# **INSTRUCTION MANUAL**

# 和文は裏面をご覧下さい。 DIN Rail Mounted Indicating Controller DCL-33A

No. DCL31JE3 2019.01

## Shinko TECHNOS CO., LTD. **TECHNOS CO., LTD.** Head office: 2-5-1, Senbahigashi, Minoo, Osaka, 562-0035, Japan TEL: +81-72-727-6100 FAX: +81-72-727-7006 URL: http://www.shinko-technos.co.jp/e/ E-mail: overseas@shinko-technos.co.jp For detailed usage, refer to the Instruction Manual for the DCL-33A. Please download the full Instruction Manual from Shinko website http://shinko-technos.co.jp/e/ → Support & Downloads → Downloads → Manuals

Thank you for purchasing our DCL-33A, DIN Rail Mounted Indicating Controller. This manual contains instructions for the mounting, functions, operations and notes when operating the DCL-33A. To ensure safe and correct use, thoroughly read and understand this manual before using this instrument. To prevent accidents arising from the misuse of this instrument, please ensure the operator receives this manual.

Heating/Cooling control output

(OUT2) (DC option)

Safety Precautions (Be sure to read these precautions before using our products.) The safety precautions are classified into 2 categories: "Warning" and "Caution". Warning: Procedures which may lead to dangerous conditions and cause death or serious injury, if not arcrited up to prometiu

carried out properly. ▲ Caution: Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.

## **▲** Warning

. To prevent electric shock or fire, only Shinko or other qualified service personnel may handle the inner To prevent electric shock of me, only online of other qualified solver personnel may handle the initial assembly.
 To prevent electric shock, fire or damage to the instrument, parts replacement may only be undertaken by

Shinko or other qualified service personnel.

## ▲ SAFETY PRECAUTIONS

 To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
 This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.) • External protection devices such as protective equipment against excessive temperature rise, etc. must be

installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
 This instrument must be used under the conditions and environment described in this manual. Shinko

Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

#### **Specifications**

Power supply voltage	100 to 240 V AC 50/60 Hz, Allowable voltage fluctuation: 85 to 264 V AC 24 V AC/DC 50/60 Hz, Allowable voltage fluctuation: 20 to 28 V AC/DC		Alarm output:
Base accuracy (at ambient temperature 23°c, for a single unit mounting)	Thermocouple input: Within $\pm 0.2\%$ of each input span $\pm 1$ digit, or $\pm 2^{\circ}_{\mathbb{C}}$ (4°), whichever is greater However, R, S inputs, 0 to 200° (32 to 392°): Within $\pm 6^{\circ}_{\mathbb{C}}$ (12°) B input, 0 to 300° (32 to 572°): Accuracy is not guaranteed. K, J, E, T, N inputs, Less than 0° (32°): Within $\pm 0.4\%$ of input span $\pm 1$ digit, or $\pm 4^{\circ}_{\mathbb{C}}$ (8°), whichever is greater RTD input: Within $\pm 0.1\%$ of each input span $\pm 1$ digit, or $\pm 1^{\circ}_{\mathbb{C}}$ (2°), whichever is greater DC voltage input: Within $\pm 0.2\%$ of each input span $\pm 1$ digit Direct current input: Within $\pm 0.2\%$ of each input span $\pm 1$ digit		(Alarm, Loop bre output terminals. The alarm actior alarm), and if th (High/ Low limit When De-energi alarm is activate Setting accurad Action: ON/OFF Hysteresis: The DC dec
Input sampling period	125 ms		Output: Open of Alarm type: H
Power consumption	100 to 240 V AC: Approx. 5 VA max. 24 V AC: Approx. 4 VA max. 24 V DC: Approx. 4 W max.		High/Low lin limit range i High limit w
Ambient Temperature, Humidity	0 to 50°с, 35 to 85 %RH (Non-condensing)		limits with s alarm. Energized/D
Weight	Approx. 100 g	EVT output	24 alarm typ
Accessories	Instruction manual excerpt: 1 copy When W option is ordered: Connector harness W 3 m 1 length When W option (5A, 10A, 20A) is ordered: CT (CTL-6S) 1 piece When W option (50A) is ordered: CT (CTL-12-S36-10L1U) 1 piece When El option is ordered: Connector harness AOJ 3 m 1 length When EA option is ordered: Connector harness AOJ 3 m 1 length		Alarm Energize
	Relay contact: 1a, Control capacity: 3 A 250 V AC (resistive load) 1 A 250 V AC (inductive load cosΦ=0.4) Electrical life: 100,000 cycles		Alarm HOLD fu
Control output (OUT1)	Non-contact voltage (for SSR drive): 12 V DC±15% Max 40 mA (short circuit protected) Direct current: 4 to 20 mA DC, Load resistance: Max 550 Ω Output accuracy: Within ±0.3% of output span Resolution: 12000		Loop break alar (Loop break alar output terminals. Detects heater b Setting range: Loop break ala Loop break ala Thermocoup

 Caution for Installation
This instrument is intended to be used under the following environmental
conditions (IEC60101-1)): Overvoltage category II, Pollution degree 2
Ensure the mounting location corresponds to the following conditions:
 A minimum of dust, and an absence of corrosive gases
 No flammable, explosive gases
 No mechanical vibrations or shocks
 No exposure to direct sunlight, an ambient temperature of 0 to 50°c (32 to
 122F) that does not change randitive and no icing No exposure to direct sunlight, an ambient temperature of 0 to 50°C (32 to 122°F) that does not change rapidly, and no icing.
An ambient non-condensing humidity of 35 to 85 %RH
No large capacity electromagnetic switches or cables through which large current is flowing
No water, oil or chemicals or where the vapors of these substances can come into direct contact with the unit
Take note that the ambient temperature of this unit – not the ambient temperature of the control panel – must not exceed 50°C (122°F) if mounted within a control panel, otherwise the life of electronic components (especially electrolytic capacitors) may be shortened. electrolytic capacitors) may be shortened.

## Caution with Respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

Alarm o	output:					
(Alarm, Loop break alarm and optional Heater burnout alarm utilize common						
output terminals.) The alarm action point is set by ±deviation from the SV (excluding Process alarm), and if the input goes outside the range, alarm is turned ON or OFF (High/ Low limit range alarm). When De-energized action is selected in [Alarm Energized/De-energized], alarm is activated conversely. Setting accuracy: Same as base accuracy Action: ON/OFF action Hysteresis: Thermocouple, RTD inputs: 0.1 to 100.0°C (°F) DC voltage, current inputs: 1 to 1000 (The placement of the						
Output			VDC			
High/Low limits independent alarm, High/Low limit range alarm, High/Low limit range independent alarm, Process high alarm, Process low alarm, High limit with standby alarm, Low limit with standby alarm, High/Low limits with standby alarm, High/Lo						
			Alarm De-energized			
	EV/T indicator (Red)	0	Lit			
		ON	OFF			
Alarm HOLD function: Once an alarm is activated, the alarm output is maintained until the power is turned off.						
Loop break alarm output: (Loop break alarm, Alarm and optional Heater burnout alarm utilize common output terminals.) Detects heater burnout, sensor burnout and actuator trouble. Setting range: Loop break alarm time: 0 to 200 minutes Loop break alarm span: Thermocouple, RTD inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F) DC voltage, current inputs: 0 to 150°C (F) or 0.0 to 150.0°C (F)						
	(Alarm, output t The ala alarm), (High/ L When E alarm is Setting Action Hyster Output Alarm Hig limi alau Ene 24 Alarm Marm Loop b (Loop b output t Detects	output terminals.) The alarm action point is set b alarm), and if the input goes of (High/ Low limit range alarm). When De-energized action is set alarm is activated conversely. Setting accuracy: Same as ba Action: ON/OFF action Hysteresis: Thermocouple, R DC voltage, curre decimal point folli Output: Open collector, Contr Alarm type: High limit alan High/Low limits independen limit ange independent al High limit with standby alarm alarm. Energized/De-energized 24 alarm types. No alarm: Alarm Energized/De-energized EVT indicator (Red) EVT output Alarm HOLD function: Once a mainter Loop break alarm output: (Loop break alarm, Alarm and output terminals.) Detects heater burnout, senso	<ul> <li>(Alarm, Loop break alarm and optional Heater burroutput terminals.)</li> <li>The alarm action point is set by ±deviation from talarm), and if the input goes outside the range, al (High/ Low limit range alarm).</li> <li>When De-energized action is selected in [Alarm Eralarm is activated conversely.</li> <li>Setting accuracy: Same as base accuracy Action: ON/OFF action</li> <li>Hysteresis: Thermocouple, RTD inputs: 0.1 to 100 DC voltage, current inputs: 1 to 1000 decimal point follows the selection.)</li> <li>Output: Open collector, Control capacity: 0.1 A 24 Alarm type: High limit alarm, Low limit alarm High/Low limits independent alarm, Process high a High limit with standby alarm, Low limit with limits with standby alarm, Low limit with limits with standby alarm, Low limit vith alarm.</li> <li>Energized/De-energized action are applied to 24 alarm types. No alarm action can also be selected.</li> <li>EVT indicator (Red) Lit</li> <li>EVT output ON</li> <li>Alarm HOLD function: Once an alarm is activated maintained until the power</li> <li>Loop break alarm output:</li> <li>(Loop break alarm, Alarm and optional Heater burroutput terminals.)</li> <li>Detects heater burnout, sensor burnout and actuat Setting range:</li> </ul>			

Output: Open collector, Control capacity: 0.1 A 24 V DC

External Dimensions (Scale: mm)



#### **Name and Functions**

		No.	Name	Description
0000		1	EVT indicator	The red LED lights when Event output (Alarm, Loop break alarm or optional Heater burnout alarm) is ON. The red LED also lights when Cooling output is ON if Heating/Cooling control option is ordered.
	-3	2	OUT indicator	The green LED lights when OUT (control output) is ON (when Heating output is ON if Heating/Cooling control option is ordered). For Direct current output, flashes in 125 ms cycles corresponding to the output MV.
	-4	3	T/R indicator	The yellow LED flashes during Serial communication TX output (transmitting).
		4	AT indicator	The yellow LED flashes while auto-tuning (AT) is performing.
		5	PV Display	Indicates the PV (process variable), or setting characters in setting mode with a red LED.
		6	SV Display	Indicates the SV (desired value), output MV (manipulated variable) or each set value in each setting mode with a green LED.
	-	$\bigcirc$	UP key	Increases the numeric value.
		8	DOWN key	Decreases the numeric value.
	-9	9	MODE key	Switches the setting mode or registers the set data. (Registers the set data by pressing the MODE key.)
	-10	10	SUB-MODE key	Enters Auxiliary function setting mode 2 in combination with the MODE key. If 'Control output OFF' is selected in [SUB-MODE key function]: Turns all outputs OFF as if the power were turned OFF. If 'Auto/Manual control' is selected in [SUB-MODE key function]: Switches the Auto/Manual control. If 'Alarm HOLD cancel' is selected in [SUB-MODE key function]: Cancels Alarm HOLD.

## ▲ Caution

When setting the specifications and functions of this unit, connect mains power cable to terminals 1 and 2 first, then set them referring to "Key Operation Flowchart", before "Mounting to the Control Panel" and "Wiring".

• Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.

### **Terminal Arrangement**



When using ferrules, use the following ferrules made by Phoenix Contact GMBH & CO. Recommended Ferrules and Crimping Pliers

Recomment	aca i citulo	s and orninping r ners					
Terminal Number	Terminal Screw	Ferrules with Insulation Sleeve	Conductor Cross Sections	Tightening Torque	Crimping Pliers		
		AI 0.25-8 YE	0.2 to 0.25 mm <sup>2</sup>				
		AI 0.34-8 TQ	0.25 to 0.34 mm <sup>2</sup>				
1 to 1	M2.6	AI 0.5-8 WH	0.34 to 0.5 mm <sup>2</sup>	0.5 to 0.6 N ⋅ m			
1 to 4 M2.6		AI 0.75-8 GY	0.5 to 0.75 mm <sup>2</sup>	0.5 10 0.6 11 11	CRIMPFOX ZA 3 CRIMPFOX UD 6		
		AI 1.0-8 RD	0.75 to 1.0 mm <sup>2</sup>				
		AI 1.5-8 BK	1.0 to 1.5 mm <sup>2</sup>				
		AI 0.25-8 YE	0.2 to 0.25 mm <sup>2</sup>				
5 to 9	M2.0	AI 0.34-8 TQ	0.25 to 0.34 mm <sup>2</sup>	0.22 to 0.25 N ⋅ m			
		AI 0.5-8 WH	0.34 to 0.5 mm <sup>2</sup>				

# **Key Operation Flowchart**

Basic Operation Proced		Alarm T		Character Indication					
	pe and SV1 (desired value), following the procedure $(2)$ (4) (5) (6) (7) and (8) are indicated on the flow	riigiriiinii	The alarm action is ±deviation setting from the SV. The alarm is activated if the input value reaches the high lim	4	Input Type	C(W/Re5-26) 0 - 4200°	the territory	cっとに Converter	SV Rise/Fall rate start ty
tting item numbers (1), (2), ( Step 1]	(3), (4), (5), (6), (7) and (8) are indicated on the flow Turn the load circuit power OFF, and turn the pow		set value.	Al Cancel	<u>Е</u> К -200 - 1370°			Event input DI allocation (*3)	ちばちに SV start
peration before RUN	DCL-33A ON.	Low limit a	The alarm action is ± deviation setting from the SV. The alarm is activated if the input value drops below the low	handhant	<u>Е</u> <u>Г</u> К -199.9 - 400.0°				PH- PV start
	Select an input type and Alarm 1 type, etc. in Aux	kiliary function	limit set value.	Set value lock		C P C F Pt100 -300 - 1500°		Control ON/OFF	Control output OUT1/EV
	setting mode 2.	High/Low I	mits Combines High limit and Low limit alarm actions. Whe input value reaches the high limit set value or drops below		<u>г</u> <u>Г</u> R 0-1760°			Control ON/OFF	
	(1) Select an input type in [Input type].	alarm	the low limit set value, the alarm is activated.		<u> </u>				Heater burnout alarm ou
	(2) Select Alarm 1 type in [Alarm 1 type].	High/Low I range alarr			<u>Б</u> Б 0-1820°			이사/OFF	Enabled/Disabled
	If any Alarm 1 type except ("""") is selected, (3) to (6) will		Within the scale range of the controller, alarm action point	S Communication protocol	E -200 - 800°				Disabled
Step 2]	be indicated. Set them if necessary.		arm can be set at random and if the input reaches the random set action point, the alarm is activated.	Shinko protocol	<u>Γ</u> <u>Γ</u> <u>Τ</u> -199.9 - 400.0°				HE - Enabled
uxiliary function setting node 2	Note: If Alarm 1 type is changed, the Alarm 1 v default to 0 (0.0). Therefore, set the alarm		High limit and low limit set values can be set respectively	·	<u> </u>	- Circuit - Carl	independent diami	Auto/Manual control	Loop break alarm output
loue 2	(3) Select either Energized or De-energized in [Ala		The alarm is activated when the input value exceeds the high limit set value or drops below the low limit set value			C [] [] [] [] 0 - 10 V -1999 - 999		Integral action Holding	Enabled/Disabled
	Energized/De-energized].	High/Low I		Shinko protocol	C(W/Re5-26) 0 - 2315°			Set value memory	Disabled
	(4) Select either Holding or Not holding in [Alarm	1 HOLD range independe	The alarm is activated when the input value is between the low limit and high limit set values.	(Diock Read/Write)	FI Pt100 -199.9 - 850.0°	C	The The Energized Be energized	Control ON/OFF	A1 - A4 output Enabled/Dis
	function]. (5) Set Alarm 1 hysteresis in [Alarm 1 hysteresis].	High limit w	th After the power supply to the instrument is turned on, eve	Block Read/Write)	Pt100 -199.9 - 500.0			Direct/Reverse action	
	(6) Set Alarm 1 delay time in [Alarm 1 delay time].		if the input enters the alarm action range, the alarm is not	(Diock (Kead/Wille)			De-energized	Preset output 1	HE S Enabled
Step 3] Sub setting mode	(7) Set Alarm 1 value in [Alarm 1 value].	H/L limits w		)   hodel	- F K -320 - 2500	inden in the second sec	A1 - A4 HOLD function	010011	SUB-MODE key function
Step 4] Main setting mode			th action range. (If the controller is allowed to keep running	, Communication speed	F K -199.9 - 750.0		Not holding	□□□ 12 Preset output 2 ON/OFF	Control output
Step 5] RUN	Turn the load circuit power ON. Control action star	rts so as to standby	the standby function will be released once the input		- Second and the second s	F OUT2 cooling method		Auto/Manual control	Auto/Manual
	keep the control target at SV1 (desired value).	independer	t exceeds the alarm action point.)	<i>닉튐</i> 4800 bps	······································	F F Air cooling	Direct/Reverse action	1 14 Integral action Holding	RL F Alarm HOLD
				9600 bps				A1 - A4 value 0 Enabled/Disabled	Auto/Manual control afte
				/// 19200 bps	Б Б 0-3300°		Output status when input errors occur	Disabled	power ON
PV/SV Display	PV/SV Display			<u> </u>		F A1 - A4 type			
	(For 3 sec.)			Parity	<b>F</b> T -199.9 - 750.0°		Output ON	Remote/Local	· 금유규님 Manual con
in setting mode]	Output MV (manipulated			non E No parity	Annual of the second se	F H High limit alarm	Controller/Converter		
P <sup>V</sup> h SV1	variable) indication			EHEn Even		F		-E-/ Remote	-
sv [][[[][[]]] (Desired value)								nally mounted 50 $\Omega$ shunt resisted	or (*2) Built-in 50Q shunt i
		About S	etting Item		Key Operati		(*3) 001 to	007: Works when contacts are	closed (Input ON).
• •	Reverts to the PV/SV Display.	Upper left	: PV Display: Indicates setting characters. Lower left: SV Display:	play: Indicates the factory default.		ss and hold the $ riangle$ key and $ ilde{ extbf{C}}$		014: Works when contacts are	open (Input OFF).
Reverts to the PV/SV Displ	лау.	Right side	: Indicates the setting item.				key and 🧿 key (in that order) too		
		•	: This setting item is optional, and appears only when the option	is ordered.	• 🔄 + 🙆 (For	3 sec): Press and hold the $(\underline{})$ I	key and 🧿 key (in that order) tog	gether for approx. 3 seconds.	
PV/SV Display							key and $\bigtriangledown$ key (in that order) to		
		[		[	Set or select each	th item with the $(\Delta)$ or $(\nabla)$ key,	and register the value with the	) key.	
b setting mode]		PV/SV Display		PV/SV Display			eds to the next item, illustrated by		
P <sup>V</sup> <b>#</b> [ ] ] AT Perform/Ca		↓ <u></u> +©	(For 3 sec.)	(Fo	r 3 sec.) • To revert to the I	PV/SV Display, press the 🔘 ke	y for approx. 3 seconds in any mo	de.	
sv	sv proportional cycle	[Auxiliary function setting	mode 2]	[Auxiliary function setting mod	le 3]	•	•	_	
		(1) PV <b>5 E ה 5</b> Input type	₽ <sup>V</sup> ዘ ፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟፟ OUT2 ON/OFF	PV <b>E1 n</b> Event input	PV <b>81 3</b> F A	arm 3 type	PV RYL A Alarm 4 Energized	M PV Hohl Heat	ter burnout alarm
			sv [][] <i>I</i> [] hysteresis	sv D D allocation	sv		SV nonL De-energized	SV YE S output	
PV P OUT1 proportio									0
sv [][] 2.5 band		PV <b>5</b> <i>L H</i> Scaling high	limit PV Q1_15_Alarm 1 tuna	PV <b>' 7 2</b> SV2	PV 8 3 - 8 A	arm 3 value 0	PV <b>R H H d</b> Alarm 4		b break alarm output
		sv 1370	(2) SV Alarm Type	sv 110		nabled/Disabled	SV non E HOLD function	sv yE y Enab	hled/Disabled
PV P OUT2 proportio	ional (7) PV R I Alarm 1 value								O
<sup>sv</sup> [][] <i>I []</i> band		PV 45 LL Scaling low		PV # 1 = # Alarm 1 value 0	PV <b>R 3</b> ()()A	arm 3 value	PV R Y H Y Alarm 4 hysteresis		
↓ <b>○</b>	Q			sv n g Enabled/Disabled					
PV I Integral time	PV <b>H</b> Heater burnout		Sv nal n De-energized						
sv [] 200	svalarm value								
		PV <b>dP</b> Decimal point		PV # 1H Alarm 1 high limit			PV RHd H Alarm 4 delay time		
PV d Derivative time		sv	(4) SV n a n E HOLD function	sv alue	°v	arm value	<u>•• LILLIU</u>		abled/Disabled
									0
		PV FILF PV filter time	(5) PV <b>A</b> IH <b>Y</b> Alarm 1 hysteresis	PV <b>AL 2F</b> Alarm 2 type		arm 3 Energized/	PV r E n l Remote/Local	PV <b>8 3 5 L</b> Ala	rm 3 output
₩ <b>Π</b>		sv [] [] [] [] constant		<sup>sv</sup>	<sup>sv</sup> non L D		<sup>sv</sup> LocL	sv n o [] Ena	abled/Disabled
™ □□ 5 <i>0</i>	<sup>PV</sup> <b>L P</b> _ <b>H</b> Loop break								0
	sv []] alarm span	PV <b>a L H</b> OUT1 high I		PV R 2 : R Alarm 2 value 0			PV	PV <b>用</b> 45L Ala	
		sv 100		sv n g Enabled/Disabled		OLD function	sv	sv n o 🗍 Ena	abled/Disabled
	Reverts to the PV/SV Display.								Q
V [] [] [] ] proportional cy	/cle	PV <b>a L L</b> OUT1 low lin		PV R 2 Alarm 2 value	PVDJUU	arm 3 hysteresis	PV r ſ L H External setting	₽ <b>₽₽₽₽₽</b>	
O			sv HERT action		sv (() 1.0	ann o nysteresis	sv 1370 input high limit		in wiv preset
					PV				
PV/SV Display		₽ <sup>V</sup> <b>// ソ</b> \ OUT1 ON/C	FF PV AF b AT bias	Alarm 2 high limit	A SV CONSTANT	arm 3 delay time	PV r [ ] L External setting		12 MV preset
V + O (I	(For 3 sec.)	sv []][] <i>I</i> [] hysteresis		sv []][]] alarm value	sv::::::::::::::::::::::::::::::::		sv - 200 input low limit	\$v()[]] <b>[].[]</b> valu	
ciliary function setting m	node 1]			, O					0
Lock Set value lock	ר ה ל P Communication	PV <b>c R c I</b> OUT2 coolir		PV B2L n Alarm 2 Energized		arm 4 type	<sup>PV</sup> ר 🖁 ל א SV Rise/Fall rate	<sup>PV</sup> ភំគឺកដូ SUE	
w	sv 396 speed	sv #1 r 🗍 method	sv [] [] [] [] [] [] [] [] [] [] [] [] []	sv nonL De-energized	sv		<sup>sv</sup> <b>ኯ ዘ                                  </b>	sv <b></b> fung	
							Q		0
0	tion	PV <b>a L H b</b> OUT2 high I		PV <b>H2Hd</b> Alarm 2	PV 84-8 A	arm 4 value 0	PV - AL USV rise rate		o/Manual control
		sv [] 100	sv oFF input errors occur	SV non E HOLD function		nabled/Disabled	sv <b>n</b>	sv RUF o afte	r power ON
PV ho Sensor correcti									
<sup>PV</sup> Կ ք Sensor correcti <sup>sv</sup>		₽ <sup>v</sup> <i>a L L b</i> OUT2 low lin			PV <b>D</b> U (T)(T)				
<sup>SV</sup> Դ ք [][] SV [] [][][] U [] D.D] ↓ ©				<sup>₽</sup> <b>₽ ₽ ₽ ₽ ₽</b> Alarm 2 hysteresis	s PV <b>RY</b>	arm 4 value	SV fall rate	Reverts to the F	PV/SV Display.
۲۷ ۲ م () Sensor correcti sv () 0 0 ب 0 ۲۷ ۲ م ۲ ۲ Communication	on PV בהיק Stop bit	SV S	SV F		sv		sv [] [] [] [] [] [] [] [] [] [] [] [] []		
<sup>PV</sup> h @Sensor correcti <sup>sv</sup>	on אין	sv []][] <b>[]</b>	svenir						
PV h σ     Sensor correcti       SV     Ω       V     σ <td>on אין אין אין אין אין אין אין אין אין אין</td> <td></td> <td></td> <td>↓ O</td> <td></td> <td></td> <td>, O</td> <td></td> <td></td>	on אין			↓ O			, O		
P <sup>V</sup> └ @Sensor correcti S <sup>V</sup>	$\int_{S^{\vee}} \overline{n}  \overline{n}  \overline{n}$			↓ O					
P <sup>V</sup> └ O S <sup>V</sup> ○ O S <sup>V</sup> ○ O S <sup>V</sup> ← O S <sup>V</sup>	$\int_{S^{\vee}} \overline{n}  \overline{n}  \overline{n}$					arm 4 high limit			
<sup>2v</sup> 4 0 []] Sensor correcti <sup>Sv</sup> [] 0 0 ↓ <sup>2v</sup> c n h L Communication <sup>protocol</sup> ↓ ©	$\int_{S^{\vee}} \overline{n}  \overline{n}  \overline{n}$			₽ <sup>v</sup> ₽2 d y Alarm 2 delay time	е Р <sup>V</sup> <i>ЯЧН</i> ДА	arm 4 high limit	PV PoUT Control output	]	