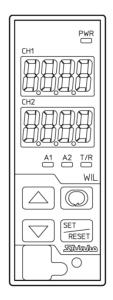
Plug-in Type Digital Indicating DO Meter WIL-102-DO

Instruction Manual





Preface

Thank you for purchasing our WIL-102-DO, Plug-in Type Digital Indicating DO (Dissolved Oxygen) Meter.

This manual contains instructions for the mounting, functions, operations and notes when operating the WIL-102-DO. To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.

To prevent accidents arising from the misuse of this instrument, please ensure the operator receives this manual.

Name	Term				
DO	Dissolved Oxygen				
DO Display	DO Concentration Display				
Display Mode	DO Concentration / Temperature Display Mode				
	DO % Saturation / Temperature Display Mode				
	Oxygen Partial Pressure / Temperature Display Mode				

Abbreviations used in this manual

Characters Used in This Manual

Indication	-/	0	1	2	3	Ч	5	5	7	8	3	Ľ	F
Number, °C/°F	-1	0	1	2	3	4	5	6	7	8	9	°C	°F
Indication	R	Ь	C	d	Ε	F	5	Н	1	L.	F	L	ñ
Alphabet	А	В	С	D	Е	F	G	Н	Ι	J	К	L	М
Indication	~	ø	Ρ	9	-	5	ſ	Ц	В	ū	Ŭ	Ч	1
Alphabet	Ν	0	Р	Q	R	S	Т	U	V	W	Х	Y	Ζ

▲ Caution

- This instrument should be used in accordance with the specifications described in the manual. If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow all of the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- This instrument is designed to be installed on a DIN rail within a control panel. If it is not, measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into 2 categories: "Warning" and "Caution". Depending on the circumstances, procedures indicated by \triangle Caution may result in serious consequences, so be sure to follow the directions for usage.

🗥 Warning

Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.



Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.

1 Warning

- To prevent an electrical shock or fire, only Shinko or other qualified service personnel may handle the inner assembly.
- To prevent an electrical shock, fire or damage to the instrument, parts replacement may only be undertaken by Shinko or other qualified service personnel.

$m m m \Lambda$ SAFETY PRECAUTIONS

- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- This instrument is intended to be used for measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protective equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
- This instrument must be used under the conditions and environment described in this manual. Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

1 Caution with Respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

PRECAUTIONS

1. Installation Precautions

\land Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1):

 \bullet Overvoltage category $~{\rm I\hspace{-0.5mm}I}$, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to $50^\circ C~(32$ to $122^\circ F)$ that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85%RH
- No large capacity electromagnetic switches or cables through which large current is flowing.
- No water, oil, chemicals or the vapors of these substances can come into direct contact with the unit.
- If the WIL-102-DO is installed within a control panel, the ambient temperature of the unit not the ambient temperature of the control panel must be kept under 50°C. Otherwise the life of electronic parts (especially electrolytic capacitors) of the unit will be shortened.

Note: Do not install this instrument on or near flammable material even though the case of this instrument is made of flame-resistant resin.

2. Wiring Precautions

Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or a malfunction.
- Use a solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the WIL-102-DO.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw may be damaged.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the instrument. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the DO Sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use the DO Sensor made by OPTEX Co., Ltd.
- Keep the input wires and power lines separate.

Note about the DO Sensor Cable

The DO Sensor cable is a highly-insulated (electrical) cable. Please handle it with utmost care as follows.

• Do not allow terminals and socket of the DO Sensor cable to come in contact with moisture or oil of any kind. Likewise, ensure fingers are clean, otherwise the insulation will deteriorate, resulting in unstable indication.

Be sure to keep the cable dry and clean at all times.

If the cable is stained, clean it with alcohol, and dry it completely.

- For calibration or checking/replacement, the DO Sensor cable should be wired with sufficient length.
- Keep the DO Sensor cable and junction cable away from electrical devices, such as motors or their power lines from which inductive interference emanates.

Connection

The DO Sensor cable has the following terminals.

Code	Terminal
RS-485 (SENSOR INPUT)	DO Sensor YB (+) input terminal (Blue)
RS-485 (SENSOR INPUT)	DO Sensor YA (-) input terminal (Green)
POWER FOR SENSOR	External power (+) terminal (Red)
POWER FOR SENSOR	External power (-) terminal (Black) and DO Sensor shield

White and brown cables of the DO Sensor are not used, so cut them off, and electrically insulate them. If they come in contact with other terminals, a malfunction will occur.

3. Operation and Maintenance Precautions

Caution

- Do not touch live terminals. This may cause an electrical shock or problems in operation.
- Turn the power supply to the instrument OFF when retightening the terminal or cleaning. Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument. (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, be careful not to put pressure on, scratch or strike it with a hard object.

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1. Model

1.1 Model

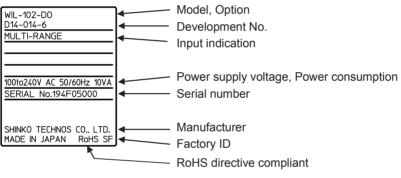
WIL-10	2	-DO		, 🗆	
Input Points	2				2 points
Input		DO			Optical DO Sensor
Power supply voltage				100 to 240 V AC (standard)	
		1		24 V AC/DC (*)	
Option		EVT	EVT output (EVT3, EVT4, EVT5, EVT 6)		

(*) Power supply voltage 100 to 240 V AC is standard.

When ordering 24 V AC/DC, enter "1" in Power supply voltage, after 'DO'.

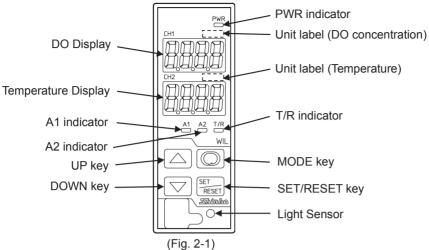
1.2 Model Label

The model label is attached to the left side of the case.



(Fig. 1.2-1)

2. Names and Functions of Instrument



Displays

DO Display	In Display Mode, DO Concentration, DO % saturation or Oxygen partial pressure is indicated in red.	
	In Setting mode, setting characters are indicated in red.	
Temperature	In Display Mode, temperature is indicated in red.	
Display	In Setting mode, set value (selected item) is indicated in red.	

Unit Labels

Unit label	Attach the user's unit of DO concentration from the included unit labels if
(DO concentration)	necessary.
Unit label	Attach the user's unit of temperature from the included unit labels if necessary.
(Temperature)	

Action Indicators

PWR indicator	ndicator When power supply to the instrument is turned ON, the yellow LED lights up.			
A1 indicator	When EVT1 output (Contact output 1) is ON, the red LED lights up.			
A2 indicator When EVT2 output (Contact output 2) is ON, the yellow LED lights up.				
T/R indicator	The yellow LED lights up during Serial communication TX output (transmitting).			

Keys

🛆 UP key	Increases the numeric value, or progresses through the selection items.			
	Switches the Display Mode.			
DOWN key	Decreases the numeric value, or progresses back through the selection items.			
O MODE key	Selects a group.			
SET/RESET key	Switches the setting modes, and registers the set value (or selected item).			

Light Sensor	Automatically measures and controls brightness of the DO Display,
	Temperature Display and Action indicators.

▲ Notice

When setting the specifications and functions of this instrument, connect mains power cable to terminals 13 and 14 first, then set them referring to "6. Outline of Key Operation and Setting Groups" and "7. Setup (pp. 20 to 40)" before performing "3. Mounting to and Removal from the Control Panel (p.9)" and "5. Wiring (p.16)".

3. Mounting to and Removal from the Control Panel

3.1 Site Selection

▲ Caution

Use within the following temperature and humidity ranges.

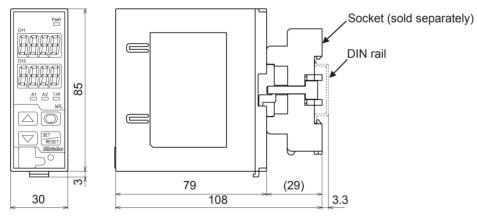
Temperature: 0 to 50° C (32 to 122° F) (No icing), Humidity: 35 to 85 %RH (Non-condensing) If the WIL-102-DO is installed within a control panel, the ambient temperature of the unit – not the ambient temperature of the control panel – must be kept under 50° C. Otherwise the life of electronic parts (especially electrolytic capacitors) of the unit will be shortened.

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category II, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- · A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to 50 $^\circ C$ (32 to 122 $^\circ F)$ that does not change rapidly
- An ambient non-condensing humidity of 35 to 85 %RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil, chemicals or the vapors of these substances can come into direct contact with the unit.

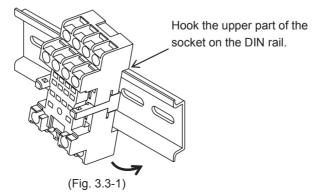
3.2 External Dimensions (Scale: mm)



(Fig. 3.2-1)

3.3 Mounting

(1) Hook the upper part of the socket on the DIN rail, and mount it (A clicking sound is heard).



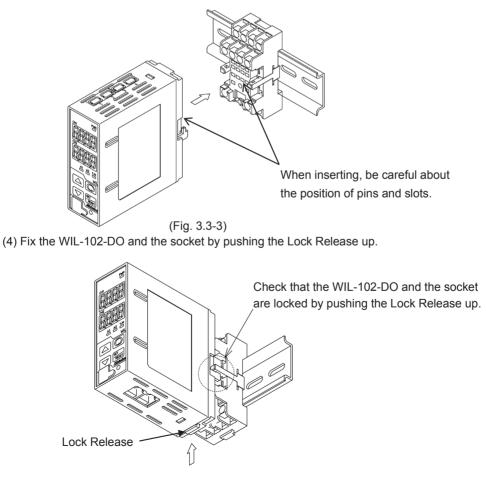
A Caution

Before inserting the WIL-102-DO into the socket, wire the unit while referring to Section "5. Wiring" (p.16).

(2) Check that the Lock Release has been lowered.



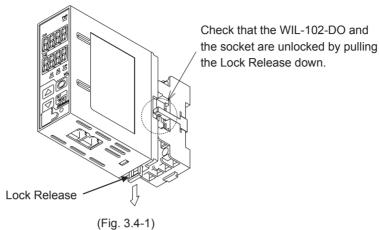
(3) Insert the WIL-102-DO into the socket.



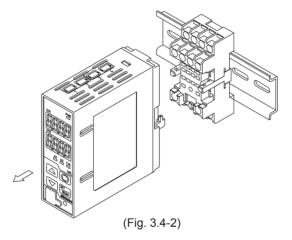
(Fig. 3.3-4)

3.4 Removal

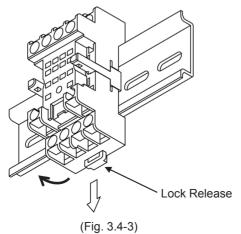
- (1) Turn the power supply to the unit OFF.
- (2) Pull the Lock Release down, and release the WIL-102-DO from the socket.



(3) Separate the WIL-102-DO from the socket.



(4) Remove the socket from the DIN rail by pulling the socket Lock Release (at the bottom of the socket) down.

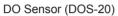


4. DO Sensor

4.1 Contents of Package

The following items are contained in the DO Sensor package.







(Fig. 4.1-1)

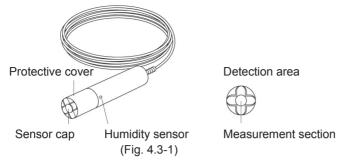


Calibration container

4.2 Caution when Using DO Sensor

Caution when Using DO Sensor						
1 Caution						
Do not use the DO Sensor for any purposes other than water quality measurement.						
A CONTRACTOR	Do not disassemble or modify. The sensor contains a high voltage component which may cause fire or electrical shock. For internal inspection, maintenance or repair, please consult us or our agency.					
(Fig. 4.2-1)						
e e e e e e e e e e e e e e e e e e e	Do not subject the sensor to any rough treatment. Do not drop the unit. Handle with care.					
(Fig. 4.2-2)						
(Fig. 4.2-3)	Do not touch the measurement section. If it is not clean, wipe it with a clean, soft cloth.					
e mart	Be careful not to damage the cable. Ensure that the cable is not tangled, nor caught or trapped in any way when installing and using the sensor. Use a spiral cable wrap to protect the cable. If the cable is damaged, it may malfunction when immersed, and fire or electrical shock will occur.					
(Fig. 4.2-4)						

4.3 Name of Sections



4.4 Attaching the Sensor Cap

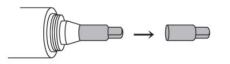
\land Caution

• Before attaching, make sure that the O-ring of the sensor is not crooked or is in the right position in the groove.

- Take the sensor cap out from the package just before mounting, and mount it immediately.
- When mounting the sensor cap, keep the dust or water from entering into the cap.

Otherwise correct measurement will not be performed.

- Date of manufacture is written on the storage case of sensor cap as the right diagram.
- (1) Remove the protective cover from the sensor by rotating it, then remove the red protective cap. Please carefully set aside the protective cap.





Protective cover

Date of manufacture: 04/2016

(Fig. 4.4-1)

Protective cap

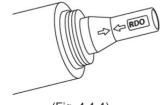
(Fig. 4.4-2)

(2) Take the provided sensor cap out from the storage case.



(Fig. 4.4-3)

(3) Match the arrows on the sensor cap and on the sensor, then push the sensor cap straight onto it until no gap is visible.



(Fig. 4.4-4)

(4) Reattach the protective cover.

4.5 Installing the DO Sensor

▲ Caution

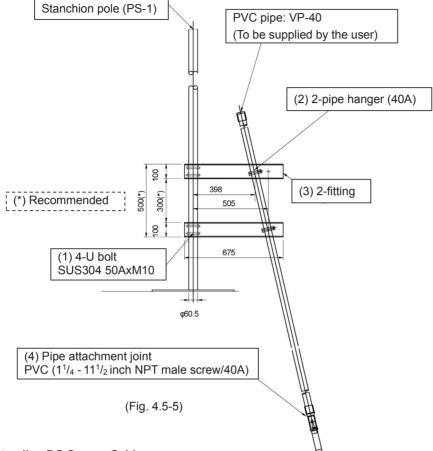
Before installation, remove the power supply cable from the power source.

After completion, wire the power supply cable.

	The end of DO Sensor cable is equipped with a
	female screw (1 ¹ / ₄ -11 ¹ / ₂ NPT) to enable a male screw
	to be attached to a severed pipe.
	NPT stands for National Pipe Thread Taper (which is
	a U.S. standard for tapered threads used on threaded
	pipes and fittings).
(Fig. 4.5-1)	
	When installing the DO Sensor, make sure that air
	bubbles are not present on and near the detection surface.
	If air bubbles accumulate in the measurement section
	area, correct measurement cannot be obtained.
(Fig. 4.5-2)	
	Do not install the DO Sensor near to any walls or
	where water collects.
	Correct dissolved oxygen in the tank (for measure- ment) cannot be measured.
Wall	
(Fig. 4.5-3)	
	Install the DO Sensor at a minimum of about 30 cm
	below the lowest water surface, taking water level
	changes into consideration.
$\int \int / 30$ cm minimum	
$\int \sqrt{-\sqrt{-1}}$	
(Fig. 4.5-4)	

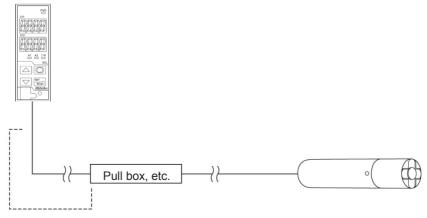
Recommendations

- As an accessory, the attachment (DA-1), sold separately, is recommended to use in a place where water currents are fast.
- The following (1) to (4) are included in the immersion holder.
- The Polyvinyl chloride (PVC) pipe (VP-40) is to be supplied by the user.



4.6 Extending DO Sensor Cable

DO Sensor cable standard length is 10 m. To extend the cable, refer to the following diagram. Use a device such as a pull box if necessary.



Extendable cable length: 1200 m (Nominal cross-section area: 0.2 to 1.25 mm²)

5. Wiring

🚹 Warning

Turn the power supply to the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.

1 Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or a malfunction.
- Use a solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the unit.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw may be damaged.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the instrument. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the DO Sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use the DO Sensor made by OPTEX Co., Ltd.
- Keep the input wires and power lines separate.

Note about the DO Sensor Cable

The DO Sensor cable is a highly-insulated (electrical) cable. Please handle it with utmost care as follows.

 Do not allow terminals and socket of the DO Sensor cable to come in contact with moisture or oil of any kind. Likewise, ensure fingers are clean, otherwise the insulation will deteriorate, resulting in unstable indication.

Be sure to keep the cable dry and clean at all times.

If the cable is stained, clean it with alcohol, and dry it completely.

- For calibration or checking/replacement, the DO Sensor cable should be wired with sufficient length.
- Keep the DO Sensor cable and junction cable away from electrical devices, such as motors or their power lines from which inductive interference emanates.

Connection

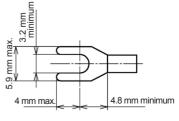
The DO Sensor cable has the following terminals.

Code	Terminal	
RS-485 (SENSOR INPUT)	DO Sensor YB (+) input terminal (Blue)	
RS-485 (SENSOR INPUT)	DO Sensor YA (-) input terminal (Green)	
POWER FOR SENSOR	External power (+) terminal (Red)	
POWER FOR SENSOR External power (-) terminal (Black) and DO Sensor shield		
White and brown cables of the DO Sensor are not used, so cut them off, and electrically insulate them.		
If they come in contact with other terminals, a malfunction will occur.		

5.1 Lead Wire Solderless Terminal

Use a solderless terminal with an insulation sleeve in which an M3 screw fits as follows. **The tightening torque should be 0.63 N·m.**

Solderless Terminal	Manufacturer	Model
Y-type	Nichifu Terminal	TMEV1.25Y-3S



5.2 Terminal Arrangement Standard specifications

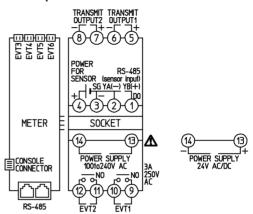
TRANSMIT 8 Power For Sensor R R (sensor input SG YA(—) YB(+ METER SOCKET F (14) (13) Λ (14 POWER SUPPLY 100to240V AC POWER SUPP 24V AC/DO NO 2500 r<mark>o o</mark> (11 RS-485

Modular Jack Pin (WIL-102-DO side arrangement)

No. 1	No. 1	СОМ
No. 6	No. 2	NC
No. 1	No. 3	YB(+)
	No. 4	YA(-)
RS-485	No. 5	NC
	No. 6	COM

(Fig. 5.2-1)

EVT option



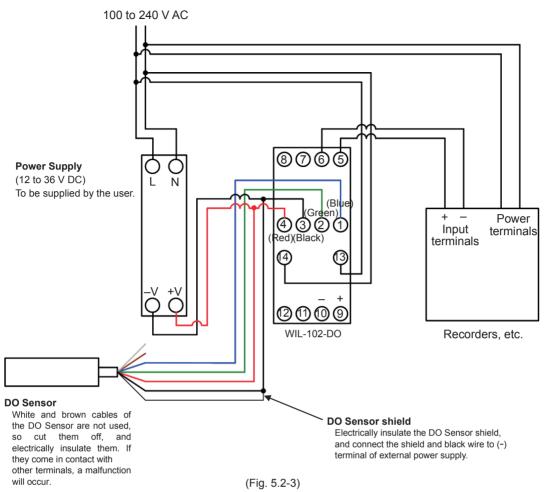
Modular Jack Pin (WIL-102-DO side arrangement)

	No. 1	COM
No. 6	No. 2	NC
No. 1 No. 6	No. 3	YB(+)
	No. 4	YA(-)
RS-485	No. 5	NC
	No. 6	COM

(Fig. 5.2-2)

Code	Description
DO RS-485 (sensor input)	DO Sensor YB(+) input terminal (Blue)
DO RS-485 (sensor input)	DO Sensor YA(-) input terminal (Green)
DO POWER FOR SENSOR	External power supply (-) terminal (Black) and DO Sensor shield
DO POWER FOR SENSOR	External power supply (+) terminal (Red)
TRANSMIT OUTPUT1	Transmission output 1
TRANSMIT OUTPUT2	Transmission output 2
EVT1	EVT1 output (Contact output 1)
EVT2	EVT2 output (Contact output 2)
EVT3	EVT3 output (Open collector output 3) (EVT option)
	Use the included wire harnesses WJ.
EVT4	EVT4 output (Open collector output 4) (EVT option)
	Use the included wire harnesses WJ.
EVT5	EVT5 output (Open collector output 5) (EVT option)
	Use the included wire harnesses WJ.
EVT6	EVT6 output (Open collector output 6) (EVT option)
	Use the included wire harnesses WJ.
POWER SUPPLY	Power supply voltage 100 to 240 V AC or 24 V AC/DC (when "1" is added after the model name "DO")
	24 V DC: Ensure polarity is correct.
RS-485	Serial Communication modular jack

Wiring Example

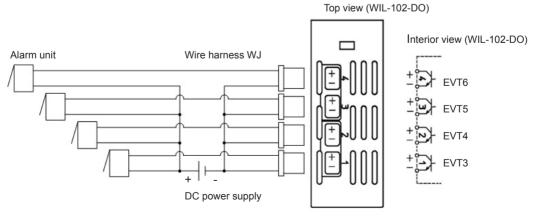


Wiring Example of EVT3 to EVT6

If EVT output (EVT option) is ordered, EVT3 to EVT6 output connectors are equipped on the top of this instrument. Use the included wire harnesses WJ.

Output specifications are shown below.

Open collector control capacity: 0.1 A 24 V DC

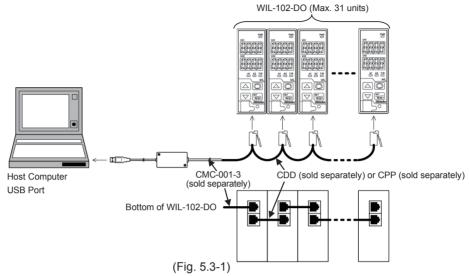


(Fig. 5.2-4)

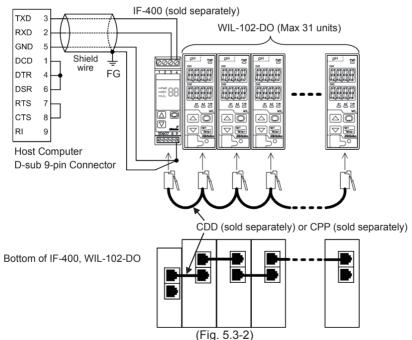
5.3 Wire the Communication Cable

Connect to the modular jack at the bottom of the instrument, using CDD (sold separately) or CPP (sold separately).

• Wiring Example Using the USB Communication Cable CMC-001-3 (sold separately)



• Wiring Example Using the Communication Converter IF-400 (sold separately)



Shield Wire

Be sure to ground only one end of the shield wire so that current cannot flow to the shield wire. If both ends of the shield wire are grounded, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (Use a twisted pair cable.)

Terminator (Terminal Resistor)

The terminator is mounted at the end of the wire when connecting multiple peripheral devices to a personal computer. The terminator prevents signal reflection and disturbance.

Do not connect a terminator with the communication line because each WIL-102-DO has built-in pull-up and pull-down resistors.

Communication converter IF-400 (sold separately) has a built-in terminal resistor.

6. Outline of Key Operation and Setting Groups

6.1 Outline of Key Operation

Setting items are divided into groups, and group selection has to be made with keypads. Press the key in Display Mode or Cleansing Output Mode. The unit enters Group Selection Mode. Select a group with the key, and press the key. The unit enters each setting item. To set each setting item, use the or key, and register the set value with the key. If the key is held down for 3 seconds at any setting item, the unit will revert to Display Mode or Cleansing Output Mode.

6.2 Setting Groups

Setting groups are indicated on p.21.

[About setting items]

Setting group or setting item in shaded section will be displayed only when the corresponding option is ordered.

- (*1) In Cleansing Output Mode, the measured value (DO concentration, DO % saturation, Oxygen partial pressure, Temperature) will be held during cleansing action (Cleansing time, Standby after cleansing).
- (*2) If errors occur during 1st-point calibration (100% saturation calibration) while in 2-point calibration mode, press the or Key Key. The unit will revert to Display Mode or Cleansing Output Mode.
- (*3) Depending on the selection in [Data clear Stop/Perform], the unit operates as follows.
 - If 'Data clear Stop' is selected, data will not be cleared. The unit will revert to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode).
 - If 'Data clear Perform' is selected, data will be cleared. The unit will revert to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode). (While data is being cleared, all indications are momentarily unlit.)

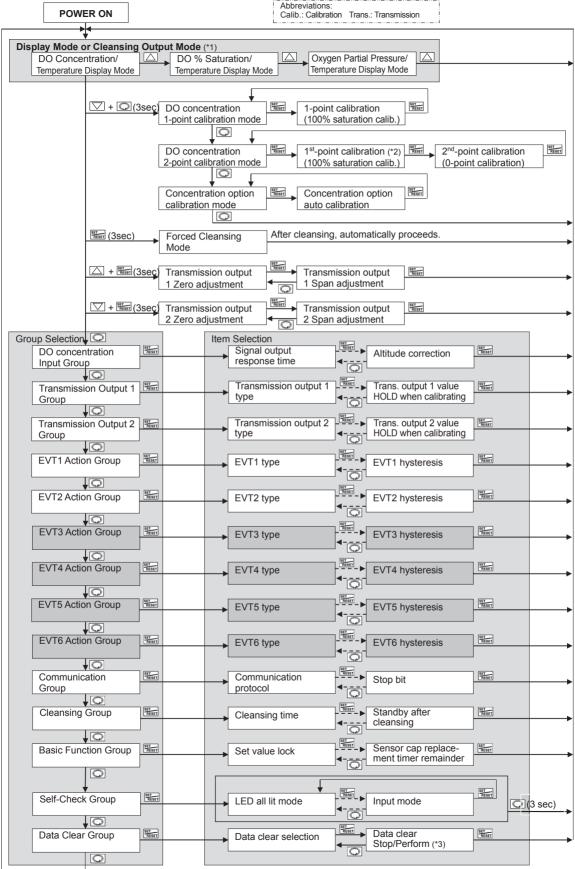
About Key Operation

• \square , \square , \blacksquare : Press the \square , \square or \blacksquare key. The unit will proceed to the next setting item,

illustrated by an arrow.

 $\textcircled{\ }$ or $\textcircled{\ }$: Press the $\textcircled{\ }$ or $\textcircled{\ }$ key until the desired setting mode appears.

- 🚟 (3 sec), 🔘 (3 sec): Press the 🚟 key or 🔘 key for approx. 3 seconds. The unit will proceed to the next setting mode, illustrated by an arrow.
- 🛆 + 🚟 (3 sec): Press and hold the 🛆 key and 🚟 key (in that order) together for approx. 3 seconds. The unit will proceed to Transmission output 1 Zero adjustment.
- 🔽 + 🚟 (3 sec): Press and hold the 🖾 key and 🚟 key (in that order) together for approx. 3 seconds. The unit will proceed to Transmission output 2 Zero adjustment.



7. Setup

Setup should be done before using this instrument according to the user's conditions:

Setting the DO concentration input, Transmission output 1, Transmission output 2, EVT1, EVT2, EVT3 to EVT6 (EVT option) types, Communication, Cleansing and Indication settings, etc.

Setup can be conducted in the groups below:

DO Concentration Input Group, Transmission Output 1 Group, Transmission Output 2 Group,

EVT1 to EVT6 Action Groups, Communication Group, Cleansing Group, Basic Function Group If the user's specification is the same as the factory default value of the WIL-102-DO, or if setup has already been completed, it is not necessary to set up the instrument. Proceed to "8. Calibration (p.41)".

7.1 Turn the Power Supply to the WIL-102-DO ON.

For approx. 8 seconds after the power is switched ON, the following characters are indicated on the DO Display and Temperature Display.

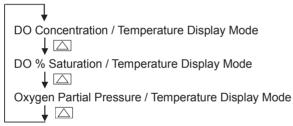
Display	Indication	
DO Display	do	
Temperature Display	□ <i>に口</i> [Version number (e.g.) 1.00]	

During this time, all outputs are in OFF status, and action indicators except the PWR indicator turn off. After that, measurement starts, indicating DO concentration, DO % saturation or Oxygen partial pressure on the DO Display, and temperature on the Temperature Display.

This status is called Display Mode or Cleansing Output Mode.

Switching Between Modes

Every time the 🖾 key is pressed, modes (on the DO Display) progress as follows.



7.2 DO Concentration Input Group

To enter the DO Concentration Input Group, follow the procedure below.

- ① Fric Press the 🔘 key once in Display Mode or Cleansing Output Mode.
- 2 dFcf Press the **E** key.

The unit enters the DO Concentration Input Group, and "Signal output response time" will appear.

Character	Setting Item, Function, Setting Range	Factory Default	
dFcF	Signal output response time	60 seconds	
50	 Sets the signal output response time. 		
	Moving average is calculated from the set signal o	output response time, and the	
	resulting value is updated every Data update cycle	e (fixed at 5 seconds) as a	
	measurement value.		
	Moving average = Signal output response time	÷ Data update cycle (5 sec.)	
	(e.g.) If signal output response time is set to 50 seconds, the Moving average will be:		
	50/5 = 10 (times)		
	However, signal output response time setting will be invalidated during DO		
	concentration calibration mode, Transmission output 1 adjustment mode, or		
	Transmission output 2 adjustment mode.		
	Setting range: 5 to 600 seconds		
58L/	Salinity correction	0 PSU	
	• Sets the salinity concentration correction value.		
	Setting range: 0 to 42 PSU		
4EAL	Altitude correction	0 m	
	Sets altitude.		
	Setting range: 0 to 5000 m		

7.3 Transmission Output 1 Group

To enter the Transmission Output 1 Group, follow the procedure below.

- (1) F.r.a. / Press the 🔘 key twice in Display Mode or Cleansing Output Mode.
- ② / ┌ ┍ / Press the Key.

The unit enters Transmission Output 1 Group, and "Transmission output 1 type" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
Fra I	Transmission output 1 type	DO concentration transmission
do	Selects Transmission output 1 type.	
	・ ゴロ : DO concentration transmission	
	デラ戸: Water temperature transmission	
	<i>古</i> ューデ : DO % saturation transmission	
	<i>ふP</i> ート: Oxygen partial pressure transmission	
Ггни	Transmission output 1 high limit	20.00 mg/L
2000	Sets Transmission output 1 high limit value. (This value)	value correponds to 20 mA DC
	output.)	
	If Transmission output 1 high limit and low limit a	are set to the same value,
	Transmission output 1 will be fixed at 4 mA DC.	
_	Setting range: Transmission output 1 low limit to	Measurement range high limit
	Transmission output 1 low limit	0.00 mg/L
000	Sets Transmission output 1 low limit value. (This value)	alue correponds to 4 mA DC
	output.)	
	If Transmission output 1 high limit and low limit are set to the same value,	
	Transmission output 1 will be fixed at 4 mA DC.	
	Setting range: Measurement range low limit to Tra	
Fre I	Transmission output 1 status when calibrating	Last value HOLD
6EFH	Selects Transmission output 1 output status when calibrating DO concentration.	
	• Selection item: $b \mathcal{E} \mathcal{F} \mathcal{H}$: Last value HOLD (Retains the last value before calibrating DO concentration,	
	and outputs it.)	
	$\neg E\Gamma H$: Set value HOLD (Outputs the value set in [Transmission output 1 value HOLD	
	when calibrating].)	
	PBH Measured value (Outputs the measured value when calibrating DO	
1 - 1 1	concentration.)	
	Transmission output 1 value HOLD when calibrating	0.00 mg/L
	Sets Transmission output 1 value HOLD.	
	• Available only when $\neg \mathcal{E}\mathcal{F}\mathcal{H}$ (Set value HOLD) i	is selected in [Transmission output 1
	status when calibrating].	
	Setting range: Measurement range low limit to Measurement range high limit	

7.4 Transmission Output 2 Group

To enter the Transmission Output 2 Group, follow the procedure below.

- ② 「┌ ♫ ⊑' Press the ^{str} key.

The unit enters Transmission Output 2 Group, and "Transmission output 2 type" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
Fro2	Transmission output 2 type	DO concentration transmission
do	Selects Transmission output 2 type.	
	・ ゴロ : DO concentration transmission	
	<u> 「</u> 「 戸 F : Water temperature transmission	
	<i>do</i> ㄣ厂:DO % saturation transmission	
	ごピート : Oxygen partial pressure transmission	
F-H2	Transmission output 2 high limit	20.00 mg/L
2000	Sets Transmission output 2 high limit value. (This value)	value correponds to 20 mA DC
	output.)	
	If Transmission output 2 high limit and low limit a	are set to the same value,
	Transmission output 2 will be fixed at 4 mA DC.	
	Setting range: Transmission output 2 low limit to	Measurement range high limit
<u>[-12</u>	Transmission output 2 low limit	0.00 mg/L
000	Sets Transmission output 2 low limit value. (This value)	alue correponds to 4 mA DC
	output.)	
	If Transmission output 2 high limit and low limit are set to the same value,	
	Transmission output 2 will be fixed at 4 mA DC.	
	Setting range: Measurement range low limit to Tra	
line2	Transmission output 2 status when calibrating	Last value HOLD
68FH	Selects Transmission output 2 output status when calibrating DO concentration.	
	Selection item: bEFH: Last value HOLD (Retains the last value	$rac{1}{2}$
	and outputs it.)	before calibrating DO concentration,
	$\neg \mathcal{E} \Gamma \mathcal{H}$: Set value HOLD (Outputs the value set in [Transmission output 2 value HOLD)	
	when calibrating].)	
	PBH Measured value (Outputs the measured value when calibrating DO	
	concentration.)	
ſ - ≒2 _000	Transmission output 2 value HOLD when calibrating	0.00 mg/L
	Sets Transmission output 2 value HOLD.	<u> </u>
	• Available only when $\neg E\Gamma H$ (Set value HOLD) i	is selected in ITransmission output 2
	status when calibrating].	
	Setting range: Measurement range low limit to Measurement range high limit	

7.5 EVT1 Action Group

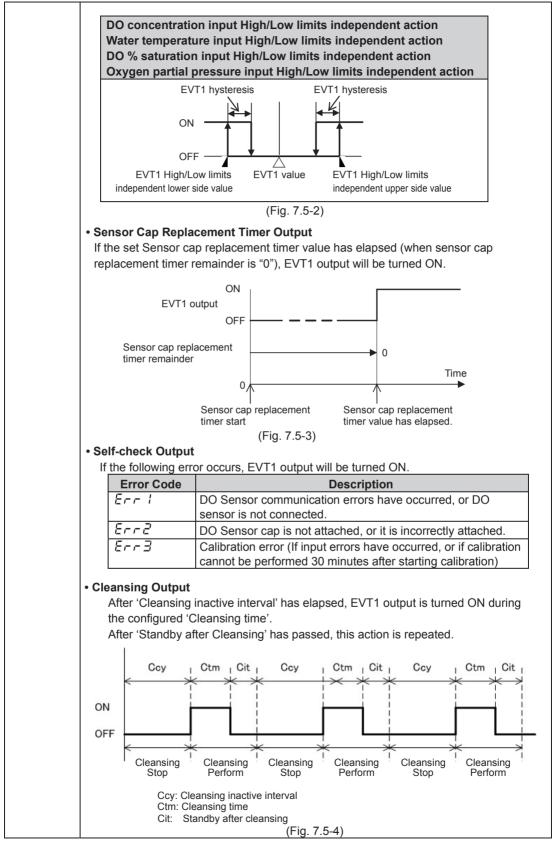
To enter the EVT1 Action Group, follow the procedure below.

① *E.H.* Press the 🔘 key 4 times in Display Mode or Cleansing Output Mode.

② *EΓF I* Press the [™] key.

The unit proceeds to the EVT1 Action Group, and "EVT1 type" will appear.

Character	The unit proceeds to the EVT1 Action Group, a Setting Item, Function, Setting Range		
	EVT1 type	No action	
	• Selects an EVT1 output type.		
·	Note: If EVT1 type is changed, EVT1 value	e defaults to 0.00 or 0.0.	
	• =====: No action		
	da_H : DO concentration input high limit action		
	d = -L: DO concentration input low limit ac		
	$\bar{\omega}^{-}\bar{\sigma}H$: Water temperature input high limit		
	ゴー 市上: Water temperature input low limit a		
	da - H: DO % saturation input high limit action		
	$d = -\frac{1}{2}$: DO % saturation input low limit action		
	$\bar{\omega}PrH$: Oxygen partial pressure input high limit action		
	$\bar{\omega}P - L$: Oxygen partial pressure input low	limit action ノ	
	$\Gamma \subset \mathcal{RP}$: Sensor cap replacement timer (Fig	g. 7.5-3) (p.27)	
	らどう : Self-Check output (p.27)		
	cLEG: Cleansing output (Fig. 7.5-4) (p.27		
	ゴロビン : DO concentration input High/Low I		
	「「「HL」: Water temperature input High/Low		
	ゴービー: DO % saturation input High/Low lin		
	レデガム: Oxygen partial pressure input High/L	ow limits independent action (Fig.7.5-2) (p.27)	
	• EVT1 Action (Activated based on the ind	ication value.)	
	DO concentration input high limit	DO concentration input low limit	
	Water temperature input high limit	Water temperature input low limit	
	DO % saturation input high limit DO % saturation input low limit		
	Oxygen partial pressure input high limit	Oxygen partial pressure input low limit	
	If Medium Value is selected in [EVT1 hysteresis	If Medium Value is selected in [EVT1 hysteresis	
	type]: EVT1 ON sides	type]: EVT1 ON sides	
	ON		
		Î Î Î Î	
	EVT1 value	EVT1 value	
	If Reference Value is selected in [EVT1	If Reference Value is selected in [EVT1	
	hysteresis type]:	hysteresis type]:	
	J	nysteresis type].	
	EVT1 OFF side* EVT1 ON side*	EVT1 ON side* EVT1 OFF side*	
	EVT1 OFF side* EVT1 ON side*	EVT1 ON side* EVT1 OFF side*	
	EVT1 OFF side* EVT1 ON side*	EVT1 ON side* EVT1 OFF side*	
	EVT1 OFF side* EVT1 ON side*	EVT1 ON side* EVT1 OFF side*	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value	ON OFF	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value (Fig. 7	ON OFF	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value (Fig. 7 * Setting Example:	ON OFF EVT1 ON side* EVT1 OFF side* OFF EVT1 value 7.5-1)	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value (Fig. 7 * Setting Example: If [EVT1 ON side ($d \not \vdash \Box$ /)] is set to 0, 1	EVT1 ON side* EVT1 OFF side* ON OFF EVT1 value 7.5-1) EVT1 output can be turned ON	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value (Fig. 7 * Setting Example: If [EVT1 ON side ($\Box F \Box I$)] is set to 0, 1 at the value set in [EVT1 value ($\neg B I$)	EVT1 ON side* EVT1 OFF side* ON OFF EVT1 value C.5-1) EVT1 output can be turned ON EVT1 output can be turned ON	
	EVT1 OFF side* EVT1 ON side* ON EVT1 value (Fig. 7 * Setting Example: If [EVT1 ON side ($d \not \vdash \Box$ /)] is set to 0, 1	EVT1 ON side* EVT1 OFF side* ON OFF EVT1 value 7.5-1) EVT1 output can be turned ON EVT1 output can be turned OFF	



Character	Setting Item, Function, Setting Range	Factory Default
58 /C	EVT1 value	DO concentration input: 0.00 mg/L
000		Water temperature input: 0.0°C
		DO % saturation input: 0.0%
		Oxygen partial pressure input: 0.0 kPa
	 Sets EVT1 value. Not available for this setting item and all subsequences. 	unt itoma if
	$\Gamma \subseteq RP$ (Sensor cap replacement timer), $\neg ELF$	
	(Cleansing output) is selected in [EVT1 type].	
	Setting range:	
	DO concentration input: 0.00 to 20.00 mg/L	
	Water temperature input: 0.0 to 50.0°C	
	DO % saturation input: 0.0 to 200.0%	
	Oxygen partial pressure input: 0.0 to 150.0 kPa	
81 F 1	EVT1 hysteresis type	Reference Value
Sdl F	• Selects EVT1 output hysteresis type (Medium or	
	• Not available if $d \Box H_{L}^{L}$ (DO concentration input H	
	「	
	input High/Low limits independent action) is select	
	• $\Box \Box I F$: Medium Value	
	Sets the same value for both ON and O	FF sides in relation to EVT1 value.
	Only ON side needs to be set.	
	הב <i>ו F</i> : Reference Value	
	Sets individual values for ON and OFF	
15 1	Both ON and OFF sides need to be set	DO concentration input: 0.01 mg/L
dFo l	EVT1 ON side	Water temperature input: 1.0°C
0.0 I		DO % saturation input: 0.1%
		Oxygen partial pressure input: 0.1 kPa
	Sets the span of EVT1 ON side.	
	If	ysteresis type], the span of ON/OFF
	side will be the same value.	
	・Not available if <i>ゴロドL</i> (DO concentration input F <i>こうドL</i> (Water temperature input High/Low limits	
	saturation input High/Low limits independent activ	
	input High/Low limits independent action) is select	
	Setting range:	
	DO concentration input: 0.00 to 4.00 mg/L	
	Water temperature input: 0.0 to 10.0°C	
	DO % saturation input: 0.0 to 40.0%	
	Oxygen partial pressure input: 0.0 to 30.0 kPa	
러두십 /	EVT1 OFF side	DO concentration input: 0.01 mg/L Water temperature input: 1.0℃
<i>□00 (</i>		DO % saturation input: 0.1%
		Oxygen partial pressure input: 0.1 kPa
	Sets the span of EVT1 OFF side.	yor proceeding and the second s
	• Not available if	ted in [EVT1 hysteresis type].
	Setting range:	
	DO concentration input: 0.00 to 4.00 mg/L	
	Water temperature input: 0.0 to 10.0°C	
	DO % saturation input: 0.0 to 40.0%	
1	Oxygen partial pressure input: 0.0 to 30.0 kPa	

Character	Setting Item, Function, Setting Range	Factory Default
onf l	EVT1 ON delay time	0 seconds
	 Sets EVT1 ON delay time. 	
	The EVT1 output does not turn ON (under the co	nditions of turning ON) until the time
	set in [EVT1 ON delay time] elapses.	
	Setting range: 0 to 9999 seconds	
off	EVT1 OFF delay time	0 seconds
<i>0</i>	• Sets EVT1 OFF delay time.	
	The EVT1 output does not turn OFF (under the c set in [EVT1 OFF delay time] elapses.	onditions of turning OFF) until the time
	Setting range: 0 to 9999 seconds	
oon l	Output ON time when EVT1 output ON	0 seconds
	• Sets Output ON time when EVT1 output is ON.	0.0000140
·	If ON time and OFF time are set, EVT1 output ca	an be turned ON/OFF in a configured
	cycle when EVT1 output is turned ON. (Fig. 7.5-5	-
	Setting range: 0 to 9999 seconds	
00F	Output OFF time when EVT1 output ON	0 seconds
	Sets Output OFF time when EVT1 output is ON.	
	If ON time and OFF time are set, EVT1 output ca	in be turned ON/OFF in a configured
	cycle when EVT1 output is turned ON. (Fig. 7.5-5)	
	Setting range: 0 to 9999 seconds	
	 Timing chart (Output ON time and OFF time v 	vhen EVT1 output is ON)
	ON	
	Actual EVT1 output	
	OFF	ON time is turned
		OFF, caused by the
	EVT1 output to	actual EVT1 output
	Which ON time and OFF OFF	turning OFF.
	OFF time are set.	
	time time tim	
	(Fig. 7.5-5)	
E_L /	EVT1 High/Low limits independent	DO concentration input: 0.00 mg/L
<u>aoo</u>	lower side value	Water temperature input: 0.0°C
		DO % saturation input: 0.0%
		Oxygen partial pressure input: 0.0 kPa
	Sets the lower side value of EVT1 High/Low limits independent action.	
	• Available when daH'_{L} (DO concentration input High/Low limits independent action),	
	$\int \vec{\sigma} H L$ (Water temperature input High/Low limits independent action), $\vec{\sigma} H L$ (DO %	
	saturation input High/Low limits independent action) or $\vec{\omega}PHL$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT1 type].	
	Setting range:	
	DO concentration input: 0.00 to 20.00 mg/L	
	Water temperature input: 0.0 to 50.0°C	
	DO % saturation input: 0.0 to 200.0%	
	Oxygen partial pressure input: 0.0 to 150.0 kPa	

Character	Setting Item, Function, Setting Range	Factory Default	
E_H I	EVT1 High/Low limits independent	DO concentration input: 0.00 mg/L	
0.00	upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	 Sets the upper side value of EVT1 High/Low lin 	ne upper side value of EVT1 High/Low limits independent action.	
	Setting range:		
	DO concentration input: 0.00 to 20.00 mg/L	concentration input: 0.00 to 20.00 mg/L	
	Water temperature input: 0.0 to 50.0℃		
	DO % saturation input: 0.0 to 200.0%		
	Oxygen partial pressure input: 0.0 to 150.0 kPa		
EHYI	EVT1 hysteresis	DO concentration input: 0.01 mg/L	
<i>00 +</i>		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	 Sets hysteresis of EVT1 High/Low limits independent action. 		
	Setting range:		
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0℃		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: 0.1 to 15.0 kPa		

7.6 EVT2 Action Group

To enter EVT2 Action Group, follow the procedure below.

① $\mathcal{E}\mathcal{L}\mathcal{I}\mathcal{P}$ Press the \square key 5 times in Display Mode or Cleansing Output Mode.

(2) EFFZ Press the **EFF** key.

The unit proceeds to EVT2 Action Group, and "EVT2 type" appears.

Action, indication condition and setting range of EVT2 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT2 (\downarrow with \overline{c}), and refer to EVT1 Action Group (pp. 26 to 30). (e.g.) $\overline{c} \Gamma \overline{c} \downarrow \rightarrow \overline{c} \Gamma \overline{c} \overline{c}$

58 /□ → 582□

7.7 EVT3 Action Group

Available when EVT output (EVT option) is ordered.

To enter EVT3 Action Group, follow the procedure below.

① $\pounds B \cap B$ Press the \square key 6 times in Display Mode or Cleansing Output Mode.

2 EFFB Press the \mathbb{E} key.

The unit proceeds to EVT3 Action Group, and "EVT3 type" appears.

Action, indication condition and setting range of EVT3 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT3 (\downarrow with \exists), and refer to EVT1 Action Group (pp. 26 to 30). (e.g.) $\xi \Gamma \xi \downarrow \rightarrow \xi \Gamma \xi \exists$

7.8 EVT4 Action Group

Available when EVT $\Box\,$ output (EVT option) is ordered.

To enter EVT4 Action Group, follow the procedure below.

- ② EFFY Press the [™]EFFF key.

The unit proceeds to EVT4 Action Group, and "EVT4 type" appears.

Action, indication condition and setting range of EVT4 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT4 (i with 4), and refer to EVT1 Action Group (pp. 26 to 30). (e.g.) $E\Gamma F i \rightarrow E\Gamma F 4$

7.9 EVT5 Action Group

Available when EVT \Box output (EVT option) is ordered.

To enter the EVT5 Action Group, follow the procedure below.

- ① $\mathcal{E}\mathcal{H}\mathcal{I}\mathcal{S}$ Press the \square key 8 times in Display Mode or Cleansing Output Mode.
- ② EFF5 Press the [™]EFFF key.

The unit proceeds to EVT5 Action Group, and "EVT5 type" appears.

Action, indication condition and setting range of EVT5 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT5 (\ddagger with 5), and refer to EVT1 Action Group (pp. 26 to 30). (e.g.) $\xi \Gamma F \downarrow \rightarrow \xi \Gamma F 5$

५४ /□ → ५४५□

7.10 EVT6 Action Group

Available when EVT output (EVT option) is ordered.

To enter the EVT6 Action Group, follow the procedure below.

 ① £.出「.A Press the ^① key 9 times in Display Mode or Cleansing Output Mode.

 ② £「.F.5 Press the ¹ key.

The unit proceeds to EVT6 Action Group, and "EVT6 type" appears.

Action, indication condition and setting range of EVT6 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT6 (\downarrow with \pounds), and refer to EVT1 Action Group (pp. 26 to 30). (e.g.) $\pounds \Gamma F \downarrow \longrightarrow \xi \Gamma F \pounds$

์ ५४ /: → ५४६ 🗌

7.11 Communication Group

To enter the Communication Group, follow the procedure below.

6746	Communication protocol	Shinko protocol
noñL	Selects the communication protocol.	
	・ ヮヮヮ゙よ : Shinko protocol	
	ក្នុ <i>ធដ</i> អ៊ី : MODBUS ASCII mode	
	nadr : MODBUS RTU mode	
cñno	Instrument number	0
	• Sets the instrument number. (The instrument numbers should be set one by one when	
	multiple instruments are connected.)	
	Setting range: 0 to 95	
c.54P	Communication speed	9600 bps
<u> </u>	• Selects a communication speed equal to that of the host computer.	
	•	
	[] 192 : 19200 bps	
	384 : 38400 bps	7 1:4-75
c AFF	Data bit/Parity	7 bits/Even
7687	• Selects data bit and parity.	
	• 8 pon : 8 bits/No parity	
	Toon: 7 bits/No parity	
	8EBn : 8 bits/Even	
	$\frac{7EBn}{d}$: 7 bits/Even	
	Badd : 8 bits/Odd	
	ੀਰਰਰ : 7 bits/Odd	1.4.4.4
ะกัรก	Stop bit	1 bit
	Selects the stop bit.	
	• : 1 bit	
	$\Box \Box d$: 2 bits	

7.12 Cleansing Group

To enter the Cleansing Group, follow the procedure below.

- ① c.L.E.L Press the D key 7 times in Display Mode or Cleansing Output Mode. If EVT output (EVT option) is ordered, press the D key 11 times in Display Mode or Cleansing Output Mode.
- 2 cLTA Press the Key.
 - The unit enters the Cleansing Group, and "Cleansing time" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
elfā	Cleansing time	30 seconds
<u> </u>	Sets the time to perform cleansing. (Fig. 7.12-1)	
	Setting range: 10 to 120 seconds	
cLcY	Cleansing inactive interval	OFF (None)
oFF	Sets the cleansing inactive interval. (Fig. 7.12-1)	
	Setting range:	
	□FF (None), 10 to 240 minutes	
ELIF	Standby after cleansing	0 seconds
	Sets standby time after cleansing action. (Fig. 7.12-1)	
	Setting range: 0 to 60 seconds	

Cleansing Function

The selected EVT output is turned ON during 'cleansing time' after 'Cleansing inactive interval' has elapsed.

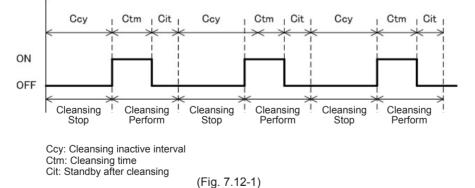
After 'Standby after cleansing' has passed, the above action is repeated.

While cleansing action is performing using 'Cleansing time' and 'Standby after cleansing', other outputs are in OFF status.

Measured value (DO concentration, DO % saturation, Oxygen partial pressure, Water temperature) will be retained.

Normal programmed action will be performed, except during Cleansing Perform action. If the power is turned on again, starts from 'Cleansing inactive interval'.

Cleansing Output Action



• If cLEL (Cleansing output) is selected in any other [EVT type] during cleansing action, the current setting values (Cleansing time, Standby after cleansing, Cleansing inactive interval) will be used for the selected cleansing output.

If cleansing action (caused by cleansing cycle) is activated in calibration mode, cleansing action will not be performed in the current session.

• If $\Box FF \square$ (None) is selected in [Cleansing inactive interval], or if any item except $\Box LE \square$ (Cleansing output) is selected in [EVT type], Cleansing Output Mode will end, and the unit will revert to Display Mode.

7.13 Basic Function Group

To enter the Basic Function Group, follow the procedure below.

- ① c.f.E.r Press the Q key 8 times in Display Mode or Cleansing Output Mode. If EVT□ output (EVT option) is ordered, press the Q key 12 times in Display Mode or Cleansing Output Mode.
- ② Loc≿ Press the [™] key.

The unit enters the Basic Function Group, and the "Set value lock" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
Lock	Set value lock	Unlock
	 Locks the set values to prevent setting errors. Image: I (Unlock): All set values can be changed. Loc I (Lock 1): None of the set values can be changed. Loc Z (Lock 2): Only EVT1 to EVT6 values can be changed. Loc Z (Lock 3): All set values can be temporarily changed. However, they revert to their previous off because they are not saved in the Do not change setting items (EVT1, EV types). If they are changed, they will a Be sure to select Lock 3 when changing software communication. (If a value set the same as the value before the setting in non-volatile IC memory.) 	hanged. nged. value after the power is turned non-volatile IC memory. (T2, EVT3, EVT4, EVT5, EVT6 ffect other setting items. ng the set value frequently via et via software communication is
LI 60	Auto-light function	Disabled
	 Selects Auto-light Enabled/Disabled. Elects Auto-light Enabled Uっと Enabled 	Diodolog
FI AE	Indication time	00.00 (Remains lit)
0000	 Sets the indication time of the displays after the last key operation until displays turn off while in Display Mode or Cleansing Output Mode. Displays remain lit when set to 00.00. Displays light up when any key is pressed while in unlit status. Setting range: 00.00 (Remains lit.) 00.01 to 60.00 (Minutes.Seconds) 	
1 Err	EVT output when input errors occur	Disabled
0FF[]	• If input errors occur, EVT output can be Enabled or Disabled. If "Enabled" is selected, EVT output will be maintained when input errors occur. If "Disabled" is selected, EVT output will be turned OFF when input errors occur. • Available when the following type is selected in [EVT type]: daH (DO concentration input high limit action) daL (DO concentration input low limit action) arrah (Water temperature input high limit action) arrah (Water temperature input low limit action) arrah (DO % saturation input high limit action) da_+H (DO % saturation input high limit action) arrah (DO % saturation input high limit action) arrah (DO % saturation input high limit action) arrah (Oxygen partial pressure input high limit action) arrah (Oxygen partial pressure input high limit action) arrah (Oxygen partial pressure input high limit action) arrah (DX is the following the following the limit action) arrah (DX is the following the limit actio	
5 <i>8 I</i>	EVT1 value	365 days
036S	 Sets EVT1 value (Sensor cap replacement timer). Available when 「こ用戸 (Sensor cap replacement timer) Setting range: 0 to 1095 days 	r) is selected in [EVT1 type].

Character	Setting Item, Function, Setting Range	Factory Default		
onf l	EVT1 ON delay time	0 seconds		
	Sets EVT1 ON delay time.			
	The EVT1 output does not turn ON after the input value exceeds the EVT1 (Sensor			
		cap replacement timer) value until the time set in [EVT1 ON delay time] elapses.		
	• Available when $\int c RP$ (Sensor cap replacement timer) is selected in [EVT1 type].			
	Setting range: 0 to 9999 seconds			
off (EVT1 OFF delay time	0 seconds		
	Sets EVT1 OFF delay time.			
	The EVT1 output does not turn OFF after the input value	-		
	cap replacement timer) value until the time set in [EVT1 C			
	• Available when $\int c RP$ (Sensor cap replacement timer)	is selected in [EVI1 type].		
	Setting range: 0 to 9999 seconds	005.1		
5820 Saco	EVT2 value	365 days		
0365	• Sets EVT2 value (Sensor cap replacement timer).			
	Available when $\int c RP$ (Sensor cap replacement timer)	is selected in [EV12 type].		
	Setting range: 0 to 1095 days			
on[2	EVT2 ON delay time	0 seconds		
	Sets EVT2 ON delay time.			
	The EVT2 output does not turn ON after the input value exceeds the EVT2 (Sensor			
	cap replacement timer) value until the time set in [EVT2 ON delay time] elapses.			
	• Available when $\int c RP$ (Sensor cap replacement timer)	is selected in [EV12 type].		
	Setting range: 0 to 9999 seconds			
oF/2	EVT2 OFF delay time	0 seconds		
<i>D</i>	Sets EVT2 OFF delay time.			
	The EVT2 output does not turn OFF after the input value	-		
	cap replacement timer) value until the time set in [EVT2 OFF delay time] elapses.			
	• Available when $\Gamma \subset \mathcal{PP}$ (Sensor cap replacement timer)	is selected in [EVI2 type].		
	Setting range: 0 to 9999 seconds	265 dava		
	EVT3 value	365 days		
365	• Sets EVT3 value (Sensor cap replacement timer).			
	• Available when EVT output (EVT option) is ordered.	is calested in [E]/T2 type]		
	Available when $\Gamma \subset \mathbb{RP}$ (Sensor cap replacement timer) • Setting range: 0 to 1095 days	is selected in [EV13 type].		
on[]	EVT3 ON delay time	0 accordo		
		0 seconds		
ii <i>i</i> /_/	• Sets EVT3 ON delay time.			
	The EVT3 output does not turn ON after the input value exceeds the EVT3 (Sensor			
	cap replacement timer) value until the time set in [EVT3 ON delay time] elapses.			
	• Available when EVT□ output (EVT option) is ordered. Available when 「ニ界P (Sensor cap replacement timer) is selected in [EVT3 type].			
	Setting range: 0 to 9999 seconds			
oF[3	EVT3 OFF delay time	0 seconds		
	Sets EVT3 OFF delay time.	0 00001140		
·	The EVT3 output does not turn OFF after the input value	exceeds the EVT3 (Sensor		
	cap replacement timer) value until the time set in [EVT3 OFF delay time] elapses.			
	• Available when EVT output (EVT option) is ordered.			
	Available when $\Gamma \subset \mathcal{RP}$ (Sensor cap replacement timer)	is selected in [EVT3 type]		
	• Setting range: 0 to 9999 seconds			

Character	Setting Item, Function, Setting Range	Factory Default	
5 <i>84</i>	EVT4 value	365 days	
<i>⊡3</i> 65	Sets EVT4 value (Sensor cap replacement timer).		
	• Available when EVT output (EVT option) is ordered.		
	Available when $\int c RP$ (Sensor cap replacement timer) is selected in [EVT4 type].		
	Setting range: 0 to 1095 days		
onf4	EVT4 ON delay time	0 seconds	
	Sets EVT4 ON delay time.		
	The EVT4 output does not turn ON after the input value exceeds the EVT4 (Sensor		
	cap replacement timer) value until the time set in [EVT4	ON delay time] elapses.	
	• Available when EVT output (EVT option) is ordered.		
	Available when $\Gamma \subset \mathcal{RP}$ (Sensor cap replacement timer) is selected in [EVT4 type].	
	Setting range: 0 to 9999 seconds		
оЕГЧ	EVT4 OFF delay time	0 seconds	
	Sets EVT4 OFF delay time.		
	The EVT4 output does not turn OFF after the input value		
	cap replacement timer) value until the time set in [EVT4 OFF delay time] elapses.		
	• Available when EVT output (EVT option) is ordered.		
	Available when $\Gamma \subseteq RP$ (Sensor cap replacement timer) is selected in [EVT4 type].	
	Setting range: 0 to 9999 seconds		
585 <u></u>	EVT5 value	365 days	
365	• Sets EVT5 value (Sensor cap replacement timer).		
	• Available when EVT \Box output (EVT option) is ordered.		
	Available when $\int c RP$ (Sensor cap replacement time)) is selected in [EV15 type].	
	Setting range: 0 to 1095 days		
on[5	EVT5 ON delay time	0 seconds	
	• Sets EVT5 ON delay time.	evenede the FV/TE (Concer	
	The EVT5 output does not turn ON after the input value	•	
	 cap replacement timer) value until the time set in [EVT5 ON delay time] elapses. Available when EVT output (EVT option) is ordered. 		
	Available when $\Gamma \subseteq RP$ (Sensor cap replacement timer) is selected in $[E]/T5$ type]	
	Setting range: 0 to 9999 seconds) is selected in [E v 13 type].	
oF/5	EVT5 OFF delay time	0 seconds	
	Sets EVT5 OFF delay time.	0.3000103	
······································	The EVT5 output does not turn OFF after the input value	exceeds the EVT5 (Sensor	
	cap replacement timer) value until the time set in [EVT5 OFF delay time] elapses.		
	• Available when EVT output (EVT option) is ordered.		
	Available when $\Gamma \subseteq \mathcal{RP}$ (Sensor cap replacement timer) is selected in [EVT5 type].		
	Setting range: 0 to 9999 seconds		

Character	Setting Item, Function, Setting Range	Factory Default
5 <i>85</i>	EVT6 value	365 days
365	 Sets EVT6 value (Sensor cap replacement timer). 	
	• Available when EVT output (EVT option) is ordered.	
	Available when $\Gamma \subset \mathcal{RP}$ (Sensor cap replacement timer) is selected in [EVT6 type].
	Setting range: 0 to 1095 days	
onf6	EVT6 ON delay time	0 seconds
	Sets EVT6 ON delay time.	
	The EVT6 output does not turn ON after the input value	exceeds the EVT6 (Sensor
	cap replacement timer) value until the time set in [EVT6 ON delay time] elapses.	
	 Available when EVT□ output (EVT option) is ordered. 	
	Available when $\int c RP$ (Sensor cap replacement timer) is selected in [EVT6 type].	
	Setting range: 0 to 9999 seconds	
off6	EVT6 OFF delay time	0 seconds
	Sets EVT6 OFF delay time.	
	The EVT6 output does not turn OFF after the input value	e exceeds the EVT6 (Sensor
	cap replacement timer) value until the time set in [EVT6 OFF delay time] elapses.	
	• Available when EVT output (EVT option) is ordered.	
	Available when $\Gamma \subset BP$ (Sensor cap replacement timer) is selected in [EVT6 type].	
	Setting range: 0 to 9999 seconds	
rEFA	Sensor cap replacement timer remainder	365 days
<i>⊡3</i> 65	 Indicates the remaining time of the sensor cap replacement timer. 	
	 Setting range: 0 to 1095 days 	

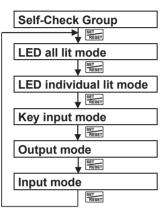
7.14 Self-Check Group

To enter the Self-Check Group, follow the procedure below.

- ② BBBB Press the self-Check Group, and "LED all lit mode" will appear.

Every time the key is pressed, modes progress as follows.

If the 🔘 key is held down for approx. 3 seconds in any setting mode, the unit will revert to the Display Mode or Cleansing Output Mode.



Following is a description of each mode.

Mode	Description		
LED all lit mode	All indicatio	ns light up.	
	All displays and action indicators light up.		
LED individual lit	Each segm	ent lights up	sequentially every 0.5 seconds, in a cycle, as shown
mode	below.		
	$1 \rightarrow 2 \rightarrow \cdots \rightarrow 11 \rightarrow 1$		
	Order		Contents
	1		'a' segment of DO Display, Temperature Display
	2	H	'b' segment of DO Display, Temperature Display
	3		'c' segment of DO Display, Temperature Display
	4	B	'd' segment of DO Display, Temperature Display
	5	8	'e' segment of DO Display, Temperature Display
	6	B	'f' segment of DO Display, Temperature Display
	7		'g' segment of DO Display, Temperature Display
	8	H	'dp' segment of DO Display, Temperature Display
	9	A1	A1 indicator
	10	A2	A2 indicator
	11	T/R	T/R indicator

Mode		Description
Key input mode	Characters allocated to e	
		s EE , and the Temperature Display indicates the
	following characters.	
	If 2 or more keys are pressed simultaneously, db will be indicated. Temperature Key leget	
	Display	Key Input
	nonE	When no key is pressed
	;_;;P	When the 🛆 key is pressed
	doūn	When the 🖾 key is pressed
	db	When 2 or more keys are pressed simultaneously
Output mode	Each EVT output is turne	ed ON.
	Transmission output 1 ar	
	The DO Display indicates	s $\Box \Box \Box \Box$, and the Temperature Display indicates the
	following characters.	
		s pressed, each output is turned ON sequentially after
	being checked.	
	Temperature	Output
	Display	-
	oFF[]	All EVT outputs OFF
		Transmission output 1 and 2: 4 mA DC
	EBL I	EVT1 output ON
	<u> </u>	EVT2 output ON
	ЕНГЭ	EVT3 output ON
	ЕНГЧ	EVT4 output ON
	E8/5	EVT5 output ON
	<u> </u>	EVT6 output ON
	<u> </u>	Transmission output 1: 20 mA DC
	Frad	Transmission output 2: 20 mA DC
Input mode	Indicates each input.	
		s pressed, input checking is performed, and the DO
		oonding input characters, and the Temperature Display
	indicates corresponding measured value.	
	DO Display	Temperature Display
		DO concentration measured value
	JE AP	Water temperature measured value
	ゴローゲー DO % saturation measured value	
	<u> </u>	Oxygen partial pressure measured value
	nc8P	Sensor cap serial number
		has occurred, or if the DO Sensor is not connected, the
	Temperature Display indi	
		not attached, or it is incorrectly attached, the
	Temperature Display indi	
	-	er consists of 6 digits. Since Temperature Display of this
	_	he DO Display indicates upper 2 figures,
		play indicates the remaining 4 digits.
		er is 123456, it is alternately indicated as follows.
	$ \qquad \qquad$	
		מכדו

7.15 Data Clear Group

To enter the Data Clear Group, follow the procedure below.

- ① *c.L.r* Press the

 Q key 10 times in Display Mode or Cleansing Output Mode.

 If EVT□ output (EVT option) is ordered, press the
 Q key 14 times in Display Mode
 or Cleansing Output Mode.
- ② ⊑'L'¬L Press the ^{set}/_{RESET} key.

The unit enters the Data Clear group, and the "Data clear selection" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
-L-L	Data clear selection	Calibration value
c RL	Selects either Calibration value or Set value to clear.	
	・ <i>c 吊L</i> : Calibration value	
	らん Set value	
c1-	Data clear Stop/Perform	Data clear Stop
no[]	Selects Data clear Stop/Perform.	
	• 🗖 🗖 🛄 : Data clear Stop	
	날돈님 : Data clear Perform	

Depending on the selection in [Data clear Stop/Perform], the unit operates as shown below.

• When 'Data clear Stop' is selected:

Data clearing is not executed, and the unit returns to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode).

• When 'Data clear Perform' is selected:

Data is cleared. The unit returns to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode).

(While data is being cleared, all indications are momentarily unlit.)

8. Calibration

The following are descriptions for DO concentration 1-point calibration mode, DO concentration 2-point calibration mode, Concentration option calibration mode, Transmission output 1 and 2 adjustment modes.

8.1 DO Concentration Calibration

8.1.1 Preparation

(1) Clean the DO Sensor body and measurement section, and remove all moisture.

(2) Remove the storage cap of the calibration container, and replace with a calibration cap (ventilating cap).



Calibration cap Storage cap (Fig. 8.1.1-1)

- (3) Keep the water, used for DO Sensor and calibration, at room temperature for approx. 30 minutes.
- (4) Select a mode from Sections 8.1.2 (DO Concentration 1-point Calibration Mode), 8.1.3 (DO Concentration 2-point Calibration Mode), and 8.1.4 (Concentration Option Calibration Mode), and perform calibration.

8.1.2 DO Concentration 1-point Calibration Mode

1 Caution

• If salinity concentration has been previously corrected, return the salinity concentration correction value to 0 PSU, then start calibration.

Refer to [Salinity correction (p.23)].

If calibration is performed with previously corrected salinity concentration, an error will occur, or calibration will not be performed normally.

• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

Refer to [Altitude correction (p.23)].

The unit cannot enter DO concentration 1-point calibration mode in the following cases.

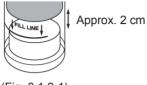
- ・When Loc 1, Lock 1), Loc 2) or Loc 3) is selected in [Set value lock (p.34)]
- When $\Box L E \tilde{L}$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'

Error Code	Description
ErrÖ	Non-volatile IC memory error
Err 1	DO Sensor communication errors have occurred, or DO Sensor is not connected.
Err2	DO Sensor cap is not attached, or it is incorrectly attached.

• When the following errors have occurred.

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(Fig. 8.1.2-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.



• Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.

(4) Press and hold the 🖂 and 🔘 key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.

The unit moves to DO concentration 1-point calibration mode, and indicates the following.

Display	Indication Contents
DO Display	DO concentration measured value
Temperature Display	

(5) Press the **E** key.

1-point calibration (100% saturation calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents
DO Display	DO concentration measured value flashes.
Temperature Display	

(6) Press the star key.

The measured value will be fixed, and automatic calibration will be performed. After calibration is finished, Displays show the following.

Display	Indication Contents
DO Display	cRL
Temperature Display	Good

1-point calibration (100% saturation calibration) is completed.

(7) Press the Est key.

The unit returns to DO concentration 1-point calibration mode.

If calibration cannot be performed during 1-point calibration (100% saturation calibration) due to unstable DO concentration input or temperature correction error, etc., the DO Display turns off, and the Temperature Display indicates $\mathcal{E} r r \mathcal{B}$.

To release the error code, press the \bigcirc or K key.

8.1.3 DO Concentration 2-point Calibration Mode

▲ Caution

• When using a sensor in geographically high elevation sites, perform altitude correction for

accurate calibration, then start calibration. Refer to [Altitude correction (p.23)].

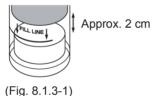
The unit cannot enter DO concentration 2-point calibration mode in the following cases.

- ・When Lac / (Lock 1), Lac 2 (Lock 2) or Lac 3 (Lock 3) is selected in [Set value lock (p.34)]
- When *cLEL* (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.
- When the following errors have occurred

Error Code	Description	
ErrO	Non-volatile IC memory error	
Err 1	DO Sensor communication errors have occurred, or DO Sensor is not	
	connected.	
Err2	DO Sensor cap is not attached, or it is incorrectly attached.	

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(3) Allow it to settle, undisturbed, for 5 to 10 minutes.

▲ Caution

• Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.

(4) Press and hold the 🖂 and 🔘 key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.

(5) Press the 🔘 key.

The unit moves to DO concentration 2-point calibration mode, and indicates the following.

Display	Indication Contents
DO Display	DO concentration measured value
Temperature Display	

(6) Press the **EFF** key.

1st-point calibration (100% saturation calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents
DO Display	DO concentration measured value flashes.
Temperature Display	

(7) Press the Est key.

The measured value will be fixed, and automatic calibration will be performed.

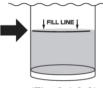
After 1st-point calibration (100% saturation calibration) is finished, Displays show the following.

Display	Indication Contents
DO Display	
Temperature Display	neur

(8) Prepare a Zero standard solution.

Zero standard solution is 100 mL of ion-exchanged water into which 5 g or more of sodium sulfite has been added and completely dissolved.

(9) Take out the calibration container sponge used for 1st-point calibration, and pour the Zero standard solution into the calibration container up to the Fill Line.



(Fig. 8.1.3-2)

(10) Insert the temperature sensor of the DO Sensor until it is immersed in the prepared Zero standard solution.



- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section so that air bubbles cannot attach to it.

(11) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.

(12) Press the Est key.

2nd-point calibration (0-point calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents	
DO Display	DO concentration measured value flashes.	
Temperature Display		

(13) Press the Key.

The measured value will be fixed, and automatic calibration will be performed.

After 2nd-point calibration (0-point calibration) is finished, Displays show the following.

Display	Indication Contents	
DO Display	cRL	
Temperature Display	Good	

2-point calibration (both 100% saturation calibration and 0-point calibration) is completed.

(14) Press the 🚟 key.

The unit returns to DO concentration 2-point calibration mode.

If calibration cannot be performed during DO concentration 2-point calibration due to unstable DO concentration input or temperature correction error, etc., the DO Display turns off, and the Temperature Display indicates $\mathcal{E} \vdash \mathcal{F} \mathcal{A}$.

To release the error code, press the \bigcirc or $\underbrace{\mathbb{E}}_{\mathbb{R}}$ key.

8.1.4 Concentration Option Calibration Mode

Immerse the DO Sensor in an aqueous solution (of which DO concentration is known), then the measurement value can be matched to the concentration.

Factory default value: 0.00 mg/L

DO concentration can be set within a range of 0.00 to 20.00 mg/L.

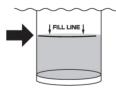
The unit cannot enter Concentration option calibration mode in the following cases.

- ・When Lock 1), Lock 2) or Lock 3) is selected in [Set value lock (p.34)]
- When LEL (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while
- cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.
- When the following errors have occurred.

Error Code	Description
ErrÖ	Non-volatile IC memory error
Err 1	DO Sensor communication errors have occurred, or DO Sensor is not connected.
Err2	DO Sensor cap is not attached, or it is incorrectly attached.

The following outlines calibration procedure (Setting to a concentration of 7.77 mg/L).

(1) Pour the already-known concentration solution into the calibration container up to the Fill Line.



(Fig. 8.1.4-1)

(2) Insert the temperature sensor of the DO Sensor until it is immersed in the poured solution.

A Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section without air bubbles being attached.

- (3) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.
- (4) Press and hold the 🖂 and 🔘 key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (5) Press the 🔘 key twice.

The unit moves to Concentration option calibration mode, and indicates the following.

Display	Indication Contents	
DO Display	cRdF	
Temperature Display	Concentration desired value	

(6) Set the concentration desired value (7.77) with the \bigtriangleup or \bigtriangledown key, and press the \blacksquare key. The following will be indicated.

Display	Indication Contents	
DO Display	DO concentration measured value flashes.	
Temperature Display		

(7) Press the start key.

The measured value will be fixed, and calibration will be performed.

If concentration option calibration is finished, Displays show the following.

Display	Indication Contents	
DO Display	cRL	
Temperature Display	Good	

Concentration option calibration is completed.

(8) Press the Key.

The unit reverts to Concentration option calibration mode.

(9) Press the 🔘 key.

The unit reverts to Display Mode or Cleansing Output Mode.

If errors occur during concentration option calibration, the DO Display will turn off, and the Temperature Display will indicate $\mathcal{E} \neg \neg \exists$.

To release the error code, press the \bigcirc or $\underbrace{\boxtimes}$ key.

8.2 Transmission Output 1 Adjustment Mode

Fine adjustment of Transmission output 1 is performed.

The WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument. In this case, perform Transmission output 1 Zero adjustment and Span adjustment.

The unit cannot enter Transmission output 1 Zero adjustment mode in the following cases.

- ・When Lac / (Lock 1), Lac 2 (Lock 2) or Lac 3 (Lock 3) is selected in [Set value lock (p.34)]
- When cLEL (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and
- cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'
- During DO concentration calibration

The following outlines the procedure for Transmission output 1 adjustment.

- (1) Press and hold the 🖾 and 🚟 key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (2) The unit enters Transmission output 1 Zero adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	RUE I	
Temperature Display	Transmission output 1 Zero adjustment value	

- (3) Set Transmission output 1 Zero adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (4) Press the Key.

The unit enters Transmission output 1 Span adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	R_5 1	
Temperature Display	Transmission output 1 Span adjustment value	

(5) Set Transmission output 1 Span adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span

Transmission output 1 adjustment is completed.

(6) Press the Key.

The unit reverts to Display Mode or Cleansing Output Mode.

8.3 Transmission Output 2 Adjustment Mode

Fine adjustment of Transmission output 2 is performed.

The WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument. In this case, perform Transmission output 2 Zero adjustment and Span adjustment.

The unit cannot enter Transmission output 2 Zero adjustment mode in the following cases.

- ・When Lac / (Lock 1), Lac 2 (Lock 2) or Lac 3 (Lock 3) is selected in [Set value lock (p.34)]
- When LEL (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'
- During DO concentration calibration

The following outlines the procedure for Transmission output 2 adjustment.

- (1) Press and hold the 🖂 and 🔚 key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (2) The unit enters Transmission output 2 Zero adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	RUEZ	
Temperature Display	Transmission output 2 Zero adjustment value	

- (3) Set Transmission output 2 Zero adjustment value with the △ or key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (4) Press the key.

The unit enters Transmission output 2 Span adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	Ruh2	
Temperature Display	Transmission output 2 Span adjustment value	

(5) Set Transmission output 2 Span adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span

Transmission output 2 adjustment is completed.

(6) Press the **Est** key.

The unit reverts to Display Mode or Cleansing Output Mode.

9. Measurement

9.1 Starting Measurement

For approx. 8 seconds after the power is switched ON, the following characters are indicated on the DO Display and Temperature Display.

Display	Indication Contents	
DO Display	do	
Temperature Display	Urrsion number (e.g.) 1.00]	

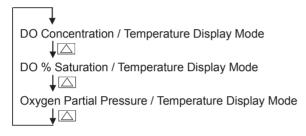
During this time, all outputs are in OFF status, and action indicators except the PWR indicator turn off.

After that, measurement starts, indicating DO concentration on the DO Display, and the measured temperature on the Temperature Display.

This status is called Display Mode or Cleansing Output Mode.

Switching Between Modes

Every time the \bigtriangleup key is pressed, modes on the DO Display progress as follows.



9.2 Outside Measurement Range

If DO concentration, DO % saturation, Oxygen partial pressure or temperature is outside the range, the following will be indicated.

Input	DO Display	Temperature Display
DO concentration	Flashes at 20.00 or 0.00.	Measured value
DO % saturation	Flashes at 200.0 or 0.0.	Measured value
Oxygen partial pressure	Flashes at 150.0 or 0.0.	Measured value
Temperature	Measured value	Flashes at 50.0 or 0.0.

9.3 Error Code

When the following errors occur, the DO Display turns off, and the Temperature Display indicates corresponding error code.

Error Code	Description	Occurrence
ErrO	Non-volatile IC memory error	Constantly
Err I	 DO Sensor communication errors have occurred, or DO Sensor is not connected. After a command is sent to the DO Sensor, if there is no response for 500 ms, the command will be sent again. If no response occurs 4 times consecutively, this error code will be indicated. If communication status returns to normal, the error will be released, and the unit will automatically return to normal status. When this error code is indicated, the previous measured value is retained. 	
Errd	DO Sensor cap is not attached, or it is incorrectly attached.	
Err3	Calibration error (If input errors have occurred, or if calibration cannot be performed 30 minutes after starting calibration)	When calibrating
Erry	DO Sensor internal memory deletion. Displayed when Quality ID3 is received from the DO Sensor.	When measuring and calibrating

9.4 About Transmission Output 1 and 2

Converting DO concentration, water temperature, DO % saturation, or Oxygen partial pressure to analog signal every update cycle via communication, and outputs in current.

If Transmission output 1 high limit and low limit are set to the same value, Transmission output 1 will be fixed at 4 mA DC.

If Transmission output 2 high limit and low limit are set to the same value, Transmission output 2 will be fixed at 4 mA DC.

Resolution	12000
Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)
Output accuracy	Within ±0.3% of Transmission output 1 or 2 span

For the following errors, Transmission output 1 or 2 will output 2 mA DC.

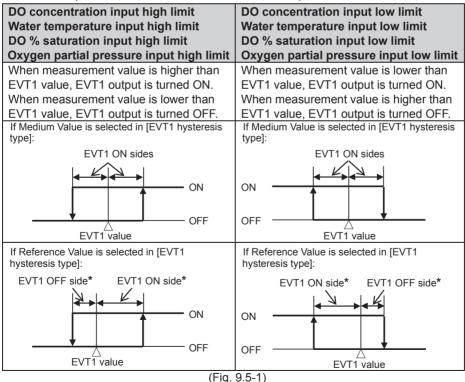
Error Code	Description
Err I	DO Sensor communication error, or DO Sensor is not connected.
Err2	DO Sensor cap is not attached, or it is incorrectly attached.
Err3	Calibration error (If input errors have occurred, or if calibration cannot be performed 30 minutes after starting calibration)

9.5 EVT1 to EVT6 Outputs

When any one of the following actions is selected in [EVT1 type (p.26)], it will perform as (Fig. 9.5-1). da_-H (DO concentration input high limit action), da_-L (DO concentration input low limit action), a_-H (Water temperature input high limit action), a_-L (Water temperature input low limit action), da_-H (DO % saturation input high limit action), da_-L (DO % saturation input low limit action), a_-H (DO % saturation input high limit action), da_-L (DO % saturation input low limit action), a_-H (Oxygen partial pressure input high limit action), a_-H (Oxygen partial pressure input low limit action)

The same applies to EVT2, EVT3, EVT4, EVT5 and EVT6.

• EVT1 Action (Activated based on the indication value)



* Setting Example:

If [EVT1 ON side (dFall)] is set to 0, EVT1 output can be turned ON at the value set in [EVT1 value $(\neg d la)$].

If [EVT1 OFF side $(d^F U^i)$] is set to 0, EVT1 output can be turned OFF at the value set in [EVT1 value $(\neg U^i)$].

When any one of the following actions is selected in [EVT1 type (p.26)], it will perform as (Fig. 9.5-2).

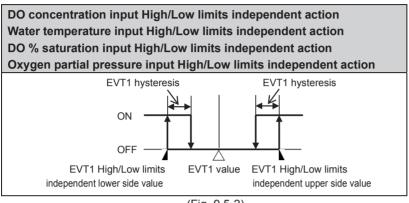
ゴロビン (DO concentration input High/Low limits independent action),

FAHL (Water temperature input High/Low limits independent action),

ゴードン (DO % saturation input High/Low limitsindependent action),

GPHL (Oxygen partial pressure input High/Low limits independent action)

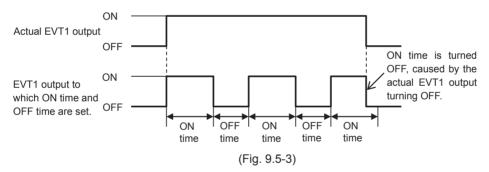
The same applies to EVT2, EVT3, EVT4, EVT5 and EVT6.



(Fig. 9.5-2)

When 'Output ON time and OFF time when EVT1 Output is ON' are set, the following action is performed.

• Timing chart (Output ON time and OFF time when EVT1 output is ON)



EVT output status can be read by reading Status flag 2 (EVT1 to EVT6 output flag bit) in Serial communication.

EVT output status, when input errors occur, differs depending on the selection in [EVT output when input errors occur (p.34)].

- If $\Box F F \square$ (Disabled) is selected: EVT output is turned OFF when input errors occur.
- If $\Box \sigma$ (Enabled) is selected: EVT output is maintained when input errors occur.

9.6 Sensor Cap Replacement Timer Output

When $\mathcal{F} \subset \mathcal{PP}$ (Sensor cap replacement timer output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], the unit operates as follows.

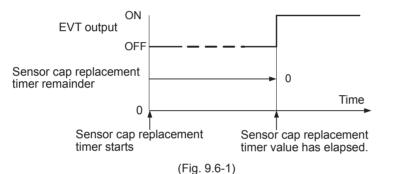
 If Sensor cap replacement timer value has elapsed (when Sensor cap replacement timer remainder is "0"), the selected EVT output will be turned ON. (*1)

The DO Display indicates DO concentration measured value and $\Gamma = RP$ alternately, informing the user to replace the sensor cap. (*2)

(2) Replace the sensor cap.

After replacing the sensor cap, this unit automatically resets the Sensor cap replacement remainder to the Sensor cap replacement timer value.

Sensor Cap Replacement Timer Output



- (*1) Even if power to this instrument is turned OFF and ON, EVT output remains ON until the sensor cap is replaced.
- (*2) After Sensor cap replacement timer value has elapsed, and if Outside measurement range error has occurred simultaneously, *F* = *BP* and the Outside measurement range value will be displayed alternately.

9.7 Cleansing Output

If cLEG (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], the unit will enter Cleansing Output Mode.

After 'Cleansing inactive interval' has elapsed, the selected EVT output is turned ON during the 'Cleansing time'.

After 'Standby after cleansing' has passed, the above action is repeated.

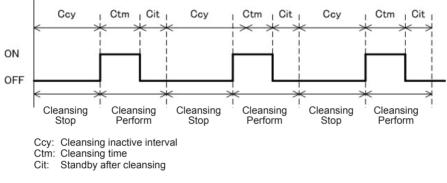
While cleansing is being performed using 'Cleansing time' and 'Standby after cleansing', other outputs are in OFF status.

Measured values (DO concentration, DO % saturation, Oxygen partial pressure, water temperature) are retained.

Normal programmed action will be performed, except during 'Cleansing Perform'.

When power is turned ON again, starts from 'Cleansing inactive interval'.

Cleansing Output Action



(Fig. 9.7-1)

• If *cLEL* (Cleansing output) is selected in any other [EVT type] during cleansing action, the current setting values (Cleansing time, Cleansing inactive interval, Standby after cleansing) will be used for the selected cleansing output.

If cleansing action (caused by cleansing cycle) is activated in calibration mode, cleansing action will not be performed in the current session.

• If $\Box FF \square$ (None) is selected in [Cleansing inactive interval], or if any item except $\Box LE \Box$ (Cleansing output) is selected in [EVT1 to EVT6 types (pp. 26, 31)], Cleansing Output Mode will end, and the unit will revert to Display Mode.

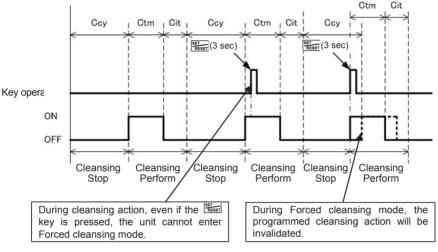
If cLEL (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and if cEE (None) is selected in [Cleansing inactive interval], only Forced cleansing mode will be enabled.

9.8 Forced Cleansing Mode

By pressing the see key for approx. 3 seconds, the unit enters Forced cleansing mode. In Forced cleansing mode, cleansing is performed using 'Cleansing time' and 'Standby after cleansing'.

After cleansing action is finished, the unit automatically reverts to Cleansing Output Mode. This mode will not be accessible by the see key if programmed cleansing is currently being performed.

During Forced cleansing mode, if programmed cleansing action initiates after 'Cleansing inactive interval' has passed, the programmed cleansing action will not be performed in the current session.



Forced Cleansing Mode Action

Ccy: Cleansing inactive interval

Ctm: Cleansing time

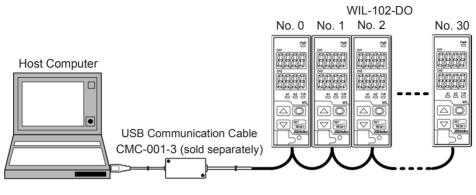
Cit: Standby after cleansing

(Fig. 9.8-1)

10. Communication

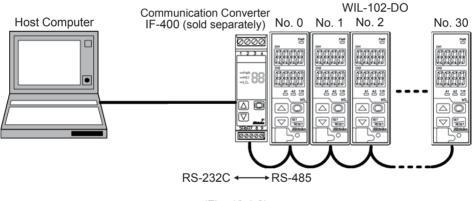
10.1 System Configuration Example

• When using the USB Communication Cable CMC-001-3 (sold separately)



(Fig. 10.1-1)

• When using the Communication Converter IF-400 (sold separately)



(Fig. 10.1-2)

10.2 Setting Method of the Instrument

Communication parameters can be set in the Communication Group.

To enter the Communication Group, follow the procedure below.

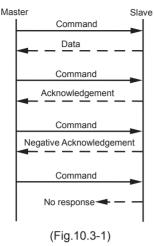
- ① ここへつ Press the D key 6 times in Display Mode or Cleansing Output Mode.
 If EVT output (EVT option) is ordered, press the D key 10 times in Display Mode or Cleansing Output Mode.
- ② ェボーム Press the End key. The unit enters Communication Group, and 'Communication protocol' will appear.
- ③ Set each item. (Use the \square or \square key for settings, and register the value with the \blacksquare key.)

Character	Setting Item, Function, Setting Range	Factory Default
c752	Communication protocol	Shinko protocol
noñL	 Selects communication protocol. 	
	・ ヮヮヮ゙゙゚ : Shinko protocol	
	ನ್ಎಡೆ∺ : MODBUS ASCII mode	
	กัดอ่า : MODBUS RTU mode	
cñno	Instrument number	0
	 Sets the instrument number. 	
	The instrument numbers should be set one by	one when multiple instruments are
	connected in Serial communication, otherwise	e communication is impossible.
	Setting range: 0 to 95	
<u>c74</u> P	Communication speed	9600 bps
<u> </u>	Selects a communication speed equal to that	of the host computer.
	•	
	☐ <i>192</i> : 19200 bps	
	<i>∃</i> ₿Ч : 38400 bps	
-7687 7687	Data bit/Parity	7 bits/Even
1280	• Selects data bit and parity.	
	• Bron : 8 bits/No parity	
	ີໄດຍດ : 7 bits/No parity ອີຣິຟິດ : 8 bits/Even	
	7EHn : 7 bits/Even	
	Bodd : 8 bits/Odd	
	Todd : 7 bits/Odd	
<u>รลิ</u> ร์โ	Stop bit	1 bit
	Selects the stop bit.	
	• <i>l</i> : 1 bit	
	\vec{z} : 2 bits	

④ Press the 🖼 key several times. The unit reverts to Display Mode or Cleansing Output Mode.

10.3 Communication Procedure

Communication starts with command transmission from the host computer (hereafter Master) and ends with the response of the WIL-102-DO (hereafter Slave).



Response with Data

When the master sends the reading command, the slave responds with the corresponding set value or current status.

Acknowledgement

When the master sends the setting command, the slave responds by sending acknowledgement after the processing is terminated.

Negative Acknowledgement

When the master sends a non-existent command or value out of the setting range, the slave returns a negative acknowledgement.

No Response

The slave will not respond to the master in the following cases:

- Global address (Shinko protocol) is set.
- Broadcast address (MODBUS protocol) is set.
- Communication error (framing error, parity error)
- Checksum error (Shinko protocol), LRC discrepancy (MODBUS ASCII mode), CRC-16 discrepancy (MODBUS RTU mode)

Communication Timing of the RS-485

Master Side (Take note while programming)

When the master starts transmission through the RS-485 communication line, the master is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the command to ensure synchronization on the receiving side.

Set the program so that the master can disconnect the transmitter from the communication line within a 1 character transmission period after sending the command in preparation for reception of the response from the slave.

To avoid collision of transmissions between the master and the slave, send the next command after carefully checking that the master has received the response.

If a response to the command is not returned due to communication errors, set the Retry Processing to send the command again. (It is recommended to execute Retry twice or more.)

Slave Side

When the slave starts transmission through the RS-485 communication line, the slave is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the response to ensure synchronization on the receiving side.

The slave is arranged so as to disconnect the transmitter from the communication line within a 1 character transmission period after sending the response.

10.4 Shinko Protocol

10.4.1 Transmission Mode

Shinko protocol is composed of ASCII.

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit Data bit: 7 bits Parity: Even Stop bit: 1 bit

Error detection: Checksum

10.4.2 Command Configuration

All commands are composed of ASCII.

The data (set value, decimal number) is represented by hexadecimal numbers.

The negative numbers are represented in 2's complement.

Numerals written below the command represent the number of characters.

(1) Setting Command

-	Header (02H)	Address	Sub address (20H)	Command type (50H)	Data item	Data	Checksum	Delimiter (03H)
	1	1	1	1	4	4	2	1

(2) Reading Command

Header (02H)	Address	Sub address (20H)	Command type (20H)	Data item	Checksum	Delimiter (03H)
1	1	1	1	4	2	1

(3) Response with Data

Header (06H)	Address	Sub address (20H)	Command type (20H)	Data item	Data	Checksum	Delimiter (03H)
1	1	1	1	4	4	2	1

(4) Acknowledgement

Header (06H)	Address	Checksum	Delimiter (03H)
1	1	2	1

(5) Negative Acknowledgement

Header	Address	Error	Checksum	Delimiter
(15H)	Address	code	CHECKSUIII	(03H)
1	1	1	2	1

 Header:
 Control code to represent the beginning of the command or the response. ASCII codes are used. Setting command, Reading command:
 STX (02H) fixed.

 Response with data, Acknowledgement:
 ACK (06H) fixed.

 Negative acknowledgement:
 NAK (15H) fixed.

 Instrument Number (Address):
 Numbers by which the master discerns each slave.

 Instrument number 0 to 94 and Global address 95.
 ASCII codes (20H to 7FH) are used by adding 20H to instrument numbers 0 to 95

> (00H to 5FH). 95 (7FH) is called Global address, which is used when the same command is sent to all the slaves connected. However, the response is not returned.

Sub Address: 20H fixed.

Command Type: Code to discern Setting command (50H) and Reading command (20H).

Data Item: Classification of the command object.

Composed of 4-digit hexadecimal numbers, using ASCII.

Refer to "10.6. Communication Command Table". (pp. 64 to 72)

Data:	The contents of data (set value) differ depending on the setting command. Composed of 4-digit hexadecimal numbers, using ASCII. Refer to "10.6. Communication Command Table". (pp. 64 to 72)
Checksum:	2-character data to detect communication errors.
	Refer to "10.4.3 Checksum Calculation".
Delimiter:	Control code to represent the end of command.
	ASCII code ETX (03H) fixed.
Error Code:	Represents an error type using ASCII.
	1 (31H)Non-existent command
	2 (32H)Not used
	3 (33H)Value outside the setting range
	4 (34H)Status unable to be set (e.g. During calibration)
	5 (35H)During setting mode by keypad operation

10.4.3 Checksum Calculation

Checksum is used to detect receiving errors in the command or data.

Set the program for the master side as well to calculate the checksum of the response data from the slaves so that communication errors can be checked.

The ASCII code (hexadecimal) corresponding to the characters which range from the address to that before the checksum is converted to binary notation, and the total value is calculated.

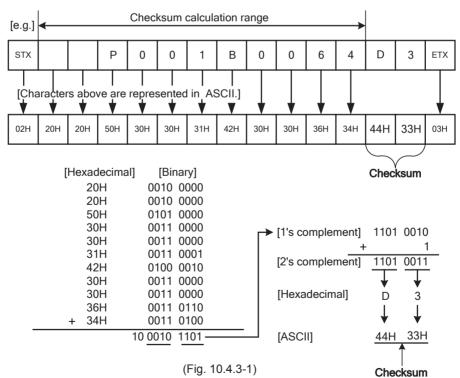
The lower one byte of the total value is converted to 2's complement, and then to hexadecimal numbers, that is, ASCII code for the checksum.

• 1's complement: Reverse each binary bit. 0 will become 1 and vice versa.

• 2's complement: Add 1 to 1's complement.

Checksum Calculation Example

Data item 001BH (EVT1 ON delay time): 100 seconds (0064H) Address (instrument number): 0 (20H)



10.5 MODBUS Protocol

10.5.1 Transmission Mode

There are 2 transmission modes (ASCII and RTU) in MODBUS protocol.

ASCII Mode

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit Data bit: 7 bits (8 bits) (Selectable) Parity: Even (No parity, Odd) (Selectable) Stop bit: 1 bit (2 bits) (Selectable)

Error detection : LRC (Longitudinal Redundancy Check)

RTU Mode

8-bit binary data in command is transmitted as it is. Data format Start bit: 1 bit Data bit: 8 bits Parity: No parity (Even, Odd) (Selectable) Stop bit: 1 bit (2 bits) (Selectable) Error detection: CRC-16 (Cyclic Redundancy Check)

10.5.2 Data Communication Interval

ASCII Mode

Max.1 second of interval between ASCII mode characters

RTU Mode

Communication speed 9600 bps, 19200 bps:

To transmit continuously, an interval between characters which consist of one message, must be within 1.5-character transmission times.

Communication speed 38400 bps:

To transmit continuously, an interval between characters which consist of one message, must be within 750 $\,\mu{
m s}.$

If an interval lasts longer than 1.5-character transmission times or 750 μ s, the WIL-102-DO assumes that transmission from the master is finished, which results in a communication error, and will not return a response.

10.5.3 Message Configuration

ASCII Mode

ASCII mode message is configured to start by Header [: (colon) (3AH)] and end by Delimiter [CR (carriage return) (0DH) + LF (Line feed) (0AH)].

Header	Slave	Function	Dete	Error check	Delimiter	Delimiter
(:)	address	code	Data	LRC	(CR)	(LF)

RTU Mode

Communication speed 9600 bps, 19200 bps: RTU mode is configured to start after idle time is processed for more than 3.5-character transmissions, and end after idle time is processed for more than 3.5-character transmissions.

Communication speed 38400 bps: RTU mode is configured to start after idle time is processed for more than 1.75 ms, and end after idle time is processed for more than 1.75 ms.

3.5 idle	Slave	Function	Data	Error check	3.5 idle
characters	address	code	Dala	CRC-16	characters

(1) Slave Address

Slave address is an individual instrument number on the slave side, and is set within the range 0 to 95 (00H to 5FH). The master identifies slaves by the slave address of the requested message.

The slave informs the master which slave is responding to the master by placing its own address in the response message.

Slave address 00H (Broadcast address) can identify all the slaves connected. However, slaves do not respond.

(2) Function Code

The function code is the command code for the slave to undertake one of the following actions. **(Table 10.5.3-1)**

Function Code	Contents
03 (03H)	Reading the set value and information from slaves
06 (06H)	Setting to slaves

The Function code is used to discern whether the response is normal (acknowledgement) or if any error (negative acknowledgement) has occurred when the slave returns the response message to the master.

When acknowledgement is returned, the slave simply returns the original function code.

When negative acknowledgement is returned, the MSB of the original function code is set as 1 for the response.

(For example, if the master sends request message setting 10H to the function code by mistake, slave returns 90H by setting the MSB to 1, because the former is an illegal function.)

For negative acknowledgement, the exception codes below are set to the data of the response message, and returned to the master in order to inform it of what kind of error has occurred. (Table 10.5.3-2)

(Table 10.5.3-2)

Exception Code	Contents
1 (01H)	Illegal function (Non-existent function)
2 (02H)	Illegal data address (Non-existent data address)
3 (03H)	Illegal data value (Value out of the setting range)
17 (11H)	Shinko protocol error code 4 [Status unable to be set. (e.g.) During calibration]
18 (12H)	Shinko protocol error code 5 (During setting mode by keypad operation)

(3) Data

Data differs depending on the function code.

A request message from the master is composed of a data item, amount of data and setting data. A response message from the slave is composed of the byte count, data and exception codes in negative acknowledgements.

The effective range of data is -32768 to 32767 (8000H to 7FFFH).

(4) Error Check

ASCII Mode

After calculating LRC (Longitudinal Redundancy Check) from the slave address to the end of data, the calculated 8-bit data is converted to two ASCII characters, and are appended to the end of message.

How to calculate LRC

- ① Create a message in RTU mode.
- ^② Add all the values from the slave address to the end of data. This is assumed as X.
- ③ Make a complement for X (bit reverse). This is assumed as X.
- ④ Add a value of 1 to X. This is assumed as X.
- ⁽⁵⁾ Set X as an LRC to the end of the message.
- ⁽⁶⁾ Convert the whole message to ASCII characters.

RTU Mode

After calculating CRC-16 (Cyclic Redundancy Check) from the slave address to the end of the data, the calculated 16-bit data is appended to the end of message in sequence from low order to high order.

How to calculate CRC-16

In the CRC-16 system, the information is divided by the polynomial series. The remainder is added to the end of the information and transmitted. The generation of a polynomial series is as follows. (Generation of polynomial series: $X^{16} + X^{15} + X^2 + 1$)

- 1 Initialize the CRC-16 data (assumed as X) (FFFFH).
- ⁽²⁾ Calculate exclusive OR (XOR) with the 1st data and X. This is assumed as X.
- ③ Shift X one bit to the right. This is assumed as X.
- ④ When a carry is generated as a result of the shift, XOR is calculated by X of ③ and the fixed value (A001H). This is assumed as X. If a carry is not generated, go to step ⑤.
- $^{(5)}$ Repeat steps $^{(3)}$ and $^{(4)}$ until shifting 8 times.
- ⁽⁶⁾ XOR is calculated with the next data and X. This is assumed as X.
- ⑦ Repeat steps ③ to ⑤.
- (8) Repeat steps (3) to (5) up to the final data.
- (9) Set X as CRC-16 to the end of message in sequence from low order to high order.

10.5.4 Message Example

ASCII Mode

Numerals written below the command represent the number of characters.

① Reading [Slave address 1, Data item 0080H (DO concentration)]

• A request message from the master

Amount of data means how many data items are to be read. It is fixed as (30H 30H 30H 31H).

Header	Slave	Function	Data item	Amount of data	Error check	Delimiter
	address	code	[0080H]	[0001H]	LRC	
(3AH)	(30H 31H)	(30H 33H)	(30H 30H 38H 30H)	(30H 30H 30H 31H)	(37H 42H)	(0DH 0AH)
1	2	2	4	4	2	2

 Response message from the slave in normal status [When DO concentration is 1.00 mg/L (0064H)] The response byte count means the byte count of data which have been read. It is fixed as (30H 32H).

Header (3AH)	address	Function code (30H 33H)	Response byte count [02H] (30H 32H)	Data [0064H] (30H 30H 36H 34H)	Error check LRC (39H 36H)	Delimiter (0DH 0AH)
1	2	2	2	4	2	2

• Response message from the slave in exception (error) status (When a data item is incorrect) The function code MSB is set to 1 for the response message in exception (error) status (83H is returned). The exception code 02H (Non-existent data address) is returned (error).

Header	Slave	Function	Exception code	Error check	Delimiter
	address	code	[02H]	LRC	
(3AH)	(30H 31H)	(38H 33H)	(30H 32H)	(37H 41H)	(0DH 0AH)
1	2	2	2	2	2

② Setting [Slave address 1, Data item 001BH (EVT1 ON delay time)

•	A request message from the master [When EVT1 ON delay time is set to 100 seconds (0064H)]						
	Header	Slave	Function	Data item	Data	Error check	Delimiter
		address	code	[001BH]	[0064H]	LRC	
	(3AH)	(30H 31H)	(30H 36H)	(30H 30H 31H 42H)	(30H 30H 36H 34H)	(44H 45H)	(0DH 0AH)
	1	2	2	4	4	2	2

• Response message from the slave in normal status

	<u> </u>					
Header	Slave	Function	Data item	Data	Error check	Delimiter
	address	code	[001BH]	[0064H]	LRC	
(3AH)	(30H 31H)	(30H 36H)	(30H 30H 31H 42H)	(30H 30H 36H 34H)	(44H 45H)	(0DH 0AH)
1	2	2	4	4	2	2

• Response message from the slave in exception (error) status (When a value out of the setting range is set.)

The function code MSB is set to 1 for the response message in exception (error) status (86H is returned). The exception code 03H (Value out of the setting range) is returned (error).

Header	Slave	Function	Exception code	Error check	Delimiter
	address	code	[03H]	LRC	
(3AH)	(30H 31H)	(38H 36H)	(30H 33H)	(37H 36H)	(0DH 0AH)
1	2	2	2	2	2

RTU Mode

Numerals written below the command represent number of characters.

① Reading [Slave address 1, Data item 0080H (DO concentration)]

• A request message from the master

Amount of data means how many data items are to be read. It is fixed as (0001H).

3.5 idle	Slave	Function	Data item	Amount of data	Error check	3.5 idle
characters	address	code			CRC-16	
characters	(01H)	(03H)	(0080H)	(0001H)	(85E2H)	characters
	1	1	2	2	2	

• Response message from the slave in normal status [When DO concentration is 1.00 mg/L (0064H)] The response byte count means the byte count of data which has been read. It is fixed as (02H).

3.5 idle	Slave	Function	Response	Data	Error check	3.5 idle
	address	code	byte count		CRC-16	
characters	(01H)	(03H)	(02H)	(0064H)	(B9AFH)	characters
.	1	1	1	2	2	

• Response message from the slave in exception (error) status (When a data item is incorrect) The function code MSB is set to 1 for the response message in exception (error) status (83H is returned).

The exception code (02H: Non-existent data address) is returned (error).

3.5 idle characters	Slave address	Function code	Exception code	Error check CRC-16	3.5 idle characters
characters	(01H)	(83H)	(02H)	(C0F1H)	characters
	1	1	1	2	

② Setting (Slave address 1, Data item 001BH (EVT1 ON delay time)

• A request message from the master [When EVT1 ON delay time is set to 100 seconds (0064H)]

3.5 idle characters	Slave address	Function code	Data item	Data	Error check CRC-16	3.5 idle characters	
	(01H)	(06H)	(001BH)	(0064H)	(F826H)		
	1	1	2	2	2		

• Response message from the slave in normal status

3.5 idle characters	Slave address (01H)	Function code (06H)	Data item (001BH)	Data (0064H)	Error check CRC-16 (F826H)	3.5 idle characters
	1	1	2	2	2	

• Response message from the slave in exception (error) status (When a value out of the setting range is set)

The function code MSB is set to 1 for the response message in exception (error) status (86H is returned.).

The exception code (03H: Value out of the setting range) is returned (error).

3.5 idle characters	Slave address (01H)	Function code (86H)	Exception code (03H)	CRC-16	3.5 idle characters
	1	1	1	2	

10.6 Communication Command Table

10.6.1 Notes about Setting/Reading Command

- The data (set value, decimal) is converted to hexadecimal numbers. Negative numbers are represented in 2's complement.
- When connecting multiple slaves, the address (instrument number) must not be duplicated.
- Data items 0200H to 0209H (User save area 1 to 10) can be read or set in 1 word units.
- Effective range of data is -32768 to 32767 (8000H to 7FFFH).
- MODBUS protocol uses Holding Register addresses. The Holding Register addresses are created as follows. A Shinko command data item is converted to decimal number, and the offset of 40001 is added. The result is the Holding Register address.

Using Data item 0001H (Signal output response time) as an example: Data item in the sending message is 0001H, however, MODBUS protocol Holding Register address is 40002 (1 + 40001).

• Even if EVT output (EVT option) is not ordered, setting or reading via software communication will be possible. However, EVT3 to EVT6 command contents will not function.

(1) Setting Command

• Up to 1,000,000 (one million) entries can be stored in non-volatile IC memory.

If the number of settings exceeds the limit, the data will not be saved. So, do not change the set values frequently via software communication. (If a value set via software communication is the same as the value before the setting, the value will not be written in non-volatile IC memory.)

- Be sure to select Lock 3 when changing the set value frequently via software communication. If Lock 3 is selected, all set values can be temporarily changed. However, they revert to their previous value after the power is turned off because they are not saved in the non-volatile IC memory.
 Do not change setting items (EVT1, EVT2, EVT3, EVT4, EVT5, EVT6 types). If they are changed, they will affect other setting items.
- Setting range of each item is the same as that of keypad operation.
- When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used.
- If EVT type is changed in [EVT1 type] to [EVT6 type], EVT1 to EVT6 value will default to 0 (zero). The output status of EVT1 to EVT6 will also be initialized.
- Settings via software communication are possible while in Set value lock status.
- Communication parameters such as Instrument Number, Communication Speed of the slave cannot be set by software communication. They can only be set via the keypad. (p.56)
- When sending a command by Global address [95 (7FH), Shinko protocol] or Broadcast address [(00H), MODBUS protocol], the same command is sent to all the slaves connected. However, the response is not returned.

(2) Reading Command

• When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used for a response.

10.6.2 Setting/Reading Command

Shinko Command	MODBUS			Dete
Type	Code			Data
50H/20H			Signal output response time	Set value (1 to 120) '1' corresponds to 5 seconds, and '120' corresponds to 600 seconds.
50H/20H			Salinity correction	Set value
50H/20H			Altitude correction	Set value
50H	06H	0005H	DO concentration calibration mode	0000H: Display Mode 0001H: DO concentration 1-point calibration mode 0002H: DO concentration 2-point calibration mode 0003H: Concentration option calibration mode
50H	06H	0006H	DO concentration calibration start	 DO concentration 1-point calibration: 0000H: DO concentration 1-point calibration mode 0001H: 1-point calibration (100% saturation calibration) start 0003H: Measured value fixed DO concentration 2-point calibration: 0000H: DO concentration 2-point calibration mode 0001H: 1st-point calibration (100% saturation calibration) start 0002H: 2nd-point calibration (0-point calibration) start 0003H: Measured value fixed Concentration option calibration: 0000H: Concentration option calibration mode 0001H: Concentration option calibration start 0003H: Measured value fixed
50H/20H	06H/03H	0007H	Concentration desired value	Set value (Decimal point ignored.)
50H/20H			Transmission output 1 type	0000H: DO concentration transmission 0001H: Water temperature transmission 0002H: DO % saturation transmission 0003H: Oxygen partial pressure transmission
50H/20H	06H/03H	0009H	Transmission output 1 high limit	Set value (Decimal point ignored.)
50H/20H			Transmission output 1 low limit	Set value (Decimal point ignored.)
50H/20H				0000H: DO concentration transmission 0001H: Water temperature transmission 0002H: DO % saturation transmission 0003H: Oxygen partial pressure transmission
50H/20H			Transmission output 2 high limit	Set value (Decimal point ignored.)
50H/20H	06H/03H		Transmission output 2 low limit	Set value (Decimal point ignored.)
50H	06H		Transmission output 1 adjustment mode	0000H: Display Mode 0001H: Transmission output 1 Zero adjustment mode 0002H: Transmission output 1 Span adjustment mode
50H/20H			Transmission output 1 Zero adjustment value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0010H	Transmission output 1 Span adjustment value	Set value (Decimal point ignored.)

Shinko Command Type	MODBUS Function Code		Data Item	Data
50H	06H	0011H	Transmission output 2 adjustment mode	0000H: Display Mode 0001H: Transmission output 2 Zero adjustment mode 0002H: Transmission output 2 Span adjustment mode
50H/20H	06H/03H	0012H	Transmission output 2 Zero adjustment value	Set value (Decimal point ignored.)
50H/20H			Transmission output 2 Span adjustment value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0014H	EVT1 type	 0000H: No action 0001H: DO concentration input high limit action 002H: DO concentration input low limit action 003H: Water temperature input low limit action 004H: Water temperature input low limit action 005H: DO % saturation input high limit action 006H: DO % saturation input low limit action 006H: DO % saturation input low limit action 007H: Oxygen partial pressure input high limit action 008H: Oxygen partial pressure input low limit action 008H: Oxygen partial pressure input low limit action 008H: Cleansing output 000CH: DO concentration input High/Low limits independent action 000DH: Water temperature input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000FH: OXygen partial pressure input High/Low limits independent action
50H/20H	06H/03H	0015H	EVT1 value	Set value (Decimal point ignored.)
50H/20H			EVT1 hysteresis type	0000H: Medium Value 0001H: Reference Value
50H/20H			EVT1 ON side	Set value (Decimal point ignored.)
50H/20H			EVT1 OFF side	Set value (Decimal point ignored.)
50H/20H			EVT1 ON delay time	Set value
50H/20H	06H/03H	001CH	EVT1 OFF delay time	Set value
50H/20H			Output ON Time when EVT1 Output ON	Set value
50H/20H			Output OFF Time when EVT1 Output ON	Set value
50H/20H	06H/03H	UU22H	EVT2 type	 0000H: No action 0001H: DO concentration input high limit action 0002H: DO concentration input low limit action 0003H: Water temperature input low limit action 0004H: Water temperature input low limit action 005H: DO % saturation input high limit action 006H: DO % saturation input low limit action 006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input low limit action 0008H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action 0008H: Cleansing output 000CH: DO concentration input High/Low limits independent action 000DH: Water temperature input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000FH: Coxygen partial pressure input High/Low limits independent action

Shinko	MODBUS					
Command Type			Data Item	Data		
50H/20H	06H/03H	0023H	EVT2 value	Set value (Decimal point ignored.)		
50H/20H	06H/03H	0026H	EVT2 hysteresis type	0000H: Medium Value		
				0001H: Reference Value		
50H/20H			EVT2 ON side	Set value (Decimal point ignored.)		
50H/20H	06H/03H	0028H	EVT2 OFF side	Set value (Decimal point ignored.)		
50H/20H			EVT2 ON delay time	Set value		
50H/20H			EVT2 OFF delay time	Set value		
50H/20H	06H/03H	002EH	Output ON Time when	Set value		
			EVT2 Output ON			
50H/20H	06H/03H	002FH	Output OFF Time when	Set value		
			EVT2 Output ON			
50H/20H	06H/03H	0030H	EVT3 type	0000H: No action		
				0001H: DO concentration input high limit action		
				0002H: DO concentration input low limit action		
				0003H: Water temperature input high limit action		
				0004H: Water temperature input low limit action		
				0005H: DO % saturation input high limit action		
				0006H: DO % saturation input low limit action		
				0007H: Oxygen partial pressure input high limit action		
				0008H: Oxygen partial pressure input low limit action		
				0009H: Sensor cap replacement timer		
				000AH: Self-check output		
				000BH: Cleansing output		
				000CH: DO concentration input High/Low limits		
				independent action		
				000DH: Water temperature input High/Low limits		
				independent action		
				000EH: DO % saturation input High/Low limits		
				independent action		
				000FH: Oxygen partial pressure input High/Low		
				limits independent action		
50H/20H	06H/03H	0031H	EVT3 value	Set value (Decimal point ignored.)		
50H/20H			EVT3 hysteresis type	0000H: Medium Value		
00172011	001//0011	000111		0001H: Reference Value		
50H/20H	06H/03H	0035H	EVT3 ON side	Set value (Decimal point ignored.)		
50H/20H			EVT3 OFF side	Set value (Decimal point ignored.)		
50H/20H			EVT3 ON delay time	Set value		
50H/20H			EVT3 OFF delay time	Set value		
50H/20H			Output ON Time when	Set value		
	501 // 0011		EVT3 Output ON			
50H/20H	06H/03H	003DH	Output OFF Time when	Set value		
0011/2011	301 // 0011		EVT3 Output ON			
<u> </u>	L	I				

Shinko Command Type	MODBUS Function Code		Data Item	Data
50H/20H	06H/03H	003EH	EVT4 type	0000H: No action
				0001H: DO concentration input high limit action
				0002H: DO concentration input low limit action
				0003H: Water temperature input high limit action
				0004H: Water temperature input low limit action
				0005H: DO % saturation input high limit action
				0006H: DO % saturation input low limit action
				0007H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action
				0009H: Sensor cap replacement timer
				000AH: Self-check output
				000BH: Cleansing output
				000CH: DO concentration input High/Low limits
				independent action
				000DH: Water temperature input High/Low limits
				independent action
				000EH: DO % saturation input High/Low limits
				independent action
				000FH: Oxygen partial pressure input High/Low
				limits independent action
50H/20H			EVT4 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0042H	EVT4 hysteresis type	0000H: Medium Value
5011/0011	0011/0011	004011		0001H: Reference Value
50H/20H			EVT4 ON side	Set value (Decimal point ignored.)
50H/20H 50H/20H			EVT4 OFF side EVT4 ON delay time	Set value (Decimal point ignored.) Set value
50H/20H			EVT4 OFF delay time	Set value
50H/20H			Output ON Time when	Set value
			EVT4 Output ON	
50H/20H	06H/03H	004BH	Output OFF Time when	Set value
			EVT4 Output ON	
50H/20H	06H/03H	004CH	EVT5 type	0000H: No action
				0001H: DO concentration input high limit action
				0002H: DO concentration input low limit action
				0003H: Water temperature input high limit action
				0004H: Water temperature input low limit action
				0005H: DO % saturation input high limit action 0006H: DO % saturation input low limit action
				0006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input high limit action
				0008H: Oxygen partial pressure input low limit action
				0009H: Sensor cap replacement timer
				000AH: Self-check output
				000BH: Cleansing output
				000CH: DO concentration input High/Low limits
				independent action
				000DH: Water temperature input High/Low limits
				independent action
				000EH: DO % saturation input High/Low limits
				independent action
				000FH: Oxygen partial pressure input High/Low
				limits independent action

Shinko Command Type	MODBUS Function Code			Data
50H/20H	06H/03H	004DH	EVT5 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0050H	EVT5 hysteresis type	0000H: Medium Value
				0001H: Reference Value
50H/20H			EVT5 ON side	Set value (Decimal point ignored.)
50H/20H			EVT5 OFF side	Set value (Decimal point ignored.)
50H/20H			EVT5 ON delay time	Set value
50H/20H			EVT5 OFF delay time	Set value
50H/20H	06H/03H	0058H	Output ON Time when EVT5 Output ON	Set value
50H/20H	06H/03H	0059H	Output OFF Time when EVT5 Output ON	Set value
50H/20H	06H/03H	005AH	EVT6 type	 0000H: No action 0001H: DO concentration input high limit action 0002H: DO concentration input low limit action 0003H: Water temperature input low limit action 0004H: Water temperature input low limit action 0005H: DO % saturation input high limit action 0006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action 0008H: Sensor cap replacement timer 000AH: Self-check output 000BH: Cleansing output 000CH: DO concentration input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000FH: DO % saturation input High/Low limits independent action 000FH: DO % saturation input High/Low limits independent action
50H/20H	06H/03H	005BH	EVT6 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	005EH	EVT6 hysteresis type	0000H: Medium Value
				0001H: Reference Value
50H/20H	06H/03H	005FH	EVT6 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0060H	EVT6 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0061H	EVT6 ON delay time	Set value
50H/20H	06H/03H	0062H	EVT6 OFF delay time	Set value
50H/20H	06H/03H	0066H	Output ON Time when EVT6 Output ON	Set value
50H/20H	06H/03H	0067H	Output OFF Time when EVT6 Output ON	Set value
50H/20H	06H/03H	0068H	Cleansing time	Set value
50H/20H	06H/03H	0069H	Cleansing inactive interval	Set value
50H	06H	006AH	Forced cleansing mode	0001H: Forced cleansing mode
50H/20H			Set value lock	0000H: Unlock 0001H: Lock 1 0002H: Lock 2 0003H: Lock 3
50H/20H	06H/03H	006CH	Auto-light function	0000H: Disabled 0001H: Enabled
50H/20H	06H/03H	006DH	Indication time	Set value
50H/20H			EVT output when input	0000H: Enabled
501/2011	001/0011	007411	errors occur	0001H: Disabled

Shinko Command Type	MODBUS Function Code			Data
50H/20H	06H/03H	0075H	Data clear selection	0000H: Calibration value 0001H: Set value
50H	06H	0076H	Data clear Stop/Perform	0000H: Data clear Stop 0001H: Data clear Perform
50H/20H	06H/03H	0077H		Set value
50H	06H	007FH	clearing	0001H: Clear change flag
50H/20H	06H/03H	0100H	independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0101H	EVT2 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0102H	EVT3 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0103H		Set value (Decimal point ignored.)
50H/20H	06H/03H	0104H	EVT5 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0105H	EVT6 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0106H	EVT1 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0107H		Set value (Decimal point ignored.)
50H/20H	06H/03H	0108H	EVT3 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H		EVT4 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	010AH	EVT5 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	010BH	EVT6 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	010CH	EVT1 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010DH	EVT2 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010EH	EVT3 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010FH	EVT4 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H			Set value (Decimal point ignored.)
50H/20H	06H/03H		·	Set value (Decimal point ignored.)
50H/20H	06H/03H		Transmission output 1 status when calibrating	0000H: Last value HOLD 0001H: Set value HOLD 0002H: Measured value
50H/20H	06H/03H	0113H	Transmission output 1 value HOLD when calibrating	Set value (Decimal point ignored.)
50H/20H	06H/03H	0114H	Transmission output 2 status when calibrating	0000H: Last value HOLD 0001H: Set value HOLD 0002H: Measured value
50H/20H	06H/03H	0115H	Transmission output 2 value HOLD when calibrating	Set value (Decimal point ignored.)
50H/20H	06H/03H	0200H	User save area 1	-32768 to 32767 (8000H to 7FFFH)
50H/20H			User save area 2	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0202H	User save area 3	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0203H	User save area 4	-32768 to 32767 (8000H to 7FFFH)
50H/20H			User save area 5	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0205H	User save area 6	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0206H	User save area 7	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0207H	User save area 8	-32768 to 32767 (8000H to 7FFFH)
50H/20H			User save area 9	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0209H	User save area 10	-32768 to 32767 (8000H to 7FFH)

10.6.3 Read Only Command

10.6.3 Read Shinko Command Type	MODBUS		Data Item		Data
20H	03H	0080H	DO concentration		DO concentration (Decimal point ignored.)
20H	03H	0081H	DO % saturation		DO % saturation (Decimal point ignored.)
20H	03H	0082H	Oxygen partial pressu	re	Oxygen partial pressure (Decimal point ignored.)
		0082H 0083H	Oxygen partial pressur Status flag 1 0000 0000 0000 2 ¹⁵ to 2 ⁰ digit: Outside meas 2 ¹ digit: Outside meas 2 ² digit: Outside meas 2 ³ digit: Outside meas 2 ³ digit: Outside meas 2 ⁴ digit: Outside meas 2 ⁵ digit: Outside meas 2 ⁶ digit: Outside meas 2 ⁶ digit: Outside meas 2 ⁶ digit: Outside meas 2 ⁷ digit: DO Sensor ca 2 ⁸ digit: Unit status flag 2 ¹⁰ , 2 ¹¹ digits: Calibration err 2 ⁹ digit: Unit status flag 0 0 0 0 0 0 0 0 0 1 0 0	D000 2 ⁰ uremen 0: uremen 0: uremen 0: uremen 0: uremen 0: n errors 0: p is not 0: or 0: g 0: ion mode <u>ncentra</u> <u>ncentra</u>	Oxygen partial pressure (Decimal point ignored.) Oxygen partial pressure (Decimal point ignored.) It range of DO concentration (high limit) Normal 1: Error t range of DO concentration (low limit) Normal 1: Error t range of DO % saturation (high limit) Normal 1: Error t range of DO % saturation (low limit) Normal 1: Error t range of DO % saturation (low limit) Normal 1: Error t range of Oxygen partial pressure (high limit) Normal 1: Error t range of Oxygen partial pressure (low limit) Normal 1: Error t have occurred or DO Sensor is not connected. Normal 1: Error attached, or it is incorrectly attached. Normal 1: Error Display Mode 1: Setting mode te status flag
			2 ¹² , 2 ¹³ digits. Calibrat	เปก รเสเ	Status
			0 0 Standb	NV	Status
					t calibration (100% saturation calibration)
					t calibration (0-point calibration)
					tration option calibration
			2 ¹⁴ digit: DO Sensor in 2 ¹⁵ digit: Change in ke	iternal r	nemory deletion 0: No 1: Yes

Shinko Command Type	MODBUS Function Code		Data	a Iten	n	Data
20H	03H	0090H	Temperature	Э		Temperature (Decimal point ignored.)
20H	03H	0091H	Sensor cap	replac	cement timer	Sensor cap replacement timer
			remainder			remaining time
20H	03H	0093H	Status flag 2			
			0000 0000	000	0000 00	
			2 ¹⁵	to	2 ⁰	
			2º digit: Outs	side n		ge of temperature (high limit)
					0: Norm	
			2 ¹ digit: Outs	side n		ge of temperature (low limit)
					0: Norm	
			2 ² digit: EVT			1: ON
			2 ³ digit: EVT			
			2 ⁴ digit: EVT			
			2 ⁵ digit: EVT			
			2 ⁶ digit: EVT 2 ⁷ digit: EVT		•	1: ON 1: ON
					•	
					smission output 1	adjustment status flag
			2 ⁹	2 ⁸		Status
			0	0	Display Mode	
			0	1	-	sion output 1 Zero adjustment
						output 1 adjustment mode
			1	0	-	sion output 1 Span adjustment
					in Transmission	output 1 adjustment mode
			2 ¹⁰ , 2 ¹¹ digits		nsmission output	2 adjustment status flag
			2 ¹¹	2 ¹⁰		Status
			0	0	Display Mode	
			0	1		ission output 2 Zero adjustment
					1	n output 2 adjustment mode
			1	0	-	ission output 2 Span adjustment
					in Transmissior	n output 2 adjustment mode
					ansing status flag	3
			2 ¹³	2 ¹²		Status
			0	0	Display Mode	
			0	1	During cleansin	g inactive interval
			1	0	During cleansin	g time
			1	1	During standby	after cleansing
			2 ¹⁴ , 2 ¹⁵ digit	s: Not	t used (Always 0)	
			¦∠'⁻, ∠'° aigit	5. 1901	usea (Always 0)	

10.7 DO Concentration Calibration by Communication Command

There are 3 calibration methods (like a key operation) for DO concentration calibration via communication: DO concentration 1-point calibration mode, DO concentration 2-point calibration mode, Concentration option calibration mode

10.7.1 Preparation

- (1) Clean the DO Sensor body and measurement section, and remove all moisture.
- (2) Remove the storage cap of the calibration container, and replace with a calibration cap (ventilating cap).



Calibration cap Storage cap (Fig. 10.7.1-1)

- (3) Keep the water, used for DO Sensor and calibration, at room temperature for approx. 30 minutes.
- (4) Select a mode from Sections 10.7.2 (DO Concentration 1-point Calibration Mode), 10.7.3 (DO Concentration 2-point Calibration Mode) and 10.7.4 (Concentration Option Calibration Mode), and perform calibration.

10.7.2 DO Concentration 1-point Calibration Mode

Λ Caution

• If salinity concentration has been previously corrected, return the salinity concentration correction value to 0 PSU, then start calibration.

[Data item 0003H (Salinity correction)]

If calibration is performed with previsously corrected salinity concentration, an error will occur, or calibration will not be performed normally.

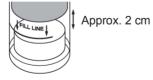
• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

[Data item 0004H (Altitude correction)]

The following outlines calibration procedure.

(1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.

(2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(Fig. 10.7.2-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.

▲ Caution

• Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.

- (4) Set Data item 0005H (DO concentration calibration mode) to 0001H.
 The unit moves to DO concentration 1-point calibration mode.
 If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 01 (DO concentration 1-point calibration mode) will be returned.
- (5) Set Data item 0006H (DO concentration calibration start) to 0001H.
 1-point calibration (100% saturation calibration) starts.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 01 [During 1st-point calibration (100% saturation calibration)] will be returned.
- (6) Set Data item 0006H (DO concentration calibration start) to 0003H.
 The measured value will be fixed, and automatic calibration will be performed.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.
 1-point calibration (100% saturation calibration) is completed.
- (7) Set Data item 0006H (DO concentration calibration start) to 0000H. The unit reverts to DO concentration 1-point calibration mode.
- (8) Set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

If calibration cannot be performed during 1-point calibration (100% saturation calibration) due to unstable DO concentration input or temperature correction error, etc., and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

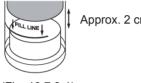
Caution

· When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

[Data item 0004H (Altitude correction)]

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



Approx. 2 cm

(Fig. 10.7.3-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.

Caution

 Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.

- (4) Set Data item 0005H (DO concentration calibration mode) to 0002H. The unit moves to DO concentration 2-point calibration mode. If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 10 (DO concentration 2-point calibration mode) will be returned.
- (5) Set Data item 0006H (DO concentration calibration start) to 0001H. 1st-point calibration (100% saturation calibration) starts. If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 01 [During 1st-point calibration (100%) saturation calibration)] will be returned.
- (6) Set Data item 0006H (DO concentration calibration start) to 0003H. The measured value will be fixed, and automatic calibration will be performed. If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned. 1st-point calibration (100% saturation calibration) is completed.
- (7) Prepare a zero standard solution.

Zero standard solution is 100 mL of ion-exchanged water into which 5 g or more of sodium sulfite has been added and completely dissolved.

(8) Take out the calibration container sponge used for 1st-point calibration, and pour the zero standard solution into the calibration container up to the Fill Line.



(Fig. 10.7.3-2)

(9) Insert the temperature sensor of the DO Sensor until it is immersed in the prepared zero standard solution.

▲ Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section so that air bubbles cannot attach to it.
- (10) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.

(11) Set Data item 0006H (DO concentration calibration start) to 0002H.
2nd-point calibration (0-point calibration) starts.
If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 10 [During 2nd-point calibration (0-point calibration)] will be returned.

(12) Set Data item 0006H (DO concentration calibration start) to 0003H.
The measured value will be fixed, and automatic calibration will be performed.
If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.
2nd-point calibration (0-point calibration) is completed.
2-point calibration (both 100% saturation calibration and 0-point calibration) is completed.

- (13) Set Data item 0006H (DO concentration calibration start) to 0000H. The unit reverts to DO concentration 2-point calibration mode.
- (14) Set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

If calibration cannot be performed during DO concentration 2-point calibration due to unstable DO concentration input or temperature correction error, etc., and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.7.4 Concentration Option Calibration Mode

Immerse the DO Sensor in an aqueous solution (of which DO concentration is known), then the measured value can be matched to the concentration.

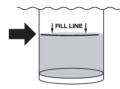
Factory default value: 0.00 mg/L

DO concentration can be set within a range of 0.00 to 20.00 mg/L.

The following outlines calibration procedure.

(e.g.) Setting to a (already-known) concentration of 7.77 mg/L

(1) Pour the already-known concentration solution into the calibration container up to the Fill Line.



(Fig. 10.7.4-1)

(2) Insert the temperature sensor of the DO Sensor until it is immersed in the poured solution.

1 Caution

• Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.

• Insert the measurement section so that air bubbles cannot attach to it.

(3) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.

- (4) Set Data item 0005H (DO concentration calibration mode) to 0003H. The unit moves to Concentration option calibration mode. If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 11 (Concentration option calibration mode) will be returned.
- (5) Set Data item 0007H (Concentration desired value) to the desired value (7.77).
- (6) Set Data item 0006H (DO concentration calibration start) to 0001H. Concentration option calibration starts.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 11 (During concentration option calibration) will be returned.
- (7) Set Data item 0006H (DO concentration calibration start) to 0003H.
 The measured value will be fixed, and calibration will be performed.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.
 Concentration option calibration is completed.
- (8) Set Data item 0006H (DO concentration calibration start) to 0000H. The unit reverts to Concentration option calibration mode.
- (9) Set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

If errors occur during concentration option calibration, and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.8 Transmission Output 1 and 2 Adjustment

10.8.1 Transmission Output 1 Adjustment Mode

Fine adjustment of Transmission output 1 is performed.

WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and the output value of this unit. In this case, perform Transmission output 1 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 1 adjustment.

- (1) Set Data item 000EH (Transmission output 1 adjustment mode) to 0001H. The unit moves to Transmission output 1 Zero adjustment mode. If 2⁹, 2⁸ digits are read at Data item 0093H (Status flag 2), 01 (During Transmission output 1 Zero adjustment in Transmission output 1 adjustment mode) will be returned.
- (2) Set Transmission output 1 Zero adjustment value at Data item 000FH (Transmission output 1 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (3) Set Data item 000EH (Transmission output 1 adjustment mode) to 0002H.
 The unit moves to Transmission output 1 Span adjustment mode.
 If 2⁹, 2⁸ digits are read at Data item 0093H (Status flag 2), 10 (During Transmission output 1 Span adjustment in Transmission output 1 adjustment mode) will be returned.
- (4) Set Transmission output 1 Span adjustment value at Data item 0010H (Transmission output 1 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (5) Repeat steps (1) to (4) if necessary.
- (6) Set Data item 000EH (Transmission output 1 adjustment mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.8.2 Transmission Output 2 Adjustment Mode

Fine adjustment of Transmission output 2 is performed. WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and the output value of this unit. In this case, perform Transmission output 2 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 2 adjustment.

- (1) Set Data item 0011H (Transmission output 2 adjustment mode) to 0001H. The unit moves to Transmission output 2 Zero adjustment mode. If 2¹¹, 2¹⁰ digits are read at Data item 0093H (Status flag 2), 01 (During Transmission output 2 Zero adjustment in Transmission output 2 adjustment mode) will be returned.
- (2) Set Transmission output 2 Zero adjustment value at Data item 0012H (Transmission output 2 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (3) Set Data item 0011H (Transmission output 2 adjustment mode) to 0002H. The unit moves to Transmission output 2 Span adjustment mode.
 If 2¹¹, 2¹⁰ digits are read at Data item 0093H (Status flag 2), 10 (During Transmission output 2 Span adjustment in Transmission output 2 adjustment mode) will be returned.
- (4) Set Transmission output 2 Span adjustment value at Data item 0013H (Transmission output 2 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (5) Repeat steps (1) to (4) if necessary.
- (6) Set Data item 0011H (Transmission output 2 adjustment mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.9 Notes on Programming Monitoring Software

10.9.1 How to Speed up the Scan Time

When monitoring multiple units of WIL-102-DO, set the program so that the requisite minimum pieces of data such as Data item 0080H (DO concentration), Data item 0090H (Temperature), Data item 0083H (Status flag 1), Data item 0093H (Status flag 2) can be read. For other data, set the program so that they can be read only when their set value has been changed. This will speed up the scan time.

10.9.2 How to Read the Set Value Changes Made by the Front Keypad Operation

If any set value is changed by keypad operation, the WIL-102-DO will set [0083H (Status flag 1) 2¹⁵: Change in key operation] to 1 (Yes).

There are 2 methods of reading the set value changes made by the front keypad.

(1) Reading method 1

- ⁽¹⁾ On the monitoring software side, check that [0083H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then read all set values.
- Clear the [0083H (Status flag 1) 2¹⁵: Change in key operation], by setting Data item 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
 If [007FH (Key operation change flag clearing)] is set to [Clear change flag (0001H)] during setting mode of this instrument, Error code 5 (35H, Shinko protocol) or Exception Code 18 (12H,

MODBUS protocol) will be returned as a negative acknowledgement. And [0083H (Status flag 1) 2¹⁵: Change in key operation] cannot be cleared.

- Set a program so that all set values can be read when a negative acknowledgement is returned.
- ③ Read all set values again after acknowledgement is returned.

(2) Reading method 2

- ⁽¹⁾ On the monitoring software side, check that [0083H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then set 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
- ⁽²⁾ Set the program depending on acknowledgement or negative acknowledgement as follows. When acknowledgement is returned:

Consider it as settings completed, and read all set values.

When Error code 5 (35H, Shinko protocol) or Exception code 18 (12H, MODBUS protocol) is returned as a negative acknowledgement:

Consider it as still in setting mode, and read the requisite minimum pieces of data such as 0080H (DO concentration), 0090H (Temperature), 0083H (Status flag 1), 0093H (Status flag 2), then return to step 1.

Thus, programs which do not affect the scan time can be created using the methods described above, even if set values on the monitoring software will not be updated until settings are complete.

10.9.3 Note when sending all set values at one time

 If EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 type is changed at Data items 0014H (EVT1 type), 0022H (EVT2 type), 0030H (EVT3 type), 003EH (EVT4 type), 004CH (EVT5 type) or 005AH (EVT6 type), the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 value will default to 0 (zero).
 Output status of EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 will also be initialized.

First, send the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 type, then send the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 value set at Data items 0015H (EVT1 value), 0023H (EVT2 value), 0031H (EVT3 value), 003FH (EVT4 value), 004DH (EVT5 value) or 005BH (EVT6 value).

11. Specifications

11.1 Specification of WIL-102-DO

11.1.1 Standard Specifications

Rating

anng							
Rated scale	Input		Input Range		Resolution		
	DO concentration		0.00 to 20.0	0 mg/L		0.01 mg/L	
	DO % saturation		0.0 to 200.0	%		0.1%	
	Oxygen partial pressure		0.0 to 150.0 kPa		0.1 kPa		
	Temperature		0.0 to 50.0℃			0.1℃	
Input	Optical DO Sensor						
Power supply	Model		WIL-102-I	00	W	/IL-102	-DO 1
	Power supply 100		to 240 V AC	50/60 Hz	24 V A	C/DC	50/60 Hz
	Allowable voltage 85 to		o 264 V AC		20 to 2	28 V AC	C/DC
	fluctuation range	fluctuation range					

General Structure

External dimensions	30 x 88 x 108 mm (W x H x D, including socket)		
Mounting	DIN rail		
Case	Material: Flame-resist	tant resin, Color: Light gray	
Front panel	Membrane sheet		
Indicating structure	Display		
	DO Display	Red LED 4-digits	
		Character size: 10 x 4.6 mm (H x W)	
	Temperature Display	Red LED 4-digits	
	Character size: 10 x 4.6 mm (H x W)		
	Action indicators		
	PWR (Yellow)	Instrument Power ON: Lit	
	A1 (Red)	EVT1 output (Contact output 1) ON: Lit	
	A2 (Yellow)	EVT2 output (Contact output 2) ON: Lit	
	T/R (Yellow)	Serial communication TX output (transmitting): Lit	
Setting structure	Setting method: Input system using membrane sheet key		

Indication Performance

Indication accuracy	Depends on the accuracy of the Optical DO Sensor.	
Time accuracy	Within ±1% of setting time	
Data update cycle	5 seconds	

Standard Function

	dard Function					
С	alibration	DO concentration 1-point calibration, DO concentration 2-point calibration,				
		Concentration option calibration				
Si	gnal output response					
tir	ne	the resulting value	e is updated every Data update cycle (5 seconds) as a			
		measurement value. However, signal output response time will be				
		invalidated during DO concentration calibration mode, Transmission output 1				
		or 2 adjustment mode.				
Tr	ansmission output 1	Converts any one of	of – DO concentration, water temperature, DO %			
		saturation, or Oxygen partial pressure – to an analog signal every update				
		cycle, and outputs	in current.			
		If Transmission ou	tput 1 high limit and low limit are set to the same value,			
		Transmission outp	ut 1 will be fixed at 4 mA DC.			
		Resolution	12000			
		Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)			
		Output				
		accuracy	Within ±0.3% of Transmission output 1 span			
	Transmission output		the Transmission output 1 is performed via			
	1 adjustment		ut 1 Zero and Span adjustments.			
	Transmission	Selects Transmiss	ion output 1 output status when calibrating DO			
	output 1 status	concentration.				
when calibrating		Last value HOLD	Retains the last value before DO concentration			
			calibration, and outputs it.			
		Set value HOLD	Outputs the value set in [Transmission output 1 value HOLD when calibrating].			
		Measured value	Outputs the measured value when calibrating			
			DO concentration.			
Tr	ansmission output 2		of – DO concentration, water temperature, DO %			
		saturation, or Oxygen partial pressure – to an analog signal every update				
		cycle, and outputs in current.				
		If Transmission output 2 high limit and low limit are set to the same value,				
		Transmission outp	ut 2 will be fixed at 4 mA DC.			
		Resolution	12000			
		Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)			
		Output accuracy	Within $\pm 0.3\%$ of Transmission output 2 span			
	Transmission output		the Transmission output 2 is performed via			
2 adjustment		Transmission output 2 Zero and Span adjustments.				
Transmission output		Selects Transmission output 2 output status when calibrating DO				
	2 status when	concentration.				
	calibrating	Last value HOLD	Retains the last value before DO concentration			
			calibration, and outputs it.			
		Set value HOLD	Outputs the value set in [Transmission output 2 value			
			HOLD when calibrating].			
		Measured value	Outputs the measured value when calibrating			
			DO concentration.			

EVT output						
Contact output)						
Action	ON/OFF cont	ol action				
EVT ON side	DO concentra		0.00 to 4.00 mg/L			
EVT OFF side	Water temper	-	0.0 to 10.0℃			
	DO % saturat	•	0.0 to 40.0%			
		•	ut: 0.0 to 30.0 kPa			
	DO concentra					
EVT High/Low	Water temper		0.00 to 20.00 mg/L 0.0 to 50.0℃			
limits independent			0.0 to 200.0%			
upper side value,	DO % saturat					
EVT High/Low	Oxygen partia	i pressure inp	ut: 0.0 to 150.0 kPa			
limits independent						
lower side value	DO constantas	41 1 4-	0.04 to 0.00 mm m/l			
EVT hysteresis	DO concentra	-	0.01 to 2.00 mg/L			
	Water temper		1.0 to 5.0°C			
	DO % saturat		0.1 to 20.0%			
			ut: 0.1 to 15.0 kPa			
Туре	Selectable by	keypad operat	ion			
	• No action					
	DO concentration input high limit action					
	DO concentration input low limit action					
	Water temperature input high limit action					
	 Water temperature input low limit action DO % saturation input high limit action 					
	DO % saturation input low limit action DO % saturation input low limit action					
	Oxygen partial pressure input high limit action					
	Oxygen partial pressure input low limit action					
	Sensor cap r					
	Self-check or					
		Cleansing output				
	DO concentration input High/Low limits independent action					
			gh/Low limits independent action			
	• DO % saturation input High/Low limits independent action					
	Oxygen partial pressure input High/Low limits independent action					
Output	Relay contact					
	Control		(resistive load)			
	capacity	1 A 250 V AC	; (inductive load $\cos\phi$ =0.4)			
	Electrical life	100,000 cycl	es			
EVT ON delay	0 to 9999 sec					
time						
EVT OFF delay	0 to 9999 sec	onds				
time						
Output ON Time/			set, the output can be turned ON/OFF in a			
OFF Time when	configured cyc	le when EVT	∃ output is ON.			
EVT Output ON						
Sensor cap			urned ON after sensor cap replacement timer			
replacement timer			ap replacement timer remainder is "0").			
output			value and $\Gamma \subset \overline{BP}$ are alternately indicated			
	on the DO Dis	play.				

Self-check output	The selected E	/T output is t	urned ON for the followir	ng errors	
			mmunication errors have		
		ensor is not			
	Err2 D	O Sensor ca	p is not attached, or it is	incorrectly attached.	
			or (If input errors have oc		
			not be performed 30 mir	nutes after starting	
		alibration)			
			ernal memory deletion.		
			en Quality ID3 is received	d from the DO Sensor.	
Cleansing output	Cleansing Output Mode: After 'Cleansing inactive interval' has elapsed, the selected EVT out turned ON during the preset 'Cleansing time'.			selected EVT output is	
	After 'Standby a While cleansing after cleansing',	After 'Standby after cleansing' has passed, the above action is repeated. While cleansing is being performed using 'Cleansing time' and 'Standby after cleansing', other outputs are in OFF status.			
	pressure, water	temperature			
	Perform'.		will be performed, ex		
	When power is Forced Cleans		gain, starts from 'Cleansi	ng inactive interval'.	
	By pressing the cleansing mode	key for In Forced c	approx. 3 seconds, the i leansing mode, cleansin y after cleansing'.	unit enters Forced g is performed using	
			hed, the unit automatica	lly reverts to Cleansing	
	This mode will not be accessible by the stars key if programmed cleansing is currently being performed.				
			de, if programmed clean	sing action initiates	
			val' has passed, the prog	grammed cleansing	
			n the current session.		
Serial communication			n be carried out from an e arious set values	external computer.	
			entration, DO % saturation	on, Oxygen partial	
	pressure, ter				
	(3) Function cha				
	(4) Reading and	setting of us	ser save area		
Cable length			nce: Within 50 Ω (Termi 20 Ω minimum on both		
Communicationl line	EIA RS-485	i useu, use i		sides.)	
Communication method					
Communication speed			lectable by keypad)		
Synchronization method		ronization			
Code form	ASCII, Binary				
Communication protocol	•		SCII, MODBUS RTU (S	5 51 7	
Data bit/Parity	8 bits/No parity, 7 bits/No parity, 8 bits/Even, 7 bits/Even, 8 bits/Odd, 7 bits/Odd (Selectable by keypad)				
Stop bit	1 bit, 2 bits (Selectable by keypad)				
Error correction	Command reque	est repeat sy	stem		
Error detection	Parity check, Checksum (Shinko protocol), LRC (MODBUS protocol ASCII), CRC-16 (MODBUS protocol RTU)				
	CRC-16 (MODP	0000000000000			
Data format		Shinko		MODBUS	
Data format	CRC-16 (MODE Communication Protocol		MODBUS ASCII	MODBUS RTU	
Data format	Communication	Shinko	MODBUS		
Data format	Communication Protocol	Shinko Protocol	MODBUS ASCII	RTU	
Data format	Communication Protocol Start bit	Shinko Protocol 1	MODBUS ASCII	RTU	

Insulation, Dielectric Strength

isulation, Dielectric Stre	
Circuit insulation configuration	EVT1 EVT2 Transmission Output 1 Power circuit
	CPU Electrically insulated
	Sensor Input RS-485 Serial communication RS-485 EVT3 EVT4 EVT5 EVT6
	EVT option
	Insulation Resistance: 10 M Ω minimum, at 500 V DC
Dielectric strength	Power terminal – ground (GND): 1.5 kV AC for 1 minute Input terminal – ground (GND): 1.5 kV AC for 1 minute
	Input terminal – power terminal: 1.5 kV AC for 1 minute

Attached Function

		emeasurement range	e, the following will be
Input		DO Display	Temperature Display
DO concentration	Flashes	at 20.00 or 0.00.	Measured value
DO % saturation	Flashes	at 200.0 or 0.0.	Measured value
Oxygen partial Flashes at 150.0 or 0.0. pressure		Measured value	
Temperature Measured value Flashes at			Flashes at 50.0 or 0.0.
The setting data is backed up in the non-volatile IC memory.			C memory.
The CPU is monitored by a watchdog timer, and if an abnormal status occurs, the WIL-102-DO is switched to warm-up status.			
For approx. 8 seco	nds after	the power is switche	ed ON, characters below
are indicated on the	e DO Dis	play and Temperature	e Display.
Display			ontents
DO Display			
Temperature Displa	ay	🗌 / 🖓 [Version nu	mber (e.g.) 1.00]
If no operation occurs for the duration of the previously set indication time,			
the displays will go off.			
By pressing any key, the display re-lights. If the Indication time is set to			
00.00, the displays remain lit, and this function is disabled.			
Automatically measures and controls brightness of the DO Display,			
Temperature Displa	ay and ac	tion indicators.	
	Lock 2: Only EVT1 Lock 3: All set value However, th off because If inputs (DO conce Temperature) are of indicated. DO concentration DO % saturation Oxygen partial pressure Temperature The setting data is The CPU is monit occurs, the WIL-10 For approx. 8 seco are indicated on th Display DO Display Temperature Displa If no operation occ the displays will go By pressing any ke 00.00, the displays	Lock 2: Only EVT1 to EVT6 v Lock 3: All set values can be However, they revert off because they are off lf inputs (DO concentration, Temperature) are outside the indicated. DO concentration Flashes DO % saturation Flashes Oxygen partial pressure Flashes Oxygen partial pressure Flashes Temperature Measure The setting data is backed u The CPU is monitored by occurs, the WIL-102-DO is s For approx. 8 seconds after are indicated on the DO Dis Display DO Display Temperature Display If no operation occurs for th the displays will go off. By pressing any key, the dis 00.00, the displays remain lii Automatically measures and	InputDO DisplayDO concentrationFlashes at 20.00 or 0.00.DO % saturationFlashes at 200.0 or 0.0.DXygen partial pressureFlashes at 150.0 or 0.0.TemperatureMeasured valueThe setting data is backed up in the non-volatile IThe CPU is monitored by a watchdog timer, a occurs, the WIL-102-DO is switched to warm-upFor approx. 8 seconds after the power is switche are indicated on the DO Display and TemperatureDO DisplaydaTemperature DisplayUDD [Version nuIf no operation occurs for the duration of the pre the displays will go off.By pressing any key, the display re-lights. If the Ir 00.00, the displays remain lit, and this function is

Error indication	Error Code	Description	Occur- rence
	ErrO	Non-volatile IC memory error	Constantly
	Errl	DO Sensor communication errors have occurred, or DO Sensor is not connected. After a command is sent to the DO Sensor, if there is no response for 500 ms, the command will be sent again. If no response occurs 4 times consecutively, this error code will be indicated. If communication status returns to normal, the unit will automatically return to normal status. When this error code is displayed, the previous measured value is retained.	When measuring and calibrating
	Err2	DO Sensor cap is not attached, or it is incorrectly attached.	
	Err3	Calibration error (when input errors have occurred, or when calibration cannot be performed 30 minutes after starting calibration)	When calibrating
	Erry	DO Sensor internal memory deletion. Displayed when Quality ID3 is received from the DO Sensor.	When measuring and calibrating

Other

Approx. 10 VA
0 to 50°C
35 to 85 %RH (Non-condensing)
Approx. 200 g (including socket)
RoHS directive
Unit label: 1 sheet
Instruction manual: 1 copy
Wire harness WJ (3 m): 4 lengths (when the EVT option is ordered)
Socket ASK-001-1 (Finger-safe, terminal screw fall prevention)

11.1.2 Optional Specifications

EVT Output (Option Code: EVT)

- 2					
	EVT output	Same as standard EVT except the 'output'.			
	Output	Open collector			
		Control capacity 0.1 A 24 V DC			

11.2 DO Sensor Specifications

Model	DOS-20		
Power supply	12 to 36 V DC		
Sensor cap	One (1) year after installing the DO Sensor (Recommended)		
replacement frequency			
Sensor cap storage	Two (2) years from the date of manufacture (When storing in the		
period	designated container)		
	Storage temperature: 1 to 60℃		
Measuring water	0 to 50°C (Not freezing)		
temperature			
Material	ABS		
External dimensions	Approx. <i>Φ</i> 44 x 203 mm		
Weight	Approx. 850 g (including 10 m cable)		
Degree of protection	IP68 (Underwater type, maximum depth of 200 m)		
Accessories sold	DO Sensor attachment: DA-1		
separately	Sensor cap for replacement: DOS-CP		
	Stanchion pole: PS-1		
	Fixing bracket for stanchion pole: PS-TK		

12. Troubleshooting

Error codes and solutions to problems are described below.

12.1 Error Codes

Error Code	Description	
ErrO	Non-volatile IC memory error	Constantly
Err I Err2	DO Sensor communication errors have occurred, or DO Sensor is not connected. After a command is sent to the DO Sensor, if there is no response for 500 ms, the command will be sent again. If no response occurs 4 times consecutively, this error code will be indicated. If communication status returns to normal, the unit will automatically return to normal status. When this error code is displayed, the previous measured value is retained. DO Sensor cap is not attached, or it is incorrectly attached.	When measuring and calibrating
Err3	Calibration error (when input errors have occurred, or when calibration cannot be performed 30 minutes after starting calibration)	When calibrating
Erry	DO Sensor internal memory deletion. Displayed when Quality ID3 is received from the DO Sensor.	When measuring and calibrating

12.2 Solutions to Problems

If any malfunction occurs, refer to the following items after checking that power is being supplied to the WIL-102-DO.

12.2.1 Indication

Problem	Possible Cause	Solution
The DO Display/	The time set in [Indication time (p.34)]	If any key is pressed while displays
Temperature Display	has passed.	are unlit, it will re-light.
are unlit.		Set the Indication time to a suitable
	· · · · · · · · · · · · · · · · · · ·	time-frame.
The DO Display/	$U \neg E$ (Enabled) is selected in	Select (Disabled).
Temperature Display	[Auto-light function (p.34)].	
are dark.		
Indication of the DO	DO concentration calibration may not	Perform DO concentration
Display/Temperature	have finished.	calibration.
Display is unstable or	Specification of DO Sensor may not	Replace the sensor with a suitable
irregular.	be suitable.	one.
	There may be equipment that	Keep WIL-102-DO clear of any
	interferes with or makes noise near	potentially disruptive equipment.
	the WIL-102-DO.	
Err / is flashing	DO Sensor communication errors	Turn the power OFF, and check the
on the Temperature	have occurred, or the DO Sensor is	wiring of the DO Sensor.
Display.	not connected.	If the DO Sensor is malfunctioning,
		repair or replace the sensor.
Errd is flashing	This occurs when DO Sensor cap is	For correct attachment, refer to
on the Temperature	not attached, or when it is incorrectly	Section "4.4 Attaching the Sensor
Display.	attached.	Cap" (p.13).

Problem	Possible Cause	Solution
E ー ー ヨ is flashing on the Temperature Display.	Calibration error	Remove dirt or air bubbles from the measurement section, and calibrate again. If errors occur again, repair or replace the DO Sensor. If salinity concentration correction has been performed, return the salinity concentration correction value to 0 PSU, and calibrate again.
$\mathcal{E} \vdash \vdash \overline{G}$ is flashing on the Temperature Display.	Internal memory is defective.	Contact our agency or us.

12.2.2 Key Operation

Problem	Possible Cause	Solution
Unable to set values. The values do not change by △, ▽ keys.	とロこ / (Lock 1) is selected in [Set value lock (p. 34)].	Select (Unlock).
Settings are impossible except EVT value. The values do not change by (), () keys	レロロピ (Lock 2) is selected in [Set value lock (p. 34)].	Select (Unlock).
Unable to enter Forced cleansing mode.	cLEL (Cleansing output) is not selected in any of [EVT1 to EVT6 types (pp. 26, 31)].	Select <i>こととじ</i> (Cleansing output) in any of [EVT1 to EVT6 types (pp. 26, 31)].
	Cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.	Execute Forced cleansing after cleansing action is completed.
Unable to enter a calibration mode.	とっこ / (Lock 1), とっこご (Lock 2) or とっこう (Lock 3) has been selected in [Set value lock (p.34)].	Select (Unlock).
	<i>cLEL</i> (Cleansing output) has been selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.	Perform calibration after cleansing action is completed.

12.2.3 Communication

Check that power is being supplied to the master and slave that customers use. If communication failure still occurs, check the following.

Problem	Possible Cause	Solution
Communication failure	Communication cable is not securely connected, or is disconnected/ defective.	Check the communication cable and connector.
	Incorrect wiring of the communication cable and/or connector	Check the communication cable and connector.
	Imperfect contact between the communication cable and the connector, or between the communication connector and instrument port	Check the communication cable and connector.
	Communication speed of the slave does not match that of the master.	Check the communication speed of the slave and master.
	The data bit, parity and stop bit of the master do not correspond to those of the slave.	Check the data bit, parity and stop bit of the master and the slave.
	The instrument number (address) of the slave does not correspond to that of the command.	Check the instrument number (address) of the slave.
	The instrument numbers (addresses) are duplicated in multiple slaves.	Check the instrument numbers (addresses) of the slave.
	Make sure that the program is appropriate for the transmission timing.	Check the program.
Although communica- tion is occurring, the	A non-existent command code has been sent.	Check the command code.
response is negative acknowledgement.	The setting command data exceeds the setting range of the slave.	Check the setting range.
	The WIL-102-DO cannot be set while calibration is being performed.	Check the slave status.
	The WIL-102-DO is in front keypad operation setting mode.	Return the unit to Display Mode or Cleansing Output Mode.

13. Character Tables

The following shows our character tables. Use data column for your reference.

Setting Groups

tting Groups	
Character	Setting Group
F.nc	DO Concentration Input Group
Г.г.а. I	Transmission Output 1 Group
Г	Transmission Output 2 Group
	EVT1 Action Group
E.H.T.2	EVT2 Action Group
E.H.T.3	EVT3 Action Group (*)
E.H.T.H	EVT4 Action Group (*)
E.H.T.S	EVT5 Action Group (*)
E.H.T.B	EVT6 Action Group (*)
	Communication Group
<i>c.L.E.G</i>	Cleansing Group
	Basic Function Group
5.E.F	Self-Check Group
	Data Clear Group

(*) Available only when EVT output (EVT option) is ordered.

DO Concentration Calibration

Character	Setting Item, Setting Range	Factory Default	Data
Measured	DO concentration 1-point calibration		
value (*)	mode		
Measured	DO concentration 2 point calibration		
value (*)	DO concentration 2-point calibration mode		
	linde		
cRdF	Concentration option calibration	0.00 mg/L	
Concentration	mode		
desired value	Setting range: 0.00 to 20.00 mg/L		

(*) DO concentration measured value flashes.

Transmission Output 1 Adjustment

Character	Setting Item, Setting Range	Factory Default	Data
RJEI	Transmission output 1 Zero	0.00 mg/L	
<u> </u>	adjustment		
	Setting range: ±5.00% of Transmission	n output 1 span	
8ปร (Transmission output 1 Span	0.00 mg/L	
000	adjustment		
	Setting range: ±5.00% of Transmission output 1 span		

Transmission Output 2 Adjustment

Character	Setting Item, Setting Range	Factory Default	Data
RJEZ	Transmission output 2 Zero	0.00 mg/L	
	adjustment		
	Setting range: ±5.00% of Transmission	n output 2 span	
RJ-52	Transmission output 2 Span	0.00 mg/L	
000	adjustment		
	Setting range: ±5.00% of Transmission	n output 2 span	

DO Concentration Input Group

Character	Setting Item, Setting Range	Factory Default	Data
dFcT	Signal output response time	60 seconds	
<u> </u>	Setting range: 5 to 600 seconds		
5 <i>8LT</i>	Salinity correction	0 PSU	
	Setting range: 0 to 42 PSU		
5E8L	Altitude correction	0 m	
	Setting range: 0 to 5000 m		

Transmission Output 1 Group

Character	Setting Item, Setting Range	Factory Default	Data
Fro I	Transmission output 1 type	DO concentration transmission	
do	ದೆದ್ದ : DO concentration transmissio	n	
	<i> </i>	on	
	ゴローデ : DO % saturation transmission		
	<i>「テート</i> : Oxygen partial pressure trans	mission	
[F-H	Transmission output 1 high limit	20.00 mg/L	
2000	Setting range:		
	Transmission output 1 low limit to Mea	surement range high limit	
	Transmission output 1 low limit	0.00 mg/L	
	Setting range:		
	Measurement range low limit to Trans	mission output 1 high limit	
Fre I	Transmission output 1 status	Last value HOLD	
68FH	when calibrating		
	bEFH: Last value HOLD (Retains the	last value before calibrating DO	
	concentration, and outputs it.)	velue est in Elementicaien sutruit	
	<i>与EFH</i> : Set value HOLD (Outputs the v 1 value HOLD when calibrating	-	
	PBH Measured value (Outputs the r		
	DO concentration.)	nedeared value when calibrating	
5-51	Transmission output 1 value HOLD	0.00 mg/L	
<i>000</i>	when calibrating	Ŭ	
	Setting range:		
	Measurement range low limit to Measu	irement range high limit	

Transmission Output 2 Group

Character	Setting Item, Setting Range	Factory Default	Data
[ro2	Transmission output 2 type	DO concentration transmission	
do	ದೆದ್ದ : DO concentration transmissio	n	
	آرت آ 🖓 : Water temperature transmissi	on	
	ゴローデ : DO % saturation transmissior	1	
	<i>ふアート</i> : Oxygen partial pressure trans	mission	
FrH2	Transmission output 2 high limit	20.00 mg/L	
2000	Setting range:		
	Transmission output 2 low limit to Mea	surement range high limit	
FrL2	Transmission output 2 low limit	0.00 mg/L	
000	Setting range:		
	Measurement range low limit to Trans	mission output 2 high limit	
[re2	Transmission output 2 status	Last value HOLD	
6EFH	when calibrating		
	bEFH: Last value HOLD (Retains the	last value before calibrating DO	
	concentration, and outputs it.)		
	<i>与EFH</i> : Set value HOLD (Outputs the v		
	2 value HOLD when calibrating		
	PBH: Measured value (Outputs the measured value when calibrating DO concentration.)		
5-52	Transmission output 2 value HOLD	0.00 mg/L	
	when calibrating	······································	
	Setting range:		
	Measurement range low limit to Measu	rement range high limit	

EVT1 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
EFF	EVT1 type	No action	
	: No action		
	da_H : DO concentration input high limit action		
	$da_{-}L$: DO concentration input low		
	<i> [「] ー ー ー ー ー ー ー ー ー ー ー ー ー ー ー ー ー ー ー</i>		
	「「ここ」: Water temperature input lo	•	
	ゴローイ : DO % saturation input high		
	ゴローL : DO % saturation input low		
	$\vec{\omega}\vec{P}\vec{-H}$: Oxygen partial pressure in		
	$\vec{u}\vec{r}\vec{-}\vec{L}$: Oxygen partial pressure in		
	$\mathcal{F} \subset \mathcal{BP}$: Sensor cap replacement ti		
	Sensor cap replacement in Sensor cap replace		
	= LEE : Cleansing output		
	ー ビビン : Oleansing output ー ゴロイン : DO concentration input Hi	ah/Low limits independent action	
	$\Gamma \overline{\alpha} H L$: Water temperature input H		
		•	
	$\vec{a}' \vec{H}'_{L}$: DO % saturation input High/Low limits independent action $\vec{a}PH'_{L}$: Oxygen partial pressure input High/Low limits independent		
	action		
58 / C	EVT1 value (*1) DO	concentration input: 0.00 mg/L	
		ter temperature input: 0.0°C	
	DO	% saturation input: 0.0%	
	Oxy	gen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 20.00 mg/L		
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 200.0%		
di F i	Oxygen partial pressure input: 0.0 to		
531 F	EVT1 hysteresis type (*2) こばド : Medium Value	ference Value	-
1011	ーロート Medium Value		
dFo I		concentration input: 0.01 mg/L	
 I		ter temperature input: 1.0°C	
:; { }		% saturation input: 0.1%	
		ygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00 mg/L]
	Water temperature input: 0.0 to 10.0℃		
	DO % saturation input: 0.0 to 40.		
dFU I	Oxygen partial pressure input: 0.0 to		
0-0 / 00 /	EVT1 OFF side (*3)	concentration input: 0.01 mg/L ter temperature input: 1.0°C	
		% saturation input: 0.1%	
		ygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.		1
	Water temperature input: 0.0 to 10.		
	DO % saturation input: 0.0 to 40.		
	Oxygen partial pressure input: 0.0 to	o 30.0 kPa	

(*1) If (No action), $\mathcal{F}_{\mathcal{L}}\mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEL} (Cleansing output) is selected in [EVT1 type], this setting item and all subsequent items will not be available.

(*2) Not available if daHL (DO concentration input High/Low limits independent action), FaHL (Water temperature input High/Low limits independent action), d'HL (DO % saturation input High/Low limits independent action) or $\tilde{a}PHL$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT1 type].

Setti	ON delay time ing range: 0 to 9999 second	0 seconds	
<i>₀₣Г \</i> ЕVT 1	ing range: 0 to 9999 second		
		Setting range: 0 to 9999 seconds	
	OFF delay time	0 seconds	
Sett	ing range: 0 to 9999 second	ls	
	t ON Time when EVT1	0 seconds	
Outpu	t ON		
	ing range: 0 to 9999 second	ls	
	t OFF Time when EVT1	0 seconds	
Outpu			
	ing range: 0 to 9999 second		
	High/Low limits	DO concentration input: 0.00 mg/L	
	endent lower side value	Water temperature input: 0.0℃	
(*)		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	concentration input: 0.00 f		
	er temperature input: 0.0 to % saturation input: 0.0 to	200.0%	
	gen partial pressure input: 0		
	High/Low limits	DO concentration input: 0.00 mg/L	
	endent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
		to 20.00 mg/L	
	er temperature input: 0.0 to		
		200.0%	
	gen partial pressure input: 0		
EHY / EVT1	hysteresis	DO concentration input: 0.01 mg/L	
		Water temperature input: 1.0℃ DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
00	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0%		
Oxy	gen partial pressure input: 0).1 to 15.0 kPa	

EVT2 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
EFF2	EVT2 type	No action	
[-]-]-]-]	I No action		
	da_H : DO concentration input high limit action		
	$da_{-}L$: DO concentration input low li		
	ゴー ー · · Water temperature input high		
	レーデー: Water temperature input low		
	리고 기관 : DO % saturation input high li		
	ゴロトム : DO % saturation input low lir		
	$\vec{\omega}\vec{P}\vec{-H}$: Oxygen partial pressure input		
	$\vec{\omega}\vec{r}$ - \vec{L} : Oxygen partial pressure input	-	
	$\Gamma \subseteq \exists P$: Sensor cap replacement time		
	っという Sensor cap replacement time	51	
	= LEG : Cleansing output		
	ビビビ Cleansing output ゴロビビ : DO concentration input High	/I ow limits independent action	
	「こうけん」: Do concentration input high		
	$d' \neg H'_L$: DO % saturation input High/Low limits independent action $\vec{L}PH'_L$: Oxygen partial pressure input High/Low limits independent		
	action		
5 <i>82</i>	EVT2 value (*1) DO c	oncentration input: 0.00 mg/L	
000		temperature input: 0.0°C	
	DO %	saturation input: 0.0%	
	Охуд	en partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 20.00 mg/L		
		Water temperature input: 0.0 to 50.0°C	
	DO % saturation input: 0.0 to 200.0%		
di F2	Oxygen partial pressure input: 0.0 to		
531 F	EVT2 hysteresis type (*2) c cli F : Medium Value	ence Value	-
1011	ー Control Medium Value		
dFo2		oncentration input: 0.01 mg/L	
		r temperature input: 1.0°C	
		saturation input: 0.1%	
		en partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00 mg/L		
	Water temperature input: 0.0 to 10.0°C		
	DO % saturation input: 0.0 to 40.09		
1-1-1	Oxygen partial pressure input: 0.0 to 3		
3FU2 00 I		oncentration input: 0.01 mg/L r temperature input: 1.0℃	
		saturation input: 0.1%	
		en partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00		1
	Water temperature input: 0.0 to 10.0%		
	DO % saturation input: 0.0 to 40.0%	6	
	Oxygen partial pressure input: 0.0 to 3	0.0 kPa	

(*1) If (No action), $\mathcal{F} \subset \mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEG} (Cleansing output) is selected in [EVT2 type], this setting item and all subsequent items will not be available.

(*2) Not available if daHL (DO concentration input High/Low limits independent action), FaHL (Water temperature input High/Low limits independent action), d'HL (DO % saturation input High/Low limits independent action) or $\tilde{a}PHL$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT2 type].

Character	Setting Item, Setting Range	Factory Default	Data
onf2	EVT2 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF2	EVT2 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon2	Output ON Time when EVT2	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
oof2	Output OFF Time when EVT2	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_LZ	EVT2 High/Low limits	DO concentration input: 0.00 mg/L	
000	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00		
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
E_H2	EVT2 High/Low limits	DO concentration input: 0.00 mg/L	
	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00	to 20.00 mg/L	
	Water temperature input: 0.0 to		
		200.0%	
	Oxygen partial pressure input: (
EH92	EVT2 hysteresis	DO concentration input: 0.01 mg/L	
00 I		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0% Oxygen partial pressure input: 0.1 to 15.0 kPa		
		on and ant action) $\nabla = \Psi^{\dagger}$ (Water temperature in	

EVT3 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
ELEB	EVT3 type	No action	
	: No action		
	$da_{-}H$: DO concentration input high limit action		
	$da_{-}L$: DO concentration input low limit action		
	ゴー 市H : Water temperature input hig		
	レデート: Water temperature input lov		
	d = -H : DO % saturation input high limit action		
	ゴローム : DO % saturation input low I		
	$\vec{\omega}\vec{r}$ - \vec{H} : Oxygen partial pressure inp		
	$\vec{\omega}\vec{r}$ - \vec{L} : Oxygen partial pressure inp		
	$\Gamma \subseteq RP$: Sensor cap replacement tin		
	Sensor cap replacement un Self-check output		
	= LED : Cleansing output		
	ビビビ Cleansing output ゴロイン: DO concentration input Hig	b/Low limits independent action	
	「ころん」: DO concentration input Hig 「ころん」: Water temperature input Hi		
	ゴーデム: DO % saturation input High	•	
	$\vec{a}PHL$: Oxygen partial pressure in	-	
	action	sur righteow innus independent	
583		concentration input: 0.00 mg/L	
		er temperature input: 0.0°C	
		% saturation input: 0.0%	
		gen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 20.		
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 200.0%		
	Oxygen partial pressure input: 0.0 to		
d: F3 		erence Value	
5 <i>31 F</i>	<i>⊏ ਟੀ¦ F</i> ∶ Medium Value		
	<i>らぱ F</i> : Reference Value		
dFo3		concentration input: 0.01 mg/L	
<i>00 </i>		er temperature input: 1.0°C % saturation input: 0.1%	
		gen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.0		1
	Water temperature input: 0.0 to 10.0°C		
	DO % saturation input: 0.0 to 40.0%		
	Oxygen partial pressure input: 0.0 to	30.0 kPa	
dFU3	EVT3 OFF side (*3) DO	concentration input: 0.01 mg/L	
00 I		er temperature input: 1.0°C	
		% saturation input: 0.1%	
		gen partial pressure input: 0.1 kPa	-
	DO concentration input: 0.00 to 4.0 Water temperature input: 0.0 to 10.0		
	DO % saturation input: 0.0 to 40.0		
	Oxygen partial pressure input: 0.0 to		

(*1) If (No action), $\mathcal{F} \subset \mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEG} (Cleansing output) is selected in [EVT3 type], this setting item and all subsequent items will not be available.

(*2) Not available if daH'_{L} (DO concentration input High/Low limits independent action), faH'_{L} (Water temperature input High/Low limits independent action), $d'_{L}H'_{L}$ (DO % saturation input High/Low limits independent action) or $\bar{a}PH'_{L}$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT3 type].

Character	Setting Item, Setting Range	Factory Default	Data
on[]	EVT3 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF3	EVT3 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon3	Output ON Time when EVT3	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ls	
00F3	Output OFF Time when EVT3	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_LB	EVT3 High/Low limits	DO concentration input: 0.00 mg/L	
000	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00		
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
E_H3	EVT3 High/Low limits	DO concentration input: 0.00 mg/L	
liano	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00	to 20.00 mg/L	
	Water temperature input: 0.0 to		
		200.0%	
	Oxygen partial pressure input: (
ЕНЧЭ	EVT3 hysteresis	DO concentration input: 0.01 mg/L	
00 I		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
	DO construction innut - 0.01	Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0% Oxygen partial pressure input: 0.1 to 15.0 kPa		
		$\nabla T = 0$ (Water temperature in	

EVT4 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
EFFY	EVT4 type	No action	
	: No action		
	da_H : DO concentration input high	limit action	
	dローム : DO concentration input low limit action ぶにった : Water temperature input high limit action ぶにった : Water temperature input low limit action		
	ゴロード : DO % saturation input high		
	ゴローム : DO % saturation input low I		
	⁻ ⁻ ⁻ ⁻ ⁻ ⁻ ⁻ ⁻ ⁻		
	$\vec{\omega}\vec{r}\vec{r}$: Oxygen partial pressure inp	-	
	「こころ」 Consor cap replacement tin		
	Sensor cap replacement in SELF : Self-check output		
	= L E L : Cleansing output		
	コローン Cleansing output コローム: DO concentration input Hig	h/l ow limits independent action	
	F る H L : Water temperature input Hig		
	$d' \neg H'_{L}$: DO % saturation input High		
	<i>GPHL</i> : Oxygen partial pressure input high	•	
	action		
584		concentration input: 0.00 mg/L	
000		er temperature input: 0.0°C	
		% saturation input: 0.0%	
		gen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 20.		
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 200.		
di F4	Oxygen partial pressure input: 0.0 to		
o, rh Hdi F		erence Value	-
	<i>⊏ d¦ F</i> : Medium Value		
-117 - 1-1	Sector Sector	concentration inputs 0.04 mm "	
dFo4 [00		concentration input: 0.01 mg/L er temperature input: 1.0°C	
		% saturation input: 0.1%	
		gen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00 mg/L		
	Water temperature input: 0.0 to 10.0°C		
	DO % saturation input: 0.0 to 40.0%		
	Oxygen partial pressure input: 0.0 to		
dFU4		concentration input: 0.01 mg/L	
<i>□00 I</i>		er temperature input: 1.0°C	
		% saturation input: 0.1% gen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.0		
	Water temperature input: 0.0 to 10.0		
	DO % saturation input: 0.0 to 40.0		
	Oxygen partial pressure input: 0.0 to		

(*1) If (No action), $\mathcal{F} \subset \mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEG} (Cleansing output) is selected in [EVT4 type], this setting item and all subsequent items will not be available.

(*2) Not available if daH'_{L} (DO concentration input High/Low limits independent action), faH'_{L} (Water temperature input High/Low limits independent action), $d'_{L}H'_{L}$ (DO % saturation input High/Low limits independent action) or $\bar{a}PH'_{L}$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT4 type].

Character	Setting Item, Setting Range	Factory Default	Data
onf4	EVT4 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
0FF4	EVT4 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	st	
oon4	Output ON Time when EVT4	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
00F4	Output OFF Time when EVT4	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_LY	EVT4 High/Low limits	DO concentration input: 0.00 mg/L	
000	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.001		
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
Е_НЧ	EVT4 High/Low limits	DO concentration input: 0.00 mg/L	
<u> </u>	independent upper side value	Water temperature input: 0.0°C	
	independent upper side value	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 t	to 20.00 mg/L	
	Water temperature input: 0.0 to		
		200.0%	
	Oxygen partial pressure input: 0		
ЕНУЧ	EVT4 hysteresis	DO concentration input: 0.01 mg/L	
000 I		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0% Oxygen partial pressure input: 0.1 to 15.0 kPa		
		onendent action)	

EVT5 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
EFFS	EVT5 type	No action	
[-]-]-]-]	ELET : No action		
	daH : DO concentration input high limit action		
	ゴローム : DO concentration input low limit action ゴニゴー : Water temperature input high limit action		
	$\vec{\omega} \vec{r} \vec{n} \vec{L}$: Water temperature input	-	
	ゴロンH : DO % saturation input high		
	コロート : DO % saturation input lov		
	^{エロート} : Oxygen partial pressure i		
	Gアーム: Oxygen partial pressure i		
	$\Gamma \subseteq \overline{PP}$: Sensor cap replacement	limer	
	5ELF : Self-check output		
	ことEG : Cleansing output	lieb/Levy limite independent estien	
	daHL : DO concentration input ⊢	High/Low limits independent action	
	ゴードー · Water temperature input		
	<i>GPHL</i> : Oxygen partial pressure	o	
	action	nput high/Low innits independent	
585		O concentration input: 0.00 mg/L	
aoo		ater temperature input: 0.0°C	
		D % saturation input: 0.0%	
		kygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 2		
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 20		
	Oxygen partial pressure input: 0.0		
di FS	, , , , , , , , , , , , , , , , , , ,	eference Value	-
5 <i>61 F</i>	E = E = E : Medium Value		
	<i>hdl F</i> : Reference Value		
dFo5		O concentration input: 0.01 mg/L	
<u> </u>		ater temperature input: 1.0°C D % saturation input: 0.1%	
		xygen partial pressure input: 0.1 kPa	
		1.00 mg/L	
	Water temperature input: 0.0 to 10		
	DO % saturation input: 0.0 to 40	0.0%	
	Oxygen partial pressure input: 0.0		
dFUS	(-)	O concentration input: 0.01 mg/L	
00 I		ater temperature input: 1.0°C	
		O % saturation input: 0.1% xygen partial pressure input: 0.1 kPa	
		k.00 mg/L	
	Water temperature input: 0.0 to 10	•	
	DO % saturation input: 0.0 to 40		
	Oxygen partial pressure input: 0.0		

(*1) If (No action), $\mathcal{F} \subset \mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEG} (Cleansing output) is selected in [EVT5 type], this setting item and all subsequent items will not be available.

(*2) Not available if daH'_{L} (DO concentration input High/Low limits independent action), faH'_{L} (Water temperature input High/Low limits independent action), $d'_{L}H'_{L}$ (DO % saturation input High/Low limits independent action) or $\bar{a}PH'_{L}$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT5 type].

Character	Setting Item, Setting Range	Factory Default	Data
onfS	EVT5 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFFS	EVT5 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oonS	Output ON Time when EVT5	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
00F5	Output OFF Time when EVT5	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_15	EVT5 High/Low limits	DO concentration input: 0.00 mg/L	
000	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00		
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
E_H5	EVT5 High/Low limits	DO concentration input: 0.00 mg/L	
	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00	to 20.00 mg/L	
	Water temperature input: 0.0 to		
		200.0%	
	Oxygen partial pressure input: (
EHYS	EVT5 hysteresis	DO concentration input: 0.01 mg/L	
00 I		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0% Oxygen partial pressure input: 0.1 to 15.0 kPa		
		onendent action)	

EVT6 Action Group

Character	Setting Item, Setting Range	Factory Default	Data
EFFB	EVT6 type	No action	
	IIII : No action		
	da_H : DO concentration input high limit action		
	d = -L : DO concentration input low I		
	<i>「「「「」」</i> : Water temperature input high		
	$\vec{\mu} \vec{l} \vec{n} \vec{L}$: Water temperature input low		
	ゴロード : DO % saturation input high I		
	ゴローム : DO % saturation input low lin		
	$\vec{\omega}\vec{P}\vec{-H}$: Oxygen partial pressure input		
	$\vec{\omega}\vec{r}$: Oxygen partial pressure input	-	
	$\Gamma \subseteq \exists P$: Sensor cap replacement tim		
	Sensor cap replacement unit		
	= LEL : Cleansing output		
	ビビロ: Cleansing output ゴロイム: DO concentration input High	// ow limits independent action	
	$\Gamma \overline{\beta} H L$: Water temperature input High		
	$\exists FHL$: DO % saturation input High/Low limits independent action $\exists FHL$: Oxygen partial pressure input High/Low limits independent		
	action		
586 ·	EVT6 value (*1) DO c	oncentration input: 0.00 mg/L	
000		r temperature input: 0.0°C	
		saturation input: 0.0%	
		en partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to 20.00 mg/L		
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 200.0%		
di F6	Oxygen partial pressure input: 0.0 to		
aira Sdif		rence Value	-
יוסר	<i>E dl F</i> : Medium Value		
	<i>トd: F</i> : Reference Value		
dFa6 ⊡00 I		oncentration input: 0.01 mg/L r temperature input: 1.0°C	
		saturation input: 0.1%	
		en partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00 mg/L		
	Water temperature input: 0.0 to 10.0°C		
	DO % saturation input: 0.0 to 40.0		
	Oxygen partial pressure input: 0.0 to		
dFUS		oncentration input: 0.01 mg/L	
00 I		r temperature input: 1.0°C 6 saturation input: 0.1%	
		en partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to 4.00		1
	Water temperature input: 0.0 to 10.0°		
	DO % saturation input: 0.0 to 40.0		
	Oxygen partial pressure input: 0.0 to 3	30.0 kPa	

(*1) If (No action), $\mathcal{F} \subset \mathcal{BP}$ (Sensor cap replacement timer), $\neg \mathcal{ELF}$ (Self-check output) or \mathcal{LEG} (Cleansing output) is selected in [EVT6 type], this setting item and all subsequent items will not be available.

(*2) Not available if daH'_{L} (DO concentration input High/Low limits independent action), faH'_{L} (Water temperature input High/Low limits independent action), $d'_{L}H'_{L}$ (DO % saturation input High/Low limits independent action) or $\bar{a}PH'_{L}$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT6 type].

Character	Setting Item, Setting Range	Factory Default	Data
onf 6	EVT6 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF 5	EVT6 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon5	Output ON Time when EVT6	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
00F6	Output OFF Time when EVT6	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_16	EVT6 High/Low limits	DO concentration input: 0.00 mg/L	
000	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00		
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
E_H6	EVT6 High/Low limits	DO concentration input: 0.00 mg/L	
1 200	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to	200.0%	
	Oxygen partial pressure input: (
ЕНЧБ	EVT6 hysteresis	DO concentration input: 0.01 mg/L	
<u> </u>		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
	DO concentration input: 0.01	Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: 0.1 to 15.0 kPa		
(*) IS 2 - 41 (D)			

Communication Group

Character	Setting Item, Setting Range	Factory Default	Data
cกี่ 44	Communication protocol	Shinko protocol	
noñL	הםה'ב : Shinko protocol		
	ಗೊಡೆ∺: MODBUS ASCII mode		
	nadr : MODBUS RTU mode		
cīno	Instrument number	0	
	0 to 95		
c.54P	Communication speed	9600 bps	
<u> </u>	<i>⊟∃E</i> : 9600 bps		
	<i>∐ /∃≓</i> : 19200 bps		
	[] <i>∃B닉</i> : 38400 bps		
c AFI	Data bit/Parity	7 bits/Even	
768~	ອີກອກ:8 bits/No parity		
	הםה: 7 bits/No parity		
	8E B ⊓ : 8 bits/Even		
	フE 台っ: 7 bits/Even		
	<i>ಔದದದ</i> ∶8 bits/Odd		
	ೌಧದದ : 7 bits/Odd		
<u>ะก่า/</u>	Stop bit	1 bit	
[]]] /	i i bit		
	\vec{z} : 2 bits		

Cleansing Group

Character	Setting Item, Setting Range	Factory Default	Data
ella	Cleansing time	30 seconds	
30	Setting range: 10 to 120 seconds		
cLcY	Cleansing inactive interval	OFF (None)	
of F	$\Box FF$ (None), 10 to 240 minutes		
ell F	Standby after Cleansing	0 seconds	
	Setting range: 0 to 60 seconds		

Basic Function Group

Character	Setting Item, Setting Range	Factory Default	Data			
Lock	Set value lock	Unlock				
	Unlock): All set values can be cha	anged.				
	とっこ / (Lock 1): None of the set values c	an be changed.				
	と <i>ゅこ</i> ご (Lock 2): Only EVT1 to EVT6 valu	es can be changed.				
	$L \Box c \exists$ (Lock 3): All set values can be ten	nporarily changed. However,				
	they revert to their previo	ous value after the power is				
	turned off because they	are not saved in the				
	non-volatile IC memory.					
LI 66	Auto-light function	Disabled				
	-i-i-: Disabled					
	<i>出与E</i> □:Enabled					
FI AE	Indication time	00.00 (Remains lit)				
0000	Setting range:					
	00.00 (Remains lit)					
	00.01 to 60.00 (Minutes.Seconds)					

Character	Setting Item, Setting Range	Factory Default	Data
I Err	EVT output when input errors occur	Disabled	
oFF	an : Enabled		
	□FF□ : Disabled		
58 /	EVT1 value	365 days	
<u>365</u>	Setting range: 0 to 1095 days		
onf I	EVT1 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
off (EVT1 OFF delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
4 <i>82</i> 0	EVT2 value	365 days	
385	Setting range: 0 to 1095 days		
on[2	EVT2 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF2	EVT2 OFF delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
58 <i>3</i> 0	EVT3 value (*)	365 days	
<i>3</i> 65	Setting range: 0 to 1095 days		
on[]	EVT3 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF3	EVT3 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
5 <i>84</i>	EVT4 value (*)	365 days	
365	Setting range: 0 to 1095 days		
onf4	EVT4 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
оЕГЧ	EVT4 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
58S	EVT5 value (*)	365 days	
365	Setting range: 0 to 1095 days		
on/S	EVT5 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
oFFS	EVT5 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
58 <u>6</u>	EVT6 value (*)	365 days	
365	Setting range: 0 to 1095 days		
onf 6	EVT6 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
oF/6	EVT6 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
rEſā	Sensor cap replacement timer	365 days	
365	remainder		
	Setting range: 0 to 1095 days		

(*) Available only when EVT output (EVT option) is ordered.

Self-Check Group

Character		Mode
All lit	LED all lit mode	
Individually lit	LED individual lit mode	
1255 - C	Key input mode	
nonE	Temperature Display	Key Input
	nonE	When no key is pressed
	UP	When the 🛆 key is pressed
	doūn	When the 🖂 key is pressed
	db	When 2 or more keys are pressed simultaneously
oU/	Output mode	
oFF	Temperature Display	Output
		All EVT outputs: OFF, Transmission output 1 and 2: 4 mA DC
	E86 I	EVT1 output ON
	E862	EVT2 output ON
	E8F3	EVT3 output ON
	E864	EVT4 output ON
	<i>E8</i> /5	EVT5 output ON
	E865	EVT6 output ON
	l l	Transmission output 1: 20 mA DC
	Frad	Transmission output 2: 20 mA DC
do	Input mode	
Measured	DO Display	Temperature Display
value	do	DO concentration measured value
	<u>arap</u>	Water temperature measured value
	dohl	DO % saturation measured value
	jprs ncRP	Oxygen partial pressure measured value

Data Clear Group

Character	Setting Item, Setting Range	Factory Default	Data
-L-L	Data clear selection	Calibration value	
c 81.	<i>⊏ ⊟L</i> ∷ Calibration value		
	らとて : Set value		
cLr[]	Data clear Stop/Perform	Data clear Stop	
no[]]]	Data clear Stop		
	$\exists \mathcal{E} = \square$: Data clear Perform		

Error Codes

The following error codes are indicated on the Temperature Display.

Error Code	Description	Occurrence
ErrO	Non-volatile IC memory error	Constantly
Err I	DO Sensor communication errors have occurred, or DO Sensor is	When
	not connected.	measuring
	After a command is sent to the DO Sensor, if there is no response	and calibrating
	for 500 ms, the command will be sent again.	
	If no response occurs 4 times consecutively, this error code will be	
	displayed.	
	If communication status returns to normal, the unit will automatically	
	return to normal status.	
	When this error code is displayed, the previous measured value is	
	retained.	
Errd	DO Sensor cap is not attached, or it is incorrectly attached.	
Errð	Calibration error (when input errors have occurred, or when calibra-	When
	tion cannot be performed 30 minutes after starting calibration)	calibrating
Erry	DO Sensor internal memory deletion.	When
	Displayed when Quality ID3 is received from the DO Sensor.	measuring
		and calibrating

14. Key Operation Flowchart

POWER ON



Display Mode or Cleansing Output Mode (*1) Meas value (*2) DO Oncentration / Leavable (*2) DO % Saturation / Leavable (*2) Do yeen Partial Pressure / Leavable (*3) Temp. Display Mode Image: Display Mode Image: Display				<u> </u>		··-··		
$\begin{array}{c c c c c c c c c c c c c c c c c c c $								
Mass value (1) Temp. Display Mode Mass value (1) Temp. Display Mode Mass value (1) Temp. Display Mode $\Box + \Box = 1$ $\Box + \Box = 1$ $\Box = 1$								
$ \begin{array}{c} \hline P & P & P & P \\ \hline P $. ,		•					
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Meas.value (*3)	Temp. Display Mode	Meas.value (*3)	Temp. Display Mode		Meas.value (*3)	Temp. Display Mode	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $								
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $				•				
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			Meas.value (*2)	DO Concentration	RESET	Meas.value (*4)	1-point calibration	RESET
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $				1-point Calib, Mode				
Measurate (*2) DO Concentration The strate (*2) The strate (*2) $\square Z^{2-1}$ Concentration The strate (*2) The strate (*2) $\square Z^{2-1}$ (P43) The strate (*4) Concentration Option $\square Z^{2-1}$ Concentration Option The strate (*4) Concentration Option The strate (*4) $\square Z^{2-1}$ Concentration Option The strate (*4) Concentration Option The strate (*4) $\square Z^{2-1}$ Concentration Option The strate (*4) Concentration Option The strate (*4) $\square Z^{2-1}$ Concentration Option The strate (*2) Forced Cleansing Automatically proceeds after cleansing action. $\square Z^{2-1}$ Transmission output The strate (*3) The strate (*4) The strate (*4) $\square Z^{2-1}$ Transmission output The strate (*2) The strate (*2) The strate (*4) $\square Z^{2-1}$ Transmission output The strate (*2) The strate (*2) The strate (*2) $\square Z^{2-1}$ Transmission output The strate (*2) The strate (*2) The strate (*2) $\square Z^{2-1}$ Transmission output The strate (*2) The strate strate (*2) The strate strate (*2) <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>(10070 bataratori banbi)</td> <td></td>							(10070 bataratori banbi)	
$\begin{array}{c c c c c c c c c c c c c c c c c c c $			Maga volue (*2)		SET	Maga value (*4)	1 st point calibration (*E)	
$ \begin{array}{c} \hline \hline$					- Keselj			
$ \begin{array}{c} & & & & & & & & & & & & & & & & & & &$								
$ \begin{array}{c} \hline \hline$				(P.43)				
$ \begin{array}{c} \hline c \ R di \\ \hline c \ R di \\ \hline c \ Desired value} \hline calibration Mode \\ \hline calibrat \\ \hline calibrat \\ \hline calibration Mode \\ \hline calibratio$								RESET
$ \begin{array}{c} \hline c. Desired value \ \hline$							(0-point calibration)	
$ \begin{array}{c} \hline c. Desired value \ \hline$				↓ <u></u>				
$ \begin{array}{c} \hline C. Desired value \ Calibration Mode \ \hline C. desired value \ Calibration Mode \ \hline C. desired value \ Calibration Mode \ \hline C. desired value \ \hline C. de$			cRdF	Concentration Option	RESET	Meas.value (*4)	Concentration Option	RESET
$ \begin{array}{c} \hline \bigcirc & (P.45) \\ \hline \bigcirc & (P.45) \\ \hline \bigcirc & (P.45) \\ \hline \hline \bigcirc & (P.45) \\ \hline \hline \bigcirc & (P.45) \\ \hline \hline \bigcirc & (P.54) \\ \hline \hline & (P.52) \\ \hline \hline \hline \hline & (P.5) \\ \hline \hline \hline \hline \hline & (P.5) \\ \hline $			C.Desired value					
$ \begin{array}{c} \hline \hline$						1		I
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			<u>aoo</u>					
		L		(P.24)		. – .	(P.25)	1

About Setting Item

dFcfSignal output_____5response time (P.23)

• Upper left: DO Display: Indicates the setting item characters. • Lower left: Temperature Display: Indicates the factory default. • Right side: Indicates the setting item and reference page.

EBT3 EVT3 Action Group

Setting item in shaded section will be displayed only when the corresponding option is ordered.

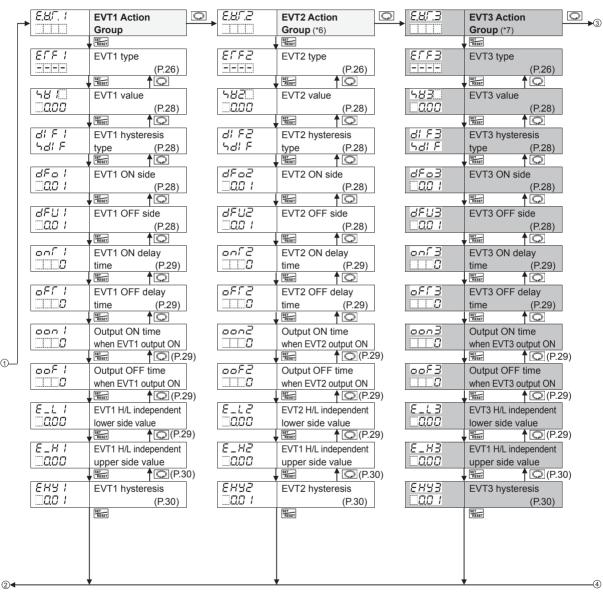
(*1) In Cleansing Output Mode, the measured value (DO concentration, DO % saturation, Oxygen partial pressure, temperature) is held during cleansing action (using 'Cleansing time' and 'Standby after cleansing').

(*2) Indicates the measured value of DO concentration, DO % saturation or Oxygen partial pressure.

(*3) Indicates temperature measured value. (*4) During calibration, DO concentration measured value flashes.

(*5) If errors occur during 1st-point calibration (100% saturation calibration) in 2-point Calibration Mode, the unit will revert to the Display Mode or Cleansing Output Mode by pressing the 💭 or 🔚 key.

Abbreviation: H/L: High/Low limits



Key Operation

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- 🖾, 🔘, 🔚 Press the 🛆, 🔘 or 🔚 key. The unit will proceed to the next setting item, illustrated by an arrow.
- 🖂 + 🖸 (3 sec): Press and hold the 🖂 and 🖸 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- 🚟 (3 sec), 🖸 (3 sec): Press the 🚟 or 🖸 key for 3 seconds. The unit will proceed to the next setting item, illustrated by an arrow.
- 🖂 + 🚟 (3 sec): Press and hold the 🖾 and 🚟 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- 🗁 + 🖼 (3 sec): Press and hold the 🖂 and 🚟 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- To set each item, use the \bigtriangleup or \bigtriangledown key, and register the set value with the \blacksquare key.
- If the 🖸 key is pressed for 3 seconds at any setting item, the unit will revert to Display Mode or Cleansing Output Mode.
- (*6) Action, indication condition and setting range of the EVT2 Action Group are the same EVT1 Action Group.
- Substitute EVT1 character (¹) with EVT2 character (²). Refer to EVT1 Action Group (pp. 26 to 30). (*7) Action, indication condition and setting range of the EVT3 Action Group are the same EVT1 Action Group.
- Substitute EVT1 character ($\frac{1}{2}$) with EVT3 character ($\frac{3}{2}$). Refer to EVT1 Action Group (pp. 26 to 30).

F	1
Abbreviation: H/L: High/Low limits	į
L	

ⓐ→ <u>E.H. H</u> EVT4 Action	E.8.7.5	EVT5 Action	E.8.F.8	EVT6 Action
Group (*8)		Group (*9)		Group (*10)
SET RESET		SET Reset		SET RESET
EFFY EVT4 type	EFFS	EVT5 type	EF F 6	EVT6 type
(P.26)		(P.26)		(P.26)
				▼ RESET ↑ CO
584 EVT4 value	585	EVT5 value	585	EVT6 value
(P.28)	000	(P.28)	0.00	(P.28)
				RESET C
di FH EVT4 hysteresis	di FS	EVT5 hysteresis	81 F 5	EVT6 hysteresis
	5 <i>61 F</i>	type (P.28)	Sdi F	type (P.28)
dF⊇Y EVT4 ON side	dFaS		dFo6	
	000	EVT5 ON side	0001	EVT6 ON side
		(P.28)		(P.28)
עדניין ערדע OFF side	arus	EVT5 OFF side	dFU5	EVT6 OFF side
		(P.28)		(P.28)
			(
ローディ EVT4 ON delay	on[5	EVT5 ON delay	onf 6	EVT6 ON delay
time (P.29)		time (P.29)		time (P.29)
oFデイ EVT4 OFF delay	oFFS	EVT5 OFF delay	oFFS	EVT6 OFF delay
time (P.29)		time (P.29)	0	time (P.29)
QDDY Output ON time	oonS	Output ON time	oonS	Output ON time
when EVT4 output ON	<i>0</i>	when EVT5 output ON		when EVT6 output ON
↓ ^{BET} ↑ 💭 (P.29)		▼ ^{BET} RESET ↑ (P.29)		▼ RESET ↑ (P.29)
Output OFF time	0085	Output OFF time	00F6	Output OFF time
when EVT4 output ON		when EVT5 output ON		when EVT6 output ON
■ ■ ■ ■ ■ ■ ■ ■ ■ ■		▼ SET (P.29)		▶ ^{SET} ↑ (P.29)
ELH EVT4 H/L independent	ELLS	EVT5 H/L independent	8_18	EVT6 H/L independent
LOO lower side value	000	lower side value	0.00	lower side value
	E 115	↓ SET ↑ (P.29)	<i>E</i> 11 <i>E</i>	▼ FEFE (P.29)
EVT4 H/L independent	E_HS	EVT5 H/L independent	E_H5	EVT6 H/L independent
upper side value ↓ ₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩	000	upper side value	000	upper side value
	EINE		EH46	
The second se	EHYS 00 I	EVT5 hysteresis		EVT6 hysteresis
(P.30)		(P.30)		(P.30)
		RESET		[RESET]
		↓ ↓		
		Ŧ		6

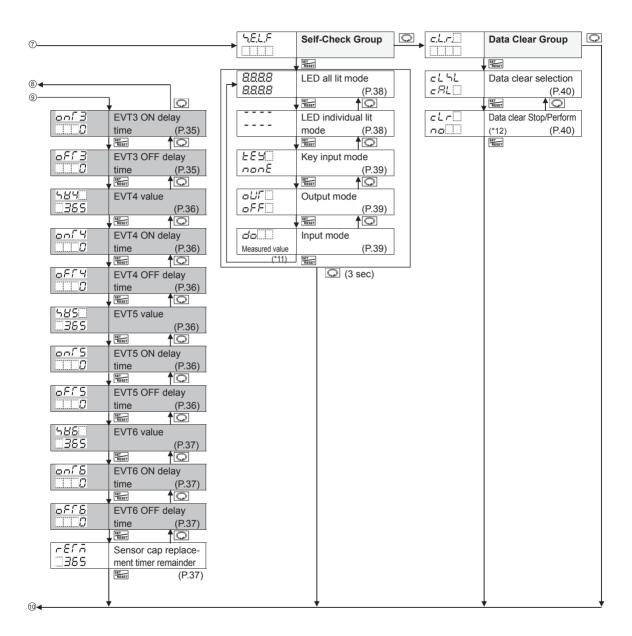
(*8) Action, indication condition and setting range of the EVT4 Action Group are the same EVT1 Action Group.

Substitute EVT1 character (¹) with EVT4 character (⁴). Refer to EVT1 Action Group (pp. 26 to 30). (*9) Action, indication condition and setting range of the EVT5 Action Group are the same EVT1 Action Group.

(a) Action, indication condution and setting range of the EVTS Action Group Group (pp. 26 to 30). Substitute EVT1 character (1) with EVT5 character (5). Refer to EVT1 Action Group (pp. 26 to 30).

(*10) Action, indication condition and setting range of the EVT6 Action Group are the same EVT1 Action Group. Substitute EVT1 character (*1*) with EVT6 character (*5*). Refer to EVT1 Action Group (pp. 26 to 30).

_	caññ	Communication	0 . c.l.E.G	Cleansing	🔘 , al Er	Basic Function	
⑤→		Group		Group		Group	▶7
		RESET	·	RESET		SET RESET	
	<i>ธก</i> ัรย	Communication	cLĨĂ	Cleansing time	Loct	Set value lock	
	noñL	protocol (P.32)	<i>30</i>	(P.33)		(P.34)	
			<u> </u>		J <u>L</u>		
	cñno	Instrument number	clcy	Cleansing inactive	LI 67	Auto-light function	
		(P.32)	oFF 🗌	interval (P.33)	[- - - -]	(P.34)	
				RESET C		ESET C	
	eñ5P	Communication	ELI F	Standby after	FI AE	Indication time	
	- 98	speed (P.32)		cleansing (P.33)	0000	(P.34)	
			_	RESET			
	c 7.87	Data bit/Parity			1 Err	EVT output when input	
	788n	(P.32)			oFF[]	errors occur (P.34)	
		RESET O	-				
	<u>ะกั</u> ร์ไ	Stop bit			58 /C	EVT1 value	
		(P.32)			<i>⊡3</i> 65	(P.34)	
		RESET				RESET	,
					on[EVT1 ON delay	
						time (P.35)	
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					oFf 1	EVT1 OFF delay	
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					<i>582</i> 385	EVT2 value	
						(P.35)	
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					·	time (P.35)	
					oF[2	EVT2 OFF delay	1 I
						time (P.35)	
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					58 <u>3</u>	EVT3 value	1
					365	(P.35)	
						SET A	
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0.							9



(*11) Indicates DO concentration measured value.

(*12) Depending on the selection in [Data clear Stop/Perform], the unit operates as follows.

If 'Data clear Stop' is selected, data will not be cleared. The unit will revert to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode).

If 'Data clear Perform' is selected, data will be cleared. The unit will revert to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode). (While data is being cleared, all indications are momentarily unlit.)

15. Maintenance

15.1 Maintenance

- Please perform the following maintenance procedure every month.
- Clean the measurement section with tap water.
- · Check that the measurement section is not damaged or deteriorated.
- Check that DO Sensor cable is not damaged or deteriorated.
- · Check that installation devices are not corroded.

15.2 Periodic Inspection

- Please check the following items every 3 months.
- The DO meter (WIL-102-DO) is securely fixed in place.
- · Check that the DO meter (WIL-102-DO) is not damaged.
- Check that screws in the terminal block are not rusty.

15.3 Replacement of Consumables (Maintenance Parts)

Purchase new sensor cap (DOS-CP), and replace one (1) year after installation (Recommended).

15.4 Calibration

The DO meter (WIL-102-DO) is designed to be used for a long period of time, however, calibrate it at least once a year to maintain measurement reliability. See Section "8. Calibration" (p.41).

15.5 Long-Term Storage

- When the DO meter (WIL-102-DO) and DO Sensor are not used for a long period of time, store them as follows.
- Disconnect the power from the mains electricity.
- Pull the DO Sensor out of the water, and clean it.
- Store the DO meter (WIL-102-DO) and DO Sensor away from direct sunlight.

16. Reference Chart

Amount of saturated DO in water at each temperature (At an atmospheric pressure 1, Salinity concentration 0 PSU)

Temper- ature (°C)	Amount of saturated DO (mg/L)						
1	13.77	11	10.67	21	8.68	31	7.42
2	13.40	12	10.43	22	8.53	32	7.32
3	13.04	13	10.20	23	8.39	33	7.22
4	12.70	14	9.97	24	8.25	34	7.13
5	12.37	15	9.76	25	8.11	35	7.04
6	12.06	16	9.56	26	7.99	36	6.94
7	11.75	17	9.37	27	7.87	37	6.86
8	11.47	18	9.18	28	7.75	38	6.76
9	11.19	19	9.01	29	7.64	39	6.68
10	10.92	20	8.84	30	7.53	40	6.59

***** Inquiries *****

For any inquiries about this unit, please contact our agency or the vendor where you purchased the unit after checking the following.

[Example] • Model ------ WIL-102-DO • Serial number ----- No. 194F05000

In addition to the above, please let us know the details of the malfunction, or discrepancy, and the operating conditions.

SHINKO TECHNOS CO., LTD. OVERSEAS DIVISION

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