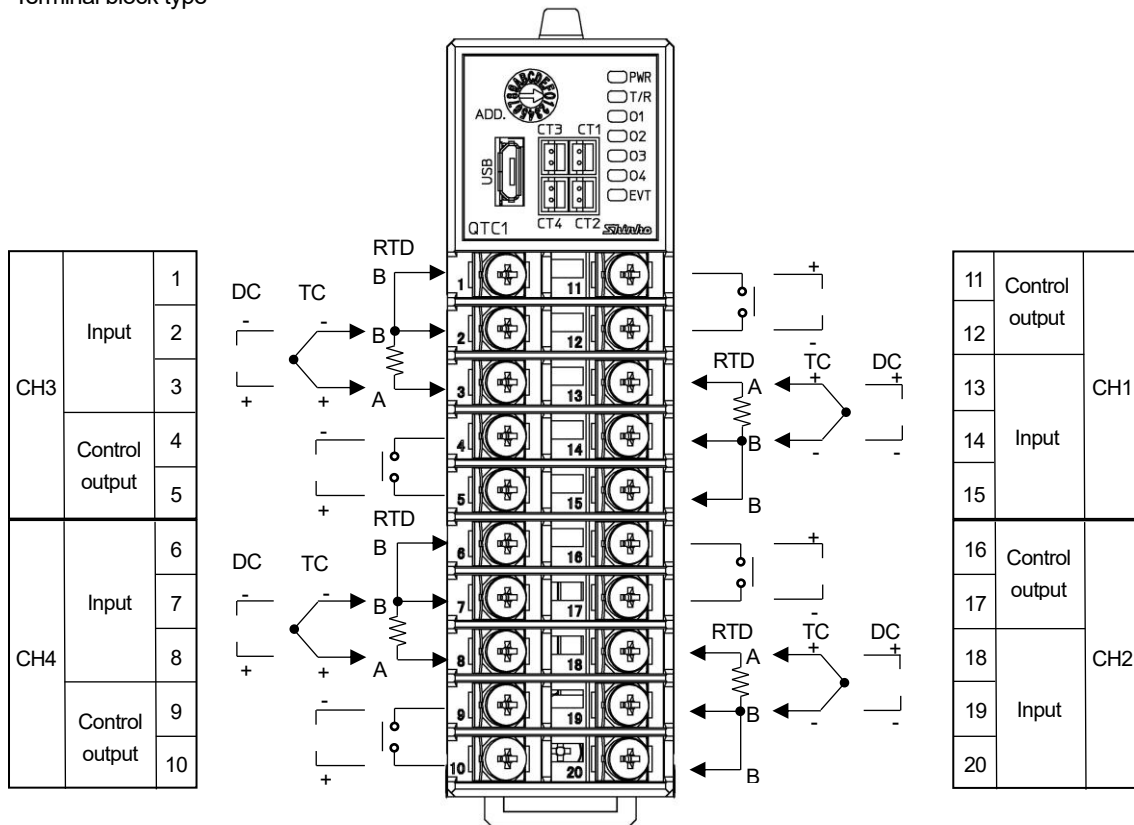
No.	Symbol	Name, Task
⑧	ADD.	Rotary switch for module address selection Use the rotary switch to select the module address from 0 to F (1 to 16).
⑨	USB	Micro USB Type-B console communication connector
⑩ (*1)	CT1	CH1 CT input connector
	CT2	CH2 CT input connector
	CT3	CH3 CT input connector
	CT4	CH4 CT input connector
⑪		DIP switches for selecting communications specification Use the DIP switches for selecting the communication speed, data bit, parity, stop bit, and communication protocol.
⑫ (*2)		Event input/output connector

(*1) When using the heater burnout alarm option (heater burnout alarm option symbols: -2, -A)

(*2) When using the event input or event output option (event input/output option symbols: 1, 2)

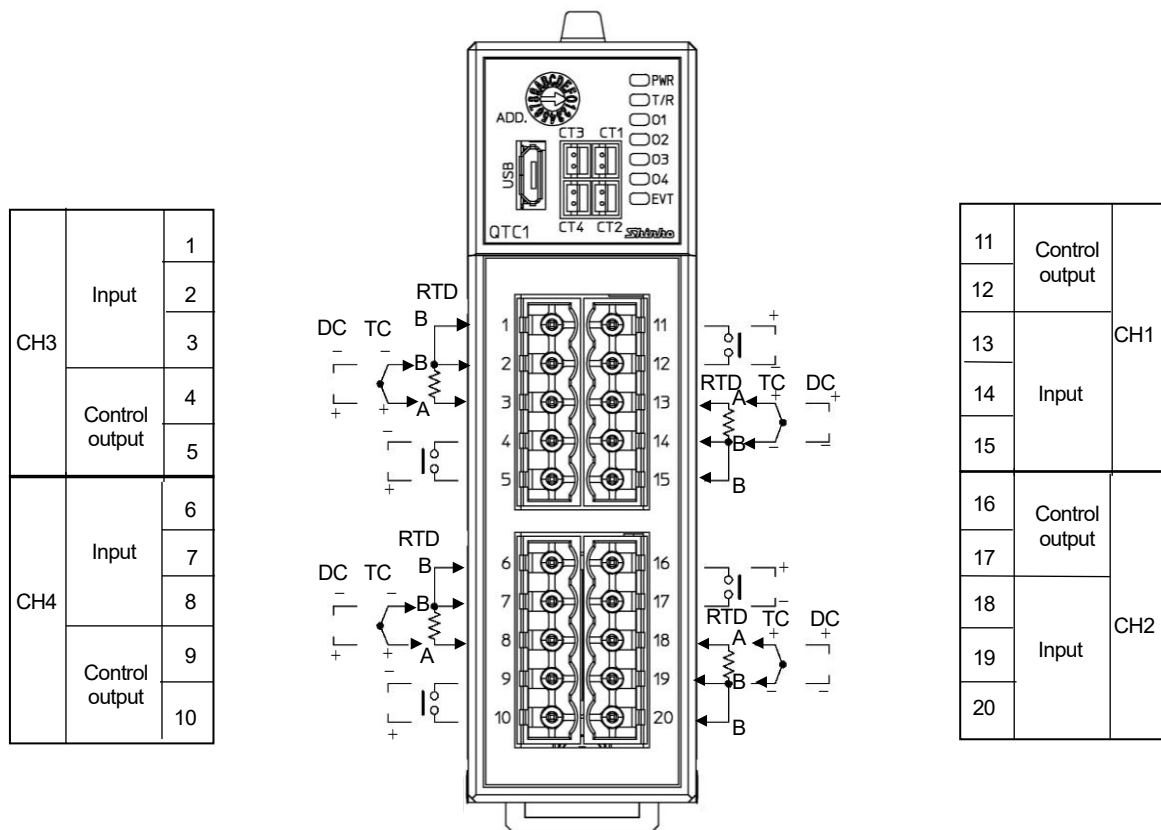
■ Terminal Arrangement

Terminal block type



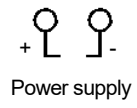
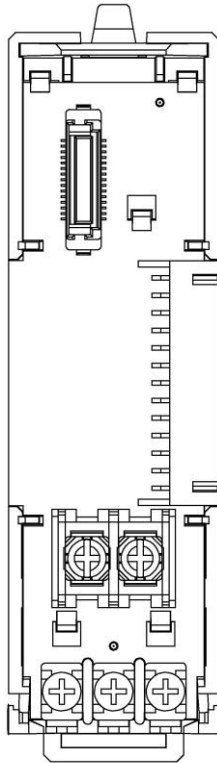
Front

Connector type

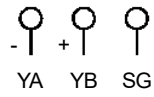


Front

QTC1-4P

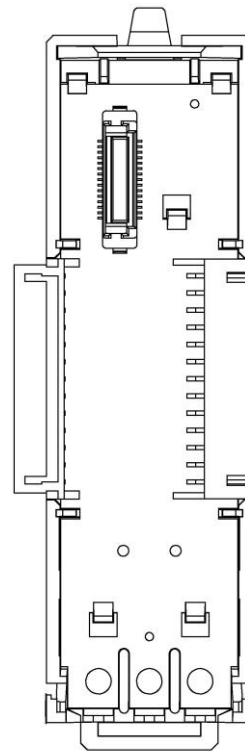


Power supply



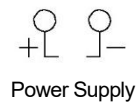
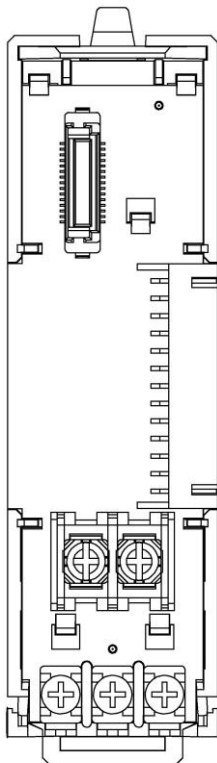
RS-485 serial communication (*)

QTC1-40

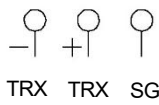


(*) The QTC1-40 do not include a Power supply terminal and RS-485 serial communication terminal.

QTC1-4C



Power Supply



CUnet communication

Base

■ Standard Functions

Alarm Output

Alarm types	12 alarm types: High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limit range alarm, Process high alarm, Process low alarm, High limit with standby alarm, Low limit with standby alarm, High/Low limits with standby alarm, High/Low limits independent alarm, High/Low limit range independent alarm, High/Low limits with standby independent alarm. No alarm action can also be selected. (Factory default: No alarm action)
Action	ON/OFF action
Hysteresis	0.1 to 1000.0°C (0.1 to 1800.0°F) (Factory default: 1.0°C (1.8°F)) Direct current, DC voltage input: 1 to 10000 (Factory default: 10)
Output	Event output assigned by status flag or event output assignment selection
Alarm value 0 Enabled/Disabled	If "Enabled" is selected in [Alarm value 0 Enabled/Disabled], the following alarm type activates even if the alarm value is set to 0 (zero): High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limit range alarm, High limit with standby alarm, Low limit with standby alarm, High/Low limits with standby alarm, High/Low limits independent alarm, High/Low limit range independent alarm, High/Low limits with standby independent alarm.

Loop Break Alarm

Setting range	Loop break alarm time: 0 to 200 minutes Loop break alarm action span: Thermocouple, RTD inputs: 0 to 150°C (0 to 270°F) or 0.0 to 150.0°C (0.0 to 270.0°F) Direct current, DC voltage input: 0 to 1500
Output	Event output assigned by status flag or event output assignment selection

Set Value Ramp Function

When changing SV, this function enables control at the specified change rate between the previous SV and the changed SV rate. When control is enabled, control is performed at the specified change rate between the current PV and the SV.	
Setting range	SV rise rate: Thermocouple, RTD inputs: 0 to 10000°C/minute (0 to 18000°F/minute) or 0.0 to 1000.0°C/minute (0.0 to 1800.0°F/minute) Direct current, DC voltage input: 0 to 10000/minute SV fall rate: Thermocouple, RTD inputs: 0 to 10000°C/minute (0 to 18000°F/minute) or 0.0 to 1000.0°C/minute (0.0 to 1800.0°F/minute) Direct current, DC voltage input: 0 to 10000/minute The factory default for both the SV rise rate and SV fall rate is 0. However, when set to 0, this function is disabled.

Power-On Return Action Selection

Select whether to return to a continued state (state before the power was turned off) or in the stopped state after the power is turned on.

Non-Volatile IC Memory Data Save Selection

Selecting whether to allow or prohibit saving data to the non-volatile IC memory is possible. If saving is prohibited, all setting values can be changed temporarily until the power is turned off and back on, at which time the values will return to the values applied before saving was prohibited.

Automatic/Manual Control Switching

Switching between automatic and manual control is possible through host communication.
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Sensor Correction Coefficient

Setting the sensor input value slope is possible.	
Setting range	0.000 to 10.000 (Factory default: 1.000)

Sensor Correction

If the control location temperature and the sensor location temperature are different, shifting and correction of the PV is possible. (Valid within the rated input range regardless of the sensor correction value.)	
Setting range	Thermocouple, RTD inputs: -100.0 to 100.0°C (-180.0 to 180.0°F) Direct current, DC voltage input: -1000 to 1000

Control Function Selection

Selecting between standard control, heating/cooling control, cascade control, or output selection function is possible.	
Cascade control	The master-side operation output amount obtained from the master-side SV and PV (CH1 or CH3; same applies below) is substituted for the slave-side SV (CH2 or CH4; same applies below), slave-side calculation is performed, and the slave-side control output is output. (With CH1 control output OFF (Current output: 0 mA))
Heating/cooling control	When heating/cooling control is selected as the control function for CH1, heating/cooling control is performed with CH1 as the heating side output and CH2 as the cooling side output. When heating/cooling control is selected as the control function for CH3, heating/cooling control is performed with CH3 as the heating side output and CH4 as the cooling side output. Heating/cooling control cannot be selected for CH2 and CH4.
Output selection function	When using the controller, if there is an unused input and an error occurs in the input channel currently being used, the input can be changed to an unused channel, and the output location for the input can be selected.

Extension Function Selection

Selecting between no extension, Peak power suppression function and the auto-balance control function is possible.	
Peak power suppression function	A function to suppress the peak power value when there is a power limit for the facility. The total current can be set, and power suppression control can be performed when the sum of the current values set for each channel is less than or equal to the total current. *(Disabled when Direct current output or DC voltage output are selected, and each set value change is effective only when control is stopped.)
Auto-balance control function (For devices with power supply / host communication function)	This function controls the temperature of a controlled object at multiple control points to suppress partial burning and mechanical distortion. There are two auto-balance control types: using multiple control modules, or using independent control modules.

Output Gain/Bias Function

When multiple outputs are used for inputs, such as input-based heater controls at multiple outputs, if the output amount distribution is known in advance, this function enables uniform control by setting the ratio and bias for the reference output.
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Proportional band decimal point position selection

For the direct current input and DC voltage input ranges, the decimal point position of the proportional band can be changed. Since the proportional band of the direct current input and DC voltage input ranges corresponds to a percentage of the full scale, it can be used differently depending on the intended use, such as when detailed settings are desired or when the sensitivity of the control response is to be reduced.

Control action selection when input error

The user can select whether to continue the control operation when the input becomes an input error, overscale, or underscale, or whether to output the fixed operation amount set in the input error operation amount setting.

Input Calculation Function

Input calculation function selection can be used to select between standard input, difference input, and addition input. The calculation function selected for CH1 applies to CH1 and CH2, and the calculation function selected for CH3 applies to CH3 and CH4. However, the selection becomes invalid if a non-standard control function is selected.

Input Difference Detection Function

The input difference between the current input difference detection selection channel and the selected channel is detected, and if the value set in the input difference detection setting is exceeded, 1 is set as the input difference flag. However, if the current input difference detection selection channel is selected, this function is disabled.

■ Optional Functions

Heater Burnout Alarm (Heater burnout alarm option symbols: -2, -A)

This function cannot be added to Direct current output, DC voltage output. The status can be determined by reading the status flag during serial communication.	
Rating	Single-phase: 20 A, Single-phase: 100 A (specified when ordering)
Setting range	20 A: 0.0 to 20.0 A (Off when set to 0.0) 100 A: 0.0 to 100.0 A (Off when set to 0.0)
Setting accuracy	±5% of rated value
Action point	Set value
Action	ON/OFF action
Output	Event output selected by status flag or event output assignment selection

Event Input (Event input/output option symbol: 1)

When an event input is input, the operations selected by the event input assignment selection are performed.	
Event input assignment selection	No action, Control start/stop (CH independent), Control start/stop (CH interlock)
No. of inputs	4
Input method	Voltage contact input sink method
Circuit current when closed	Approx. 6 mA
Reading judgment time	Approx. 100 ms

Event Output (Event input/output option symbol: 2)

The operations selected by the event output assignment selection are performed.	
Event output assignment selection	No action, EVT output (CH independent), EVT output (CH interlock)
No. of outputs	4
Circuit	NPN open collector
Maximum load voltage	30 V DC
Maximum load capacity	50 mA

Power Supply / Host Communication Function (Power supply/communication option symbol: P)

Communication line	EIA RS-485 compliant										
Communication method	Half-duplex communication										
Communication speed	Selecting 9600, 19200, 38400, or 57600 bps is possible using the DIP switches. (Factory default: 57600 bps)										
Synchronization method	Start-stop synchronization										
Data bit/parity	Data bits: 8 Parity: Selecting even, odd, or no parity is possible using the communication specification selection DIP switch. (Factory default: 8 bits / Even)										
Stop bit	Selecting 1 or 2 is possible using the communication specification selection DIP switch. (Factory default: 1)										
Response delay time setting	0 to 1000 ms (Factory default: 0 ms) The response from the module after receiving a command from the host can be delayed.										
Data structure	<table border="1"> <tr> <td>Communication protocol</td><td>MODBUS RTU</td></tr> <tr> <td>Start bit</td><td>1</td></tr> <tr> <td>Data bit</td><td>8</td></tr> <tr> <td>Parity</td><td>Enabled (even, odd), Disabled</td></tr> <tr> <td>Stop bit</td><td>1 or 2</td></tr> </table>	Communication protocol	MODBUS RTU	Start bit	1	Data bit	8	Parity	Enabled (even, odd), Disabled	Stop bit	1 or 2
Communication protocol	MODBUS RTU										
Start bit	1										
Data bit	8										
Parity	Enabled (even, odd), Disabled										
Stop bit	1 or 2										

Smart InterFace (SIF) Function (Program-less communication function)

This function enables a serial communication connection with Mitsubishi Electric MELSEC-Q series PLCs and writes/reads various data to/from the PLC register using the PLC communication protocol. The communication protocol uses QW and QR commands, and PLCs capable of using A-compatible 1C frame AnA/AnU common commands (QR/QW) (D resister) are supported.
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CUnet communication function (Power supply/communication option symbol: C)

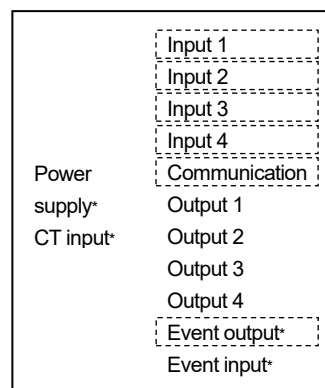
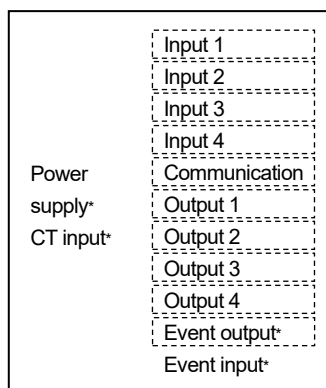
Connection type	ulti-drop								
Communication method	2-wire half-duplex								
Synchronization method	Bit-synchronous								
Error detection	CRC-16								
Number of occupied slave addresses	1								
Maximum number of connected nodes	64 nodes								
Communication speed, Communication distance	<table border="1"> <tr> <td>Communication speed</td><td>Maximum network length</td></tr> <tr> <td>12Mbps</td><td>100m</td></tr> <tr> <td>6Mbps</td><td>200m</td></tr> <tr> <td>3Mbps</td><td>300m</td></tr> </table>	Communication speed	Maximum network length	12Mbps	100m	6Mbps	200m	3Mbps	300m
Communication speed	Maximum network length								
12Mbps	100m								
6Mbps	200m								
3Mbps	300m								
Isolation method	Pulse transformer isolation								
Impedance	100Ω								
Termination resistance	Last connection, set by CUnet slave This instrument is not equipped.								

■ Insulation / Dielectric Resistance

Circuit Insulation Configuration

· Relay output, Open collector output

· Non-contact voltage output, Direct current output, DC voltage output



Insulation resistance	500 V DC, 10 MΩ or more
Dielectric resistance	Between input terminal and ground: 1.5 kV AC for 1 minute Between power terminal and ground: 1.5 kV AC for 1 minute Between power terminal and input terminal: 750 V AC for 1 minute

■ Environmental Conditions

Ambient temperature	-10 to 50°C (Non-condensing, no icing)
Ambient humidity	35 to 85% RH (Non-condensing)
Altitude	2,000 m or less
Installation environment	Pollution Degree 2 (according to EN61010-1)
Memory protection	Non-volatile IC memory (write cycles: 1 trillion times)
Environmental specifications	RoHS Directive Compliant

■ Attached Functions

Power failure countermeasures	Setting data is backed up to non-volatile IC memory.								
Self-diagnosis	The watchdog timer monitors runaway and halt of the program, and when an abnormality is detected, it resets the MCU and initializes the instrument.								
Automatic cold junction temperature Compensation	Detect the temperature at the connection terminal between the thermocouple and the instrument is detected and adjusted to be the same as if the reference contact were always at 0°C (32°F). (Valid only for channels for which thermocouple input is selected)								
PV filter time constant setting	A digital first-order low-pass filter is used to reduce PV fluctuations caused by noise.								
Moving average count setting	Values that alter input values due to noise are averaged to stabilize the indicated values.								
CH enable/disable selection	Enabled or disabled can be selected for each channel. When disabled, all operations for the selected channel are disabled, and PV becomes 0.								
Overscale	A status flag is set when overscale is detected. However, control continues during overscale.								
Underscale	A status flag is set when underscale is detected. However, control continues during underscale.								
Sensor error	A status flag is set when a sensor error is detected, and control output is turned OFF.								
Cold junction error	A cold junction error occurs when the internal cold junction temperature is below -10°C (14°F) or above 50°C (122°F). (Valid only for channels for which thermocouple input is selected)								
ADC error	If there is an error such as a failure in an internal circuit, the control output of the channel where the error occurred is turned OFF. When this occurs, the PV is 32767.								
Warm-up display	After the power is turned on, the power indicator flashes every 500 ms for about 3 seconds.								
Cumulative contact open/close count measurement function	Cumulative measurement of the control output ON/OFF count is possible.								
Cumulative energization time measurement function	Checking the cumulative energization time is possible.								
Cumulative heater energization time measurement function	Checking the cumulative heater energization time is possible for relay output and SSR output.								
Error history	In the event of an error, the bit ON/OFF status and energization time are saved. The 10 most recent errors are saved. Error history is available for each channel, and device common errors are saved in the all-channel error history. <table border="1"> <tr> <td>Error details</td><td>Alarm 1, Alarm 2, Alarm 3, Alarm 4, Heater burnout alarm, Loop break alarm, Sensor error, Input error (overscale), Input error (underscale), Cold junction error, Non-volatile IC memory error, ADC error</td></tr> </table>	Error details	Alarm 1, Alarm 2, Alarm 3, Alarm 4, Heater burnout alarm, Loop break alarm, Sensor error, Input error (overscale), Input error (underscale), Cold junction error, Non-volatile IC memory error, ADC error						
Error details	Alarm 1, Alarm 2, Alarm 3, Alarm 4, Heater burnout alarm, Loop break alarm, Sensor error, Input error (overscale), Input error (underscale), Cold junction error, Non-volatile IC memory error, ADC error								
Console communication	Connect a communication cable (commercially available) to the console communication connector to perform operation from an external computer using the console software (SWC-QTC101M). <table border="1"> <tr> <td>Operations that can be performed</td><td>(1) Reading and configuration of SV, PID, and various other setting values (2) Reading of PV and operating statuses (3) Modification of functions</td></tr> <tr> <td>Communication protocol</td><td>MODBUS RTU</td></tr> <tr> <td>Communication cable</td><td>USB to Micro USB Type-B (Commercially available)</td></tr> <tr> <td>Software</td><td>Console software (SWC-QTC101M)</td></tr> </table>	Operations that can be performed	(1) Reading and configuration of SV, PID, and various other setting values (2) Reading of PV and operating statuses (3) Modification of functions	Communication protocol	MODBUS RTU	Communication cable	USB to Micro USB Type-B (Commercially available)	Software	Console software (SWC-QTC101M)
Operations that can be performed	(1) Reading and configuration of SV, PID, and various other setting values (2) Reading of PV and operating statuses (3) Modification of functions								
Communication protocol	MODBUS RTU								
Communication cable	USB to Micro USB Type-B (Commercially available)								
Software	Console software (SWC-QTC101M)								
Firmware update function	Connect the communication cable (commercial item) to the console communication connector, and use the console software (SWC-QTC101M) to update the functions from an external computer. When the firmware is updated, the set values are initialized.								

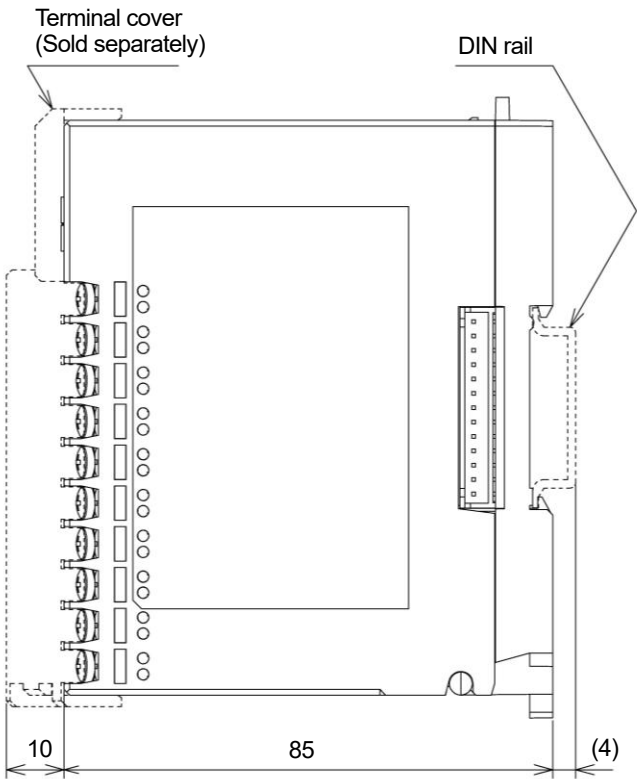
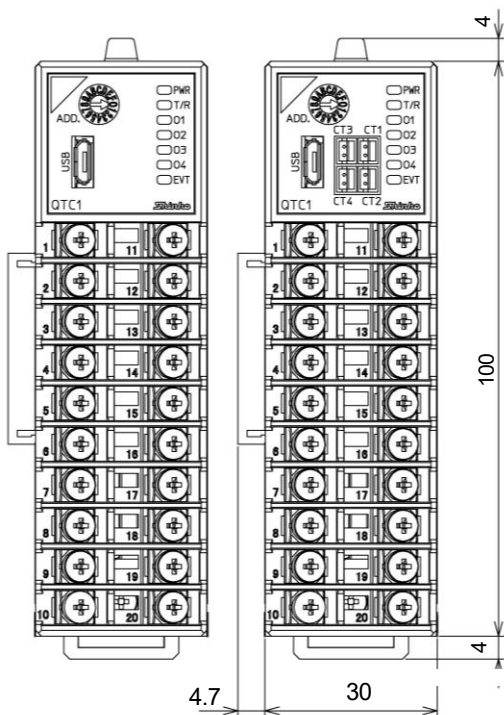
■ Other

Power supply voltage	24 V DC Allowable fluctuation range: 20 to 28 V DC
Power consumption	5 W or less
Rush current	Max. 10 A
Accessories included	Power supply terminal cover (1) (for devices with power supply / host communication function or CUNet communication function), Mounting and wiring instruction manual (1) Connector for wiring (2ESS-05P): 4 (Connector type)
Accessories sold separately	Shunt resistor (50 Ω) (RES-S01-050), Termination resistance (100 Ω) (RES-S07-100), Front terminal cover (TC-QTC), CT for heater burnout alarm 20 A (CTL-6-S-H), CT for heater burnout alarm 100 A (CTL-12-S36-10L1U), Heater burnout connector harness (WQ), Event input/output connector harness (EVQ)
Instruction manual	Please download the full Instruction Manual from the Shinko website. https://shinko-technos.co.jp/e/

■ Dimensions (Scale: mm)

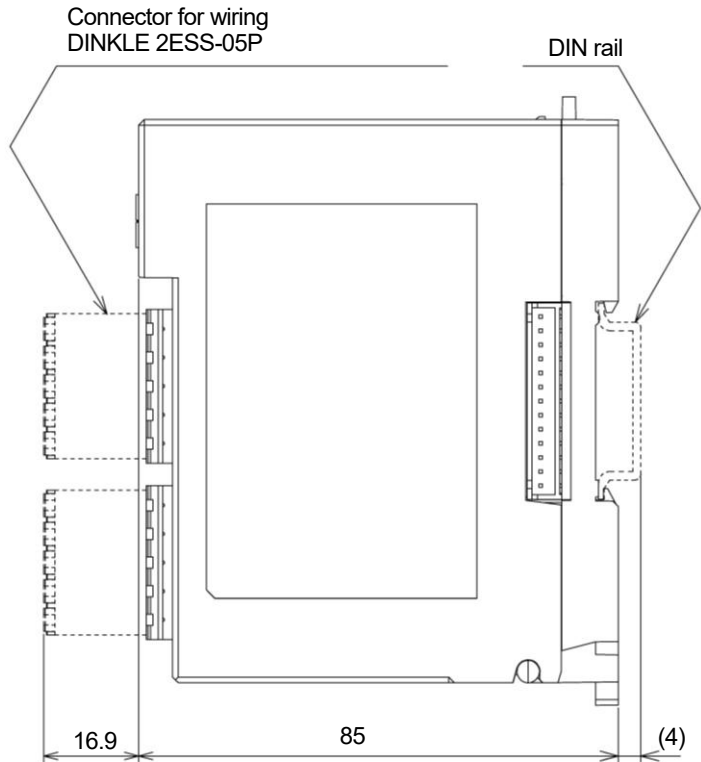
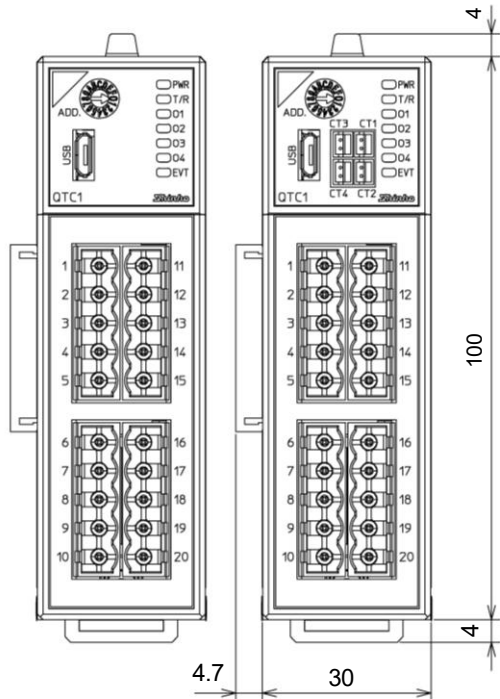
Terminal block type

Main Unit

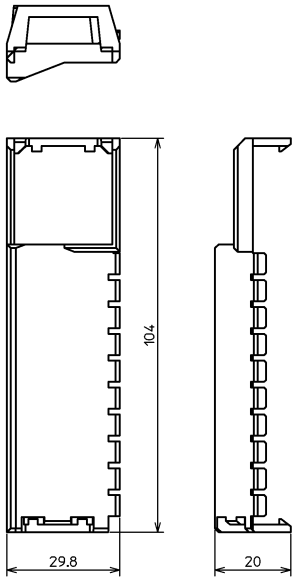
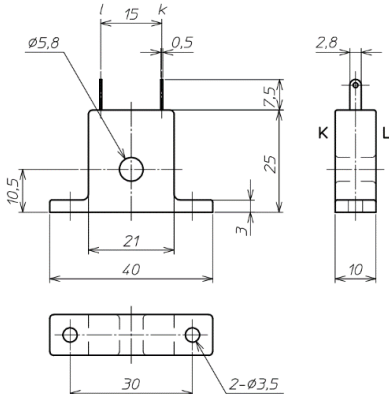
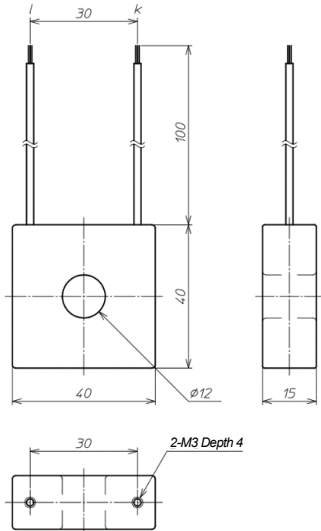
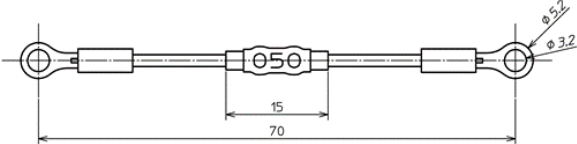
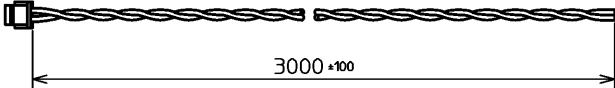


Connector type

Main Unit



Accessories Sold Separately

Front terminal cover TC-QTC		Heater burnout alarm CT (current transformer)	
		CTL-6-S-H (for 20 A) 	CTL-12-S36-10L1U (for 100 A) 
Shunt resistor: 50 Ω, RES-S01-050		Heater burnout alarm connector harness WQ	
			
Termination resistance: 100 Ω, RES-S07-100		Event input/output connector harness EVQ	
